

# TLE8888-1QK

## Engine Machine System IC



### 1 Overview

**Quality Requirement Category: Automotive**



#### Features

- Voltage pre-regulator
- Integrated 5 V regulator
- 2 integrated 5 V trackers
- Standby regulator
- Separate internal supply
- Voltage monitoring
- High speed CAN interface with wake-up by bus
- LIN interface with high speed mode for K-Line operation
- Variable reluctance sensor interface
- Microsecond Channel interface (MSC) with low voltage differential signal (LVDS) inputs pads for low EME
- SPI and direct control inputs for high flexibility
- Main relay driver
- Ignition Key detection with key off delay output
- Wake-up input
- Engine off timer
- 4 low-side power stages especially to drive injectors ( $R_{on} = 550 \text{ m}\Omega$ ) with enable input
- 3 low-side power stages ( $R_{on} = 350 \text{ m}\Omega$ )
- 6 push pull stages for driving on-board MOSFET with drain feedback
- 7 low-side power stages especially to drive relays ( $R_{on} = 1.5 \Omega$ ), one with delayed switch off functionality
- 4 half bridge stages for high flexibility, one with delayed switch off functionality
- 4 push pull stages for driving on- and off- board IGBT with back supply suppression and high voltage capability
- Open-load, short-to-GND and short-to-BAT diagnostic
- Overtemperature and short-to-BAT protection
- Monitoring watchdog module
- AEC Qualified

## Overview

### Description

The TLE8888-1QK is a U-Chip suitable for automotive engine management systems. It contains the basic functionality to supply the microcontroller and the ECU, establish the communication on- and off- board and drive EMS typical actuators. Furthermore it controls the main relay driver.

Type	Package	Marking
TLE8888-1QK	LQFP-100	TLE8888-1QK
TLE8888QK	LQFP-100	TLE8888QK
TLE8888-2QK	LQFP-100	TLE8888-2QK

### Device Variants TLE8888QK and TLE8888-2QK

The device variants TLE8888QK and TLE8888-2QK differ from the main version TLE8888-1QK in the watchdog functionality.

The TLE8888QK has a fixed set of parameter for the watchdog (see datasheet addendum “TLE8888QK - Addendum”).

For the TLE8888-2QK the watchdog function is disabled (see datasheet addendum “TLE8888-2QK - Addendum”).

Only the main version TLE8888-1QK is described in this datasheet.

For order conditions please contact the nearest Infineon Technologies office.

### Abbreviations

Symbol	Explanation
MSC	Microsecond channel
SPI	Serial peripheral interface
LVDS	Low voltage differential signal
EME	Electromagnetic emission
EMI	Electromagnetic interference
LIN	Local interconnect network
HS CAN	High speed controller area network

## Table of Contents

<b>1</b>	<b>Overview</b> .....	<b>1</b>
<b>2</b>	<b>Block Diagram</b> .....	<b>6</b>
<b>3</b>	<b>Pin Configuration</b> .....	<b>7</b>
3.1	Pin Assignment .....	7
3.2	Pin Definitions and Functions .....	7
<b>4</b>	<b>General Product Characteristics</b> .....	<b>12</b>
<b>5</b>	<b>Operation Behavior</b> .....	<b>16</b>
5.1	Operation States .....	17
5.2	Reset and Operation Modes .....	21
5.3	Electrical Characteristics Operation Behavior .....	29
<b>6</b>	<b>Monitoring Watchdog Module (Signature Watchdog)</b> .....	<b>31</b>
6.1	Window Watchdog .....	33
6.2	Functional Watchdog .....	35
6.2.1	Question and Response Definition .....	37
6.3	Total Error Counter Module .....	38
6.4	Watchdog Reset Counter .....	39
6.5	Power-Down Counter .....	39
6.6	Secure Shut Off Timer .....	39
6.7	Operation State Definition and Reset Generation .....	40
6.8	Synchronisation of Window Watchdog Sequence and Heartbeat .....	42
6.9	Electrical Characteristics Monitoring Watchdog Module .....	44
<b>7</b>	<b>Wake-Up Detection and Main Relay Driver</b> .....	<b>45</b>
7.1	Wake-up Detection by Pin <i>KEY</i> and Key Off Delay .....	46
7.2	Wake-up Detection by Pin <i>WK</i> .....	47
7.3	Main Relay Driver .....	50
7.4	Engine Off Timer .....	51
7.5	Electrical Characteristics Key Detection, Wake-up Detection and Main Relay Driver .....	55
<b>8</b>	<b>Power Supply</b> .....	<b>58</b>
8.1	Pre-Regulator .....	58
8.2	5 V Main Supply .....	59
8.3	Sensor Supply .....	59
8.4	IO Supply .....	59
8.5	Standby Supply .....	59
8.6	Charge Pump .....	59
8.7	Voltage Monitoring .....	59
8.8	Electrical Characteristics Power Supply .....	60
<b>9</b>	<b>Power Stages</b> .....	<b>64</b>
9.1	Power Stage Control .....	65
9.2	Power Stages Enable .....	66
9.3	Power Stages Configuration .....	67
9.4	Special Function “Delayed Switch Off” for <i>OUT17</i> and <i>OUT21</i> .....	67
9.5	Electrical Characteristics Direct Drive Inputs .....	70
9.6	Low-Side Switches <i>OUT1</i> to <i>OUT7</i> and <i>OUT14</i> to <i>OUT20</i> .....	71

9.6.1	Protection of <i>OUT1</i> to <i>OUT7</i> and <i>OUT14</i> to <i>OUT20</i> .....	71
9.6.2	Diagnosis of <i>OUT1</i> to <i>OUT7</i> and <i>OUT14</i> to <i>OUT20</i> .....	71
9.6.3	Electrical Characteristics Low-Side Switches <i>OUT1</i> to <i>OUT7</i> and <i>OUT14</i> to <i>OUT20</i> .....	72
9.7	Half Bridges <i>OUT21</i> to <i>OUT24</i> .....	76
9.7.1	Protection of Half Bridges <i>OUT21</i> to <i>OUT24</i> .....	78
9.7.2	Diagnosis of Half Bridges <i>OUT21</i> to <i>OUT24</i> .....	78
9.7.3	Electrical Characteristics Half Bridges .....	81
9.8	Push Pull Stages <i>OUT8</i> to <i>OUT13</i> and <i>DFB8</i> to <i>DFB13</i> .....	84
9.8.1	Protection of <i>OUT8</i> to <i>OUT13</i> .....	84
9.8.2	Diagnosis of <i>OUT8</i> to <i>OUT13</i> .....	84
9.9	Electrical Characteristics Push Pull Stages <i>OUT8</i> to <i>OUT13</i> .....	85
9.10	Push Pull Stages <i>IGN1</i> to <i>IGN4</i> .....	86
9.10.1	Protection of <i>IGN1</i> to <i>IGN4</i> .....	86
9.10.2	Diagnosis of <i>IGN1</i> to <i>IGN4</i> .....	87
9.11	Electrical Characteristics Push Pull Stages <i>IGN1</i> to <i>IGN4</i> .....	88
<b>10</b>	<b>VR and Hall Sensor Interface .....</b>	<b>90</b>
10.1	Signal Detection .....	90
10.2	Detection Modes .....	92
10.3	Diagnosis for VR Sensor Signal Detection Modes .....	92
10.4	Electrical Characteristics VR Sensor Interface .....	97
<b>11</b>	<b>Local Interconnect Network (LIN) .....</b>	<b>99</b>
11.1	Operation Modes .....	100
11.2	Failure Modes in LIN/K-Line Operation .....	100
11.2.1	Performance in Non Operation Supply Voltage Range .....	100
11.2.2	Loss of Supply Voltage and GND Connection .....	100
11.2.3	Bus Wiring Short to Battery or GND .....	101
11.2.4	TX Time Out .....	101
11.2.5	Overtemperature Protection .....	101
11.3	Electrical Characteristics LIN .....	102
<b>12</b>	<b>High Speed Controller Area Network (CAN) Transceiver .....</b>	<b>105</b>
12.1	Functional Description .....	105
12.2	Operation Modes .....	105
12.2.1	Normal Operation Mode .....	106
12.2.2	Receive Only Mode .....	106
12.2.3	Power-Down Mode .....	106
12.2.4	Remote Wake-Up .....	106
12.3	Diagnostic Functions .....	108
12.3.1	CAN Bus Failure Detection .....	108
12.3.2	Local Failure Detection .....	108
12.4	Electrical Characteristics CAN Transceiver .....	109
<b>13</b>	<b>Microsecond Channel MSC .....</b>	<b>112</b>
13.1	Downstream Communication .....	112
13.1.1	Downstream Supervisory Functions .....	114
13.1.2	Command Frame .....	115
13.1.3	Data Frame .....	115
13.2	Upstream Communication .....	117

13.3	Timing Characteristics .....	120
13.4	Electrical Characteristics .....	120
<b>14</b>	<b>Register and Commands .....</b>	<b>124</b>
14.1	Register Table .....	128
14.1.1	Command Register .....	130
14.1.2	Diagnosis Register .....	144
14.1.3	Status Register .....	155
14.1.4	Configuration Register .....	162
14.1.5	Control Register .....	192
<b>15</b>	<b>SPI .....</b>	<b>197</b>
15.1	SPI Protocol .....	197
15.2	SPI Frame Definition .....	199
15.3	Electrical Characteristics SPI .....	200
<b>16</b>	<b>EMC Requirements .....</b>	<b>201</b>
16.1	ISO Pulse Tests .....	201
<b>17</b>	<b>Application Information .....</b>	<b>202</b>
17.1	Supply Systems .....	203
17.2	VR Sensor Interface .....	204
<b>18</b>	<b>Package Outlines .....</b>	<b>206</b>
<b>19</b>	<b>Revision History .....</b>	<b>207</b>

Block Diagram

2 Block Diagram

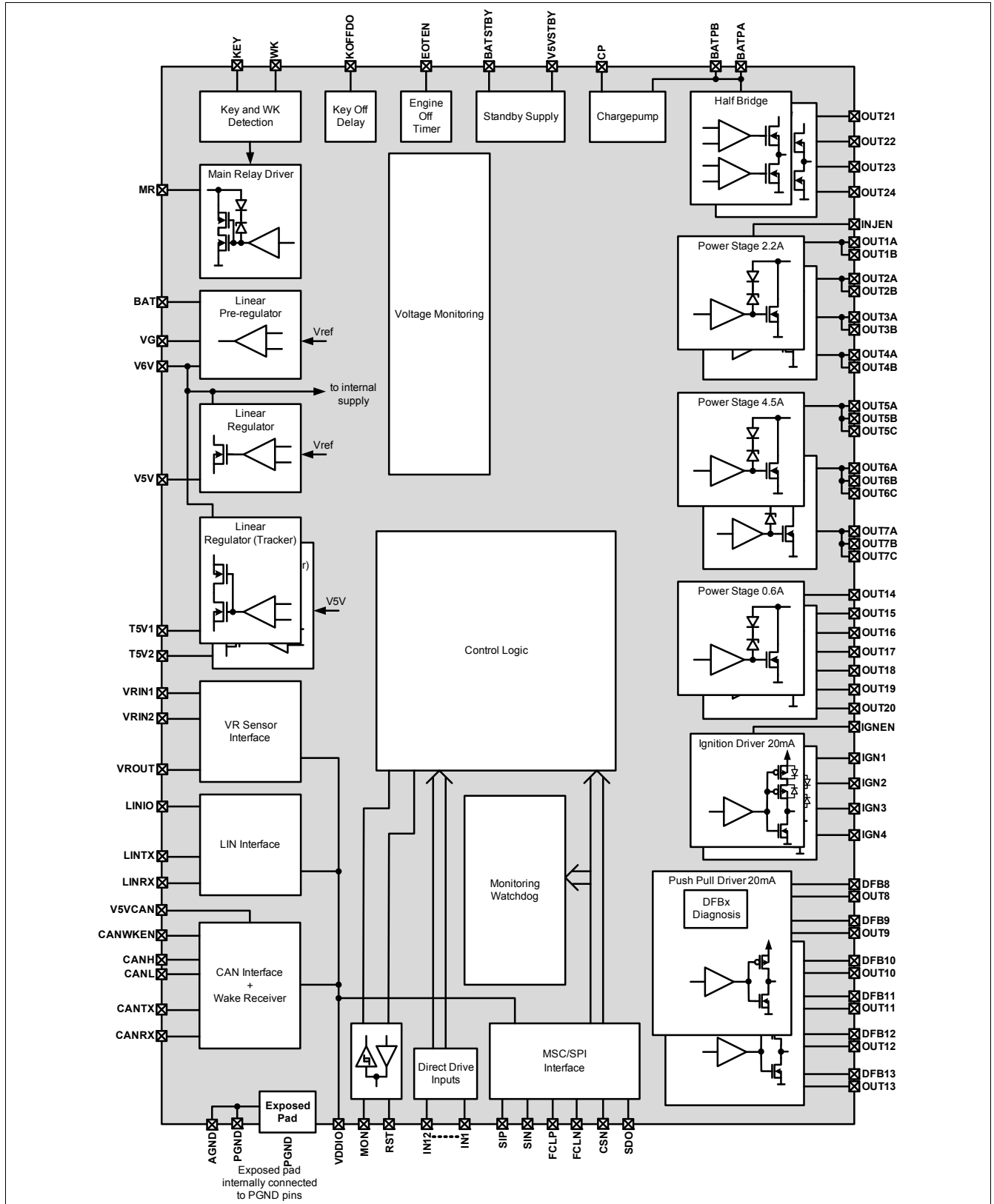


Figure 1 Block Diagram

Pin Configuration

### 3 Pin Configuration

#### 3.1 Pin Assignment

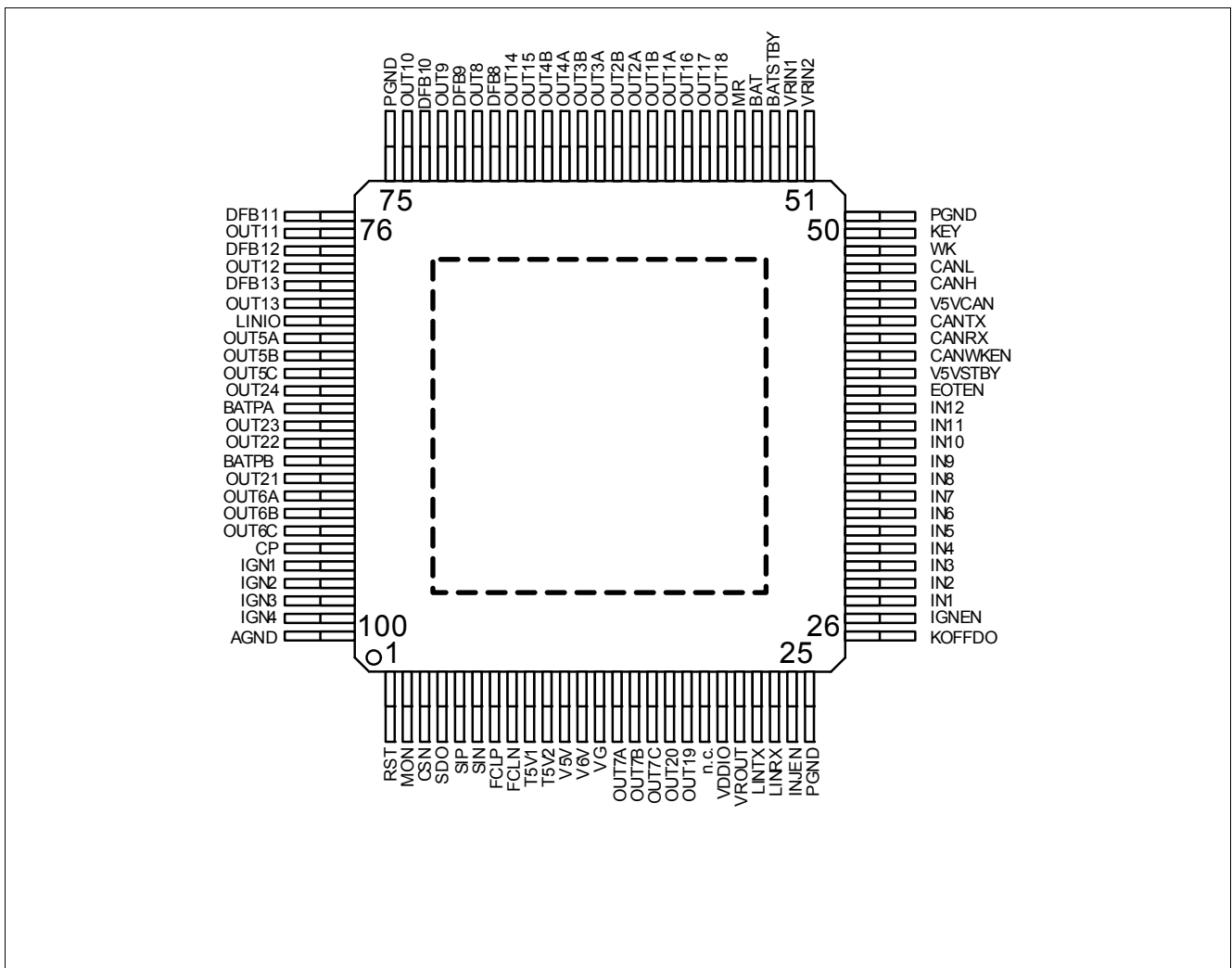


Figure 2 Pin Configuration

#### 3.2 Pin Definitions and Functions

Pin	Symbol	Function	Function
1	<i>RST</i>	IN/OUT	<b>Reset;</b> Bidirectional pin for reset functions
2	<i>MON</i>	IN/OUT	<b>Monitor;</b> Bidirectional pin for monitoring functions
3	<i>CSN</i>	IN	<b>MSC/SPI slave chip select;</b> Single ended chip select for MSC and SPI
4	<i>SDO</i>	OUT	<b>MSC/SPI serial data output;</b> Output for MSC and SPI
5	<i>SIP</i>	IN	<b>MSC/SPI Data input;</b> positive data input of LVDS in MSC mode or single ended data input in SPI mode

**Pin Configuration**

Pin	Symbol	Function	Function
6	<i>SIN</i>	IN	<b>MSC data input or select input;</b> negative data input of LVDS in MSC mode or select input for SPI mode
7	<i>FCLP</i>	IN	MSC/SPI Clock input; positive clock input of LVDS in MSC mode or single ended clock input in SPI mode
8	<i>FCLN</i>	IN	<b>Select input or MSC clock input;</b> negative clock input of LVDS in MSC mode or select input for single ended mode (SPI or MSC)
9	<i>T5V1</i>	OUT	<b>5 V tracker;</b> Supply voltage for off- board sensors
10	<i>T5V2</i>	OUT	<b>5 V tracker;</b> Supply voltage for off- board sensors
11	<i>V5V</i>	OUT	<b>5 V supply;</b> Supply voltage for main functions of the ECU
12	<i>V6V</i>	IN	<b>Source of external pre-regulator</b>
13	<i>VG</i>	OUT	<b>Gate of external pre-regulator</b>
14	<i>OUT7A</i>	OUT	<b>Low-side power stage;</b> Must be connected to <i>OUT7B</i> and <i>OUT7C</i> without any parasitic
15	<i>OUT7B</i>	OUT	<b>Low-side power stage;</b> Must be connected to <i>OUT7A</i> and <i>OUT7C</i> without any parasitic
16	<i>OUT7C</i>	OUT	<b>Low-side power stage;</b> Must be connected to <i>OUT7A</i> and <i>OUT7B</i> without any parasitic
17	<i>OUT20</i>	OUT	<b>Low-side small signal stage;</b>
18	<i>OUT19</i>	OUT	<b>Low-side small signal stage;</b>
19	n.c.		leave open or connect to GND
20	<i>VDDIO</i>	Supply	<b>Supply input for logic level inputs and outputs</b>
21	<i>VROUT</i>	OUT	<b>Output of variable reluctance sensor interface;</b> Digital output to microcontroller
22	<i>LINTX</i>	IN	<b>Transmit digital input for LIN interface;</b>
23	<i>LINRX</i>	OUT	<b>Receive digital output for LIN interface;</b>
24	<i>INJEN</i>	IN	<b>Injector enable input;</b>
25	<i>PGND</i>	GND	<b>Power ground;</b> internally connected to cooling tab
26	<i>KOFFDO</i>	OUT	<b>Key off delay output;</b>
27	<i>IGNEN</i>	IN	<b>Ignition enable input;</b>
28	<i>IN1</i>	IN	<b>Parallel input;</b> Input pin for direct control of power stage OUT1,
29	<i>IN2</i>	IN	<b>Parallel input;</b> Input pin for direct control of power stage OUT2
30	<i>IN3</i>	IN	<b>Parallel input;</b> Input pin for direct control of power stage OUT3
31	<i>IN4</i>	IN	<b>Parallel input;</b> Input pin for direct control of power stage OUT4
32	<i>IN5</i>	IN	<b>Parallel input;</b> Input pin for direct control of push pull state IGN1
33	<i>IN6</i>	IN	<b>Parallel input;</b> Input pin for direct control of push pull state IGN2
34	<i>IN7</i>	IN	<b>Parallel input;</b> Input pin for direct control of push pull state IGN3
35	<i>IN8</i>	IN	<b>Parallel input;</b> Input pin for direct control of push pull state IGN4
36	<i>IN9</i>	IN	<b>Parallel input;</b> Input pin for direct control of power stages, could be multiplexed to various stages



**Pin Configuration**

Pin	Symbol	Function	Function
37	<i>IN10</i>	IN	<b>Parallel input;</b> Input pin for direct control of power stages, could be multiplexed to various stages
38	<i>IN11</i>	IN	<b>Parallel input;</b> Input pin for direct control of power stages, could be multiplexed to various stages
39	<i>IN12</i>	IN	<b>Parallel input;</b> Input pin for direct control of power stages, could be multiplexed to various stages
40	<i>EOTEN</i>	IN	<b>Engine off timer enable input;</b>
41	<i>V5VSTBY</i>	OUT	<b>5 V standby supply;</b> Supply voltage in sleep mode
42	<i>CANWKEN</i>	IN	<b>Enable input for remote CAN wake-up;</b>
43	<i>CANRX</i>	OUT	<b>Receive digital output for CAN;</b>
44	<i>CANTX</i>	IN	<b>Transmit digital input for CAN;</b>
45	<i>V5VCAN</i>	Supply	<b>5 V supply input for CAN;</b>
46	<i>CANH</i>	IN/OUT	<b>CAN bus high;</b>
47	<i>CANL</i>	IN/OUT	<b>CAN bus low;</b>
48	<i>WK</i>	IN	<b>Wake-up input;</b> Input signal and supply for MR
49	<i>KEY</i>	IN	<b>Key input;</b> Input signal and supply for MR
50	<i>PGND</i>	GND	<b>Power ground;</b> internally connected to cooling tab
51	<i>VRIN2</i>	IN	<b>Differential input of variable reluctance sensor;</b> Analog input from sensor
52	<i>VRIN1</i>	IN	<b>Differential input of variable reluctance sensor;</b> Analog input from sensor
53	<i>BATSTBY</i>	Supply	<b>Battery input for standby supply;</b> Battery supply voltage standby supply regulator
54	<i>BAT</i>	Supply	<b>Battery;</b> Supply voltage for main functions of the device.
55	<i>MR</i>	OUT	<b>Low-side power stage for main relay;</b>
56	<i>OUT18</i>	OUT	<b>Low-side power stage;</b>
57	<i>OUT17</i>	OUT	<b>Low-side power stage;</b>
58	<i>OUT16</i>	OUT	<b>Low-side power stage;</b>
59	<i>OUT1A</i>	OUT	<b>Low-side power stage;</b> Must be connected to <i>OUT1B</i> without any parasitic
60	<i>OUT1B</i>	OUT	<b>Low-side power stage;</b> Must be connected to <i>OUT1A</i> without any parasitic
61	<i>OUT2A</i>	OUT	<b>Low-side power stage;</b> Must be connected to <i>OUT2B</i> without any parasitic
62	<i>OUT2B</i>	OUT	<b>Low-side power stage;</b> Must be connected to <i>OUT2A</i> without any parasitic
63	<i>OUT3A</i>	OUT	<b>Low-side power stage;</b> Must be connected to <i>OUT3B</i> without any parasitic
64	<i>OUT3B</i>	OUT	<b>Low-side power stage;</b> Must be connected to <i>OUT3A</i> without any parasitic

**Pin Configuration**

Pin	Symbol	Function	Function
65	<i>OUT4A</i>	OUT	<b>Low-side power stage;</b> Must be connected to <i>OUT4B</i> without any parasitic
66	<i>OUT4B</i>	OUT	<b>Low-side power stage;</b> Must be connected to <i>OUT4A</i> without any parasitic
67	<i>OUT15</i>	OUT	<b>Low-side power stage;</b>
68	<i>OUT14</i>	OUT	<b>Low-side power stage;</b>
69	<i>DFB8</i>	IN	<b>Drain Feedback;</b> Related to <i>OUT8</i>
70	<i>OUT8</i>	OUT	<b>Push pull stage;</b> To control on- board MOSFET
71	<i>DFB9</i>	IN	<b>Drain Feedback;</b> Related to <i>OUT9</i>
72	<i>OUT9</i>	OUT	<b>Push pull stage;</b> To control on- board MOSFET
73	<i>DFB10</i>	IN	<b>Drain Feedback;</b> Related to <i>OUT10</i>
74	<i>OUT10</i>	OUT	<b>Push pull stage;</b> To control on- board MOSFET
75	<i>PGND</i>	GND	<b>Power ground;</b> internally connected to cooling tab
76	<i>DFB11</i>	IN	<b>Drain Feedback;</b> Related to <i>OUT11</i>
77	<i>OUT11</i>	OUT	<b>Push pull stage;</b> To control on- board MOSFET
78	<i>DFB12</i>	IN	<b>Drain Feedback;</b> Related to <i>OUT12</i>
79	<i>OUT12</i>	OUT	<b>Push pull stage;</b> To control on- board MOSFET
80	<i>DFB13</i>	IN	<b>Drain Feedback;</b> Related to <i>OUT13</i>
81	<i>OUT13</i>	OUT	<b>Push pull stage;</b> To control on- board MOSFET
82	<i>LINIO</i>	IN/OUT	<b>BUS for LIN interface;</b>
83	<i>OUT5A</i>	OUT	<b>Low-side power stage;</b> Must be connected to <i>OUT5B</i> and <i>OUT5C</i> without any parasitic
84	<i>OUT5B</i>	OUT	<b>Low-side power stage;</b> Must be connected to <i>OUT5A</i> and <i>OUT5C</i> without any parasitic
85	<i>OUT5C</i>	OUT	<b>Low-side power stage;</b> Must be connected to <i>OUT5A</i> and <i>OUT5B</i> without any parasitic
86	<i>OUT24</i>	OUT	<b>Half bridge stage;</b>
87	<i>BATPA</i>	Supply	<b>Battery;</b> Supply voltage for half bridges and the charge pump; must be connected to <i>BATPB</i> without any parasitic
88	<i>OUT23</i>	OUT	<b>Half bridge stage;</b>
89	<i>OUT22</i>	OUT	<b>Half bridge stage;</b>
90	<i>BATPB</i>	Supply	<b>Battery;</b> Supply voltage for half bridges and the charge pump; must be connected to <i>BATPA</i> without any parasitic
91	<i>OUT21</i>	OUT	<b>Half bridge stage;</b>
92	<i>OUT6A</i>	OUT	<b>Low-side power stage;</b> Must be connected to <i>OUT6B</i> and <i>OUT6C</i> without any parasitic
93	<i>OUT6B</i>	OUT	<b>Low-side power stage;</b> Must be connected to <i>OUT6A</i> and <i>OUT6C</i> without any parasitic
94	<i>OUT6C</i>	OUT	<b>Low-side power stage;</b> Must be connected to <i>OUT6A</i> and <i>OUT6B</i> without any parasitic
95	<i>CP</i>	OUT	<b>Charge pump;</b> add external capacitance to stabilise charge pump voltage

**Pin Configuration**

<b>Pin</b>	<b>Symbol</b>	<b>Function</b>	<b>Function</b>
96	<i>IGN1</i>	OUT	<b>Push pull stage;</b> To control on- or off- board IGBT
97	<i>IGN2</i>	OUT	<b>Push pull stage;</b> To control on- or off- board IGBT
98	<i>IGN3</i>	OUT	<b>Push pull stage;</b> To control on- or off- board IGBT
99	<i>IGN4</i>	OUT	<b>Push pull stage;</b> To control on- or off- board IGBT
100	<i>AGND</i>	GND	<b>Signal ground;</b> internally connected to <i>PGND</i> and cooling tab
Cooling tab <sup>1)</sup>	<i>PGND</i>	GND	<b>Power ground;</b> internally connected PGND pins

1) Cooling tab is also called exposed pad

**General Product Characteristics**

**4 General Product Characteristics**

General definition:

$V_S$  is the short cut for all battery supplies of the TLE8888-1QK (*BAT*, *BATPA*, *BATPB*, *BATSTBY*) unless otherwise specified

*GND* is the short cut for all grounds of the TLE8888-1QK (*AGND*, *PGND*) unless otherwise specified.

**Table 1 Absolute Maximum Ratings<sup>1)</sup>**

$T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to *GND*, positive current flowing into pin, (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
<b>Voltages</b>							
BATPA, BATPB, OUT8...13, DFB8...13	$V_{\text{BATPA,MR}}$ $V_{\text{BATPB,MR}}$ $V_{\text{OUT8...13,MR}}$ $V_{\text{DFB8...13,MR}}$	-0.3	-	40	V	-	P_4.1
CP	$V_{\text{CP,MR}}$	-0.3	-	45	V	$-0.3\text{ V} < V_{\text{CP}} - V_{\text{BATPA}} < 5\text{ V}$	P_4.2
OUT1...7, OUT14...20	$V_{\text{OUT1...7,MR}}$ $V_{\text{OUT14...20,MR}}$	-0.3	-	50	V	OUTn is switched off, clamping is allowed according <a href="#">Chapter 9.6</a>	P_4.3
V6V	$V_{\text{V6V,MR}}$	-0.3	-	10	V	-	P_4.4
VG	$V_{\text{VG,MR}}$	-0.3	-	12	V	$V_{\text{VG}} - V_{\text{V6V}} < 5\text{ V}$	P_4.5
V5V, V5VSTBY, VDDIO, V5VCAN	$V_{\text{V5V,MR}}$ $V_{\text{V5VSTBY,MR}}$ $V_{\text{VDIO,MR}}$ $V_{\text{V5VCAN,MR}}$	-0.3	-	5.5	V	-	P_4.6
T5V1, T5V2, IGN1...4	$V_{\text{T5V1,MR}}$ $V_{\text{T5V2,MR}}$ $V_{\text{IGN1...4,MR}}$	-1	-	40	V	-	P_4.7
BAT, BATSTBY, KEY, WK, MR	$V_{\text{BAT,MR}}$ $V_{\text{KEY,MR}}$ $V_{\text{WK,MR}}$ $V_{\text{BATSTBY,MR}}$ $V_{\text{MR,MR}}$	-16	-	40	V	-	P_4.8

**General Product Characteristics**

**Table 1 Absolute Maximum Ratings<sup>1)</sup>** (cont'd)

$T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to GND, positive current flowing into pin, (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
IN1...12, SIP, SIN, FCLP, FCLN, CSN, LINTX, CANTX, IGNEN, INJEN, CANWKEN, EOTEN	$V_{IN1...12,MR}$ $V_{FCLP,MR}$ $V_{FCLN,MR}$ $V_{SIP,MR}$ $V_{SIN,MR}$ $V_{CSN,MR}$ $V_{LINTX,MR}$ $V_{CANTX,MR}$ $V_{IGNEN,MR}$ $V_{INJEN,MR}$ $V_{EOTEN,MR}$ $V_{CANWKEN,MR}$	-0.3	-	5.5	V	-	P_4.9
SDO, RST, VROUT, LINRX, CANRX	$V_{SDO,MR}$ $V_{RST,MR}$	-0.3	-	VDDIO+ 0.3	V	both conditions must be observed	P_4.31
	$V_{VROUT,MR}$ $V_{LINRX,MR}$ $V_{CANRX,MR}$	-0.3	-	5.5	V		
MON, KOFFDO	$V_{MON,MR}$	-0.3	-	V5V+0.3	V	both conditions must be observed	P_4.10
	$V_{KOFFDO,MR}$	-0.3	-	5.5	V		
VRIN1	$V_{VRIN1,MR}$	-0.3	-	40	V	VRIN2 open	P_4.11
VRIN2	$V_{VRIN2,MR}$	-0.3	-	40	V	VRIN1 open	P_4.12
LINIO, CANH, CANL	$V_{LINIO,MR}$ $V_{CANH,MR}$ $V_{CANL,MR}$	-40	-	40	V	-	P_4.13
OUT21...24	$V_{OUT21...24,MR}$	-0.3	-	BATPx+0 .3	V	-	P_4.14

**Currents**

DFB8...13	$I_{DFB8...13,MR}$	-5	-	5	mA	<sup>2)</sup>	P_4.15
Common Mode Input Current of VRIN1 and VRIN2	$I_{VRIN,CM,MR}$	-5	-	5	mA	$I_{VRIN,CM,MR} = I_{VRIN1} + I_{VRIN2}$ <sup>2)</sup>	P_4.16
Common Mode Input Current of VRIN1 and VRIN2, non permanent	$I_{VRIN,CM,MR}$	-15	-	15	mA	$I_{VRIN,CM,MR} = I_{VRIN1} + I_{VRIN2}$ <sup>2)</sup> , maximum duty cycle 60% and maximum on time of 1 ms, 100 h	P_4.34
Differential Current of VRIN1 and VRIN2	$\Delta I_{VRIN,MR}$	-50	-	50	mA	$\Delta I_{VRIN,MR} = (I_{VRIN1} - I_{VRIN2})/2$ <sup>2)</sup>	P_4.17
PGND	$I_{PGND,MR}$	-25	-	25	A	-	P_4.18
IGN1...4	$I_{IGN1...4,MR}$	-50	-	-	mA	<sup>2)</sup>	P_4.19

**Temperatures**

**General Product Characteristics**

**Table 1 Absolute Maximum Ratings<sup>1)</sup>** (cont'd)

$T_j = -40^{\circ}\text{C}$  to  $+150^{\circ}\text{C}$ , all voltages with respect to GND, positive current flowing into pin, (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
Junction Temperature	$T_j$	-40	–	150	$^{\circ}\text{C}$	<sup>3)</sup>	P_4.20
Storage Temperature	$T_{\text{stg}}$	-55	–	150	$^{\circ}\text{C}$	–	P_4.21

**ESD Susceptibility**

ESD Susceptibility	$V_{\text{ESDHBM}}$	-2	–	2	kV	HBM <sup>4)</sup>	P_4.22
ESD Susceptibility BAT, BATPA, BATPB, T5V1, T5V2, BATSTBY, KEY, WK, MR, OUT1...7, OUT14...24, DFB8...13, IGN1...4, CANH, CANL, LINIO, VRIN1, VRIN2 to PGND	$V_{\text{ESD,HBM}}$	-4	–	4	kV	HBM <sup>4)</sup>	P_4.23
ESD Susceptibility	$V_{\text{ESDCDM}}$	-500	–	500	V	CDM <sup>5)</sup>	P_4.24
ESD Susceptibility Pin 1, 25, 26, 50, 51, 75, 76, and 100 (corner pins)	$V_{\text{ESD1, 25, 26, 50, 51, 75, 76, 100}}$	-750	–	750	V	CDM <sup>5)</sup>	P_4.25

- 1) not subject to production test
- 2) Current has to be limited when maximum voltages are exceeded
- 3) according to qualification
- 4) ESD susceptibility, HBM according to EIA/JESD 22-A114F (1.5k  $\Omega$ , 100 pF)
- 5) ESD susceptibility, Charged Device Model "CDM" EIA/JESD22-C101 or ESDA STM5.3.1

**Notes**

1. Stresses above the ones listed here may cause permanent damage to the device. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.
2. Integrated protection functions are designed to prevent IC destruction under fault conditions described in the data sheet. Fault conditions are considered as "outside" normal operating range. Protection functions are not designed for continuous repetitive operation.

**General Product Characteristics**

**Table 2 Functional Range**

$T_j = -40^{\circ}\text{C}$  to  $+150^{\circ}\text{C}$ , all voltages with respect to GND, positive current flowing into pin, (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
Supply Voltage - Reduced Operation	$V_{\text{BAT,ro}}$	4.5	–	6	V	reduced operation range, main relay and delayed off power stages are on if enabled, remaining functions not working	P_4.26
Supply Voltage - Low Drop Range	$V_{\text{BAT,ld}}$	6	–	9	V	low drop operation range, supply regulators working with supply out of the charge pump, standby supply regulator out of operation range	P_4.27
Supply Voltage - Normal Operation range	$V_{\text{BAT,nop}}$	9	–	28	V	normal operation range <sup>1)</sup>	P_4.28
Supply Voltage - Overvoltage Range	$V_{\text{BAT,ov}}$	28	–	40	V	overvoltage, power stages are switched off	P_4.29
Supply Voltage transients <sup>2)</sup>	$d_{\text{VBAT}}/d_t$	-1	–	1	V/ $\mu\text{s}$	–	P_4.30

1) overtemperature due to bad  $R_{\text{thJA}}$  of the ECU or overload can happen

2) not subject to production test, specified by design

*Note:* Within the functional range the IC operates as described in the circuit description. The electrical characteristics are specified within the conditions given in the related electrical characteristics table.

**Table 3 Thermal Resistance**

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
Junction to Case <sup>1)</sup>	$R_{\text{thJC}}$	–	2.4	–	K/W	–	P_4.32
Junction to Ambient	$R_{\text{thJA}}$	–	–	–	K/W	<sup>2)</sup>	P_4.33

1) Not subject to production test, specified by design.

2) EIA/JESD 52\_2, FR4, 80 × 80 × 1.5 mm; 35 × Cu, 5 × Sn; 300 mm<sup>2</sup>

## **5 Operation Behavior**

The TLE8888-1QK has implemented the whole supply of an ECU. Therefore a complex control logic is implemented to provide several operation states.

In this chapter

- the ramp up and down behavior and
  - the status of the TLE8888-1QK during special conditions like 5 V undervoltage
- is described. For the description of the monitoring watchdog module see [Chapter 6](#).

In [Figure 3](#) the block diagram with all blocks affecting the status of the device and the ECU are shown. Following blocks are influenced during the different operation states and reset functions:

- Serial Interface MSC/SPI: with the serial interface the setup of the device is done
- Key input detection: start signal from key switch (KL15)
- Wake-up input detection: additional start signal e.g. from external CAN with wake-up by bus function
- Engine off timer: wake-up signal in comparator mode
- Power supply: ECU 5 V supply and 5 V sensor supplies, 5 V standby supply
- Voltage monitoring: supervision of all supplies (BAT, V5V, T5V1, T5V2)
- Main relay driver: controls external main relay to switch battery voltage to an ECU supply pin (see also application setups in [Chapter 17](#))
- Power stages and half-bridges control block
- LIN/K-Line: transmission mode depends on operation state of the ECU
- CAN: transmission mode depends on operation state of the ECU, remote wake-up function
- Reset outputs MON and RST
- Monitoring watchdog module: signature watchdog for safety applications
- Operation Mode Control

The operation mode control block consists of:

- ramp up and down sequence control logic
- the reset control logic and
- status output logic.



Operation Behavior

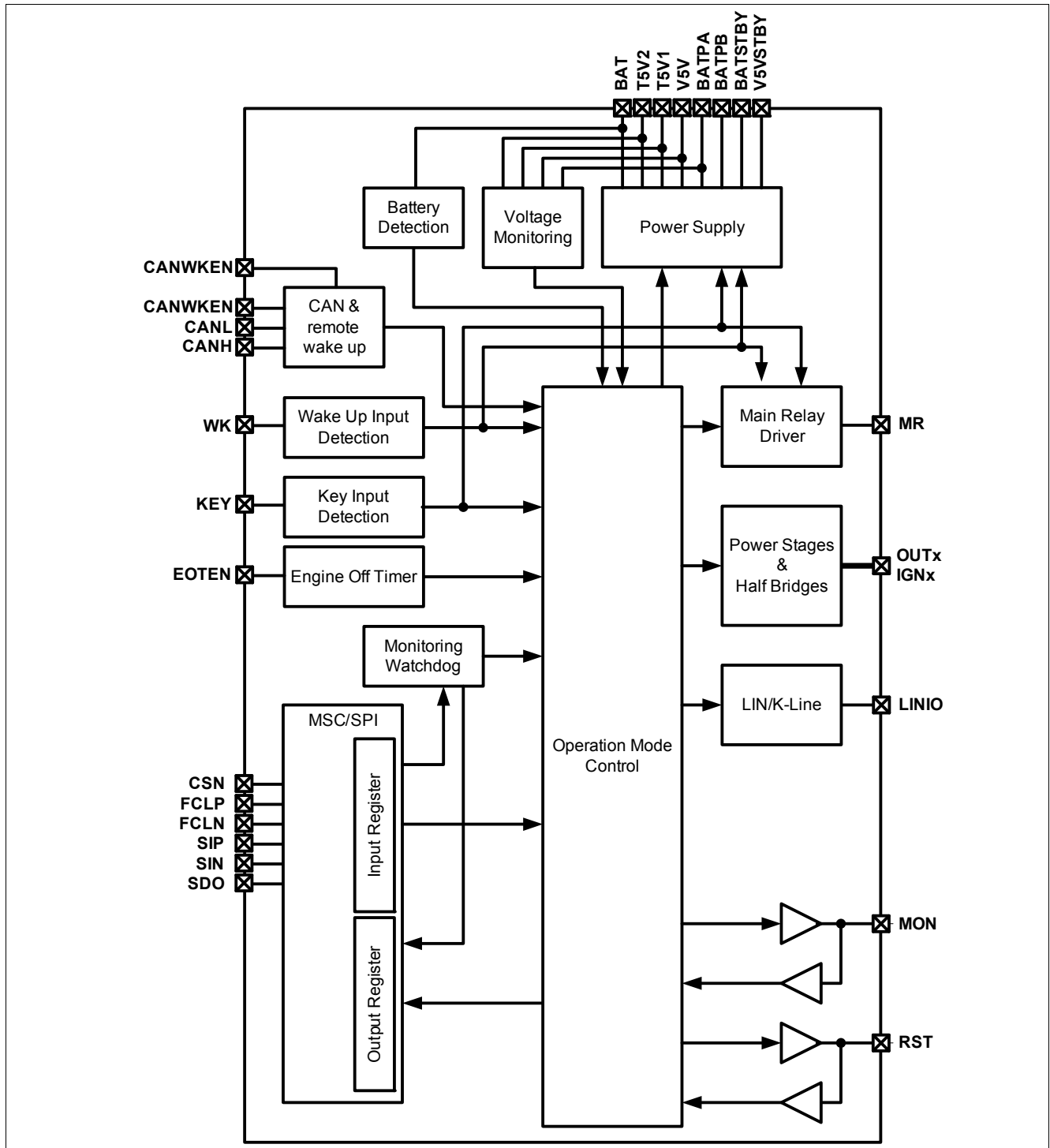


Figure 3 Block diagram operation mode control

5.1 Operation States

In **Figure 4** the state diagram of the whole ramp up and down sequence is shown. There are seven operation states:

- ECU sleep state: *KEY* and *WK* input are “low”, no wake-up signals from engine off timer or CAN are active, main relay is off, the whole ECU inclusive TLE8888-1QK is not supplied, 5 V standby supply is working if pin *BATSTBY* is supplied, engine off timer and CAN wake-up circuits are active if enabled and supplied.

## Operation Behavior

- Supply ramp up state: *KEY* input or wake<sup>1)</sup> are “high” and the supply of the TLE8888-1QK starts working, the voltage of V6V, V5V, T5V1 and T5V2 are ramping up but the voltage levels are below the undervoltage threshold. For wake-up by wake<sup>1)</sup> the ramp up of the main supply has to be finished before the ramp up timer overflow. The main relay is switched on depending on the voltage level at the pin *BAT* (see [Chapter 7.2](#))
- Normal operation state: *KEY* input or wake are “high” and main relay is switched on depending on the voltage level at the pin *BAT* or the status of bit **MR** in the status register **OpStat0** (see [Chapter 7.2](#)), the whole ECU is supplied and the status of the different functions and registers is according [Table 5](#) and [Table 6](#).
- Afterrun state: *KEY* is “low” but afterrun enable bit is set and therefore the whole ECU is supplied, the status of the different functions and registers is according [Table 5](#) and [Table 6](#) and the microcontroller can execute afterrun routines
- Afterrun reset state: the reset procedure before direct reentry in normal operation is executed if bit **AR** =1 in the configuration register **OpConfig0**
- General power-down state: the supplies of the ECU (*V5V*, *T5V1*, *T5V2*) are disabled and the power-down timer is counting, main relay remains in the switching status and the TLE8888-1QK is supplied to ensure the power-down (*V5V* drops down to 0 V) of the ECU, *V5VSTBY* is working if *BATSTBY* is supplied, all functions to external are disabled.
- Wake clear state: this state avoids permanent wake-up in failure cases. The wake clear command is executed (function according setting bit **WKCLR** in the command register **Cmd0**). All wake signals which are active after the supply ramp up and the general power-down state are reset.

1) description see [Figure 4](#), [Chapter 7.2](#), [Chapter 7.4](#) and [Chapter 12.2.4](#)

Operation Behavior

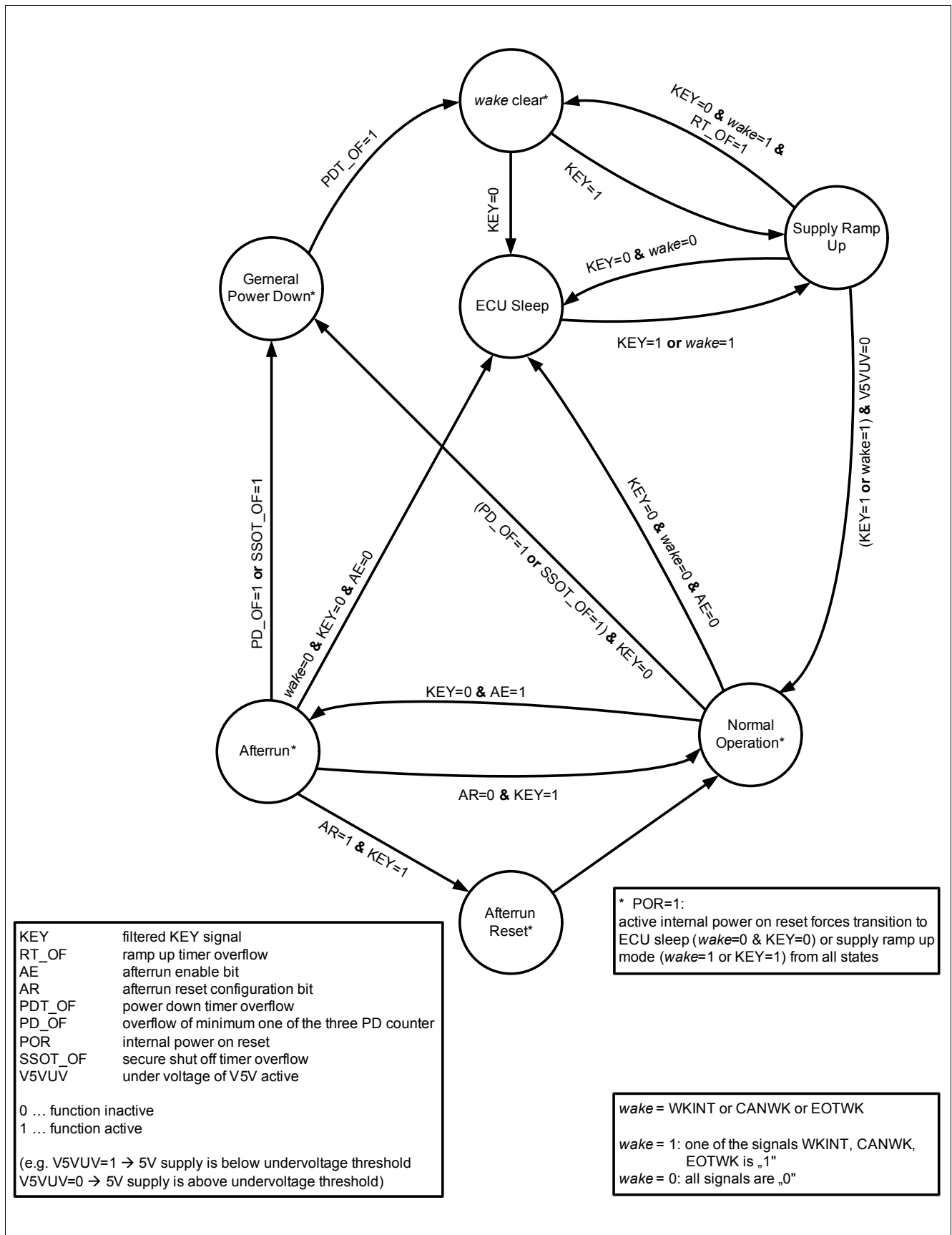


Figure 4 Operation state diagram

**Operation Behavior**

Description of the transitions:

**Table 4 Operation State Transitions**

<b>Transition</b>	<b>Condition</b>	<b>Description</b>
from all states to ECU sleep state	internal supply voltage < internal por threshold and $KEY = 0$ and $wake^{1)=0^{2)}$	internal power on reset is active and reset the whole digital logic, ECU sleep state is entered due to no wake-up signal at $KEY$ or wake
from all states to supply ramp up state	internal supply voltage < internal por threshold and $KEY = 1$ or $wake = 1^{2)}$	internal power on reset is active and reset the whole digital logic, supply ramp up state is entered due to a wake-up signal at $KEY$ or wake
ECU sleep state to supply ramp up state	$KEY > V_{KEY,th}$ or $wake = 1$	With a “high” voltage at $KEY$ or wake the wake-up of the TLE8888-1QK starts
Supply ramp up state to ECU sleep state	$KEY < V_{KEY,th}$ and $wake = 0^{2)}$	The external supply ramp up is not finished but the wake-up signals are low
Supply ramp up state to wake clear state	$KEY < V_{KEY,th}$ and $wake = 1^{2)}$ and $RT\_OF = 1$	The $KEY$ signal is low and the wake-up signals are active. The ramp up timer has an overflow which indicates a ramp up problem of the external supply (e.g. short to GND). To avoid permanent high current consumption the internal wake signals must be reset to enter the ECU sleep state.
Supply ramp up state to normal operation state	$(KEY > V_{KEY,th}$ or $wake = 1)$ and $V5V > V_{uv,V5V}^{2)}$	normal operation state is entered if the main supply voltage $V5V$ is above the undervoltage threshold, $KEY$ is high or one of the wake-up conditions are active
Normal operation state to afterrun state	$KEY < V_{KEY,th}$ and $AE = 1^{2)}$	$KEY$ is “low” and afterrun function is enabled: no changes in the setup of the TLE8888-1QK
Normal operation state to ECU sleep state	$AE = 0$ and $KEY < V_{KEY,th}$ and $wake = 0^{2)}$	normal shut off
Normal operation state to general power-down state	$(PD\_OF = 1$ or $SSOT\_OF = 1)$ and $KEY < V_{KEY,th}^{2)}$	$KEY$ is low and watchdog error shut off with overflow of the power-down counter or secure shut off due to expired secure shut off timer
Afterrun state to ECU sleep state	$AE = 0$ and $KEY < V_{KEY,th}$ and $wake = 0^{2)}$	normal shut off in afterrun mode with the reset of the afterrun enable bit $AE$ by the microcontroller
Afterrun state to general power-down state	$PD\_OF = 1$ or $SSOT\_OF = 1$	watchdog error shut off with overflow of the power-down counter or secure shut off due to expired secure shut off timer
Afterrun state to normal operation state	$KEY > V_{KEY,th}$ and $AR = 0^{2)}$	reentry of normal operation with $KEY$ on during afterrun operation, no reset is performed ( $AR = 0$ )
Afterrun state to afterrun reset state	$KEY > V_{KEY,th}$ and $AR = 1^{2)}$	reentry of normal operation with $KEY$ on during afterrun operation with reset ( $AR = 1$ )
Afterrun reset state to normal operation state		transition to normal operation with the next active internal clock edge after entry to the afterrun reset state

**Operation Behavior**

**Table 4 Operation State Transitions (cont'd)**

Transition	Condition	Description
General power-down state to wake clear state	PDT_OF = 1	with the power-down timer overflow the reset of the internal wake signals must be performed
Wake clear state to ECU sleep state	$KEY < V_{KEY,th}$	after reset of the internal wake signals and <i>KEY</i> is low the ECU sleep state is entered, no unwanted wake-up due to a failure condition will occur
Wake clear state to supply ramp up state	$KEY > V_{KEY,th}$	after reset of the internal wake signals and <i>KEY</i> is high the supply ramp up state is entered, no unwanted wake-up due to a failure condition at the CAN bus and pin <i>WK</i> will occur

- 1) wake = WKINT or CANWK or EOTWK (see [Chapter 7.2](#), [Chapter 7.4](#) and [Chapter 12.2.4](#))
- 2) including defined filter times

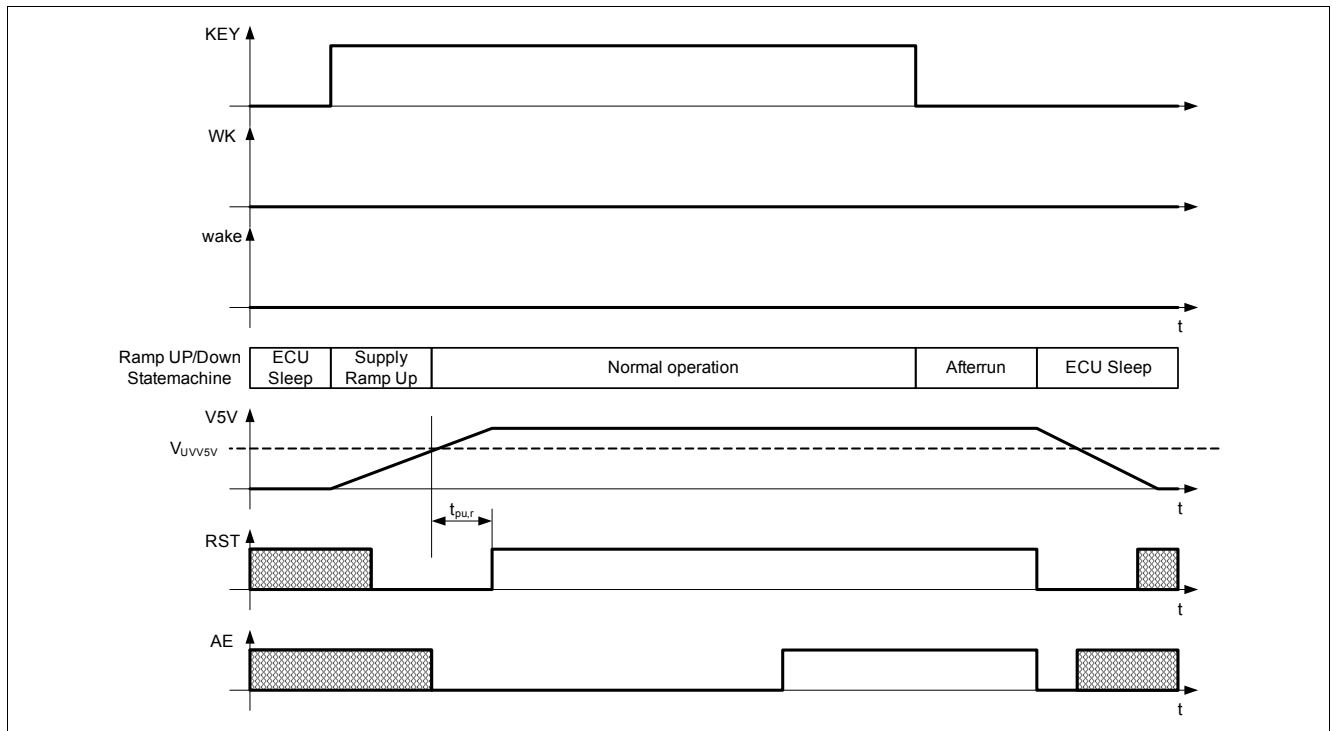
The two states:

- normal operation
- afterrun

are reflected in the bit **OM** of the status register **OpStat0**.

The power-down time is defined with the bits **PDT** of the configuration register **OpConfig0**.

In [Figure 5](#) a sequence with wake-up by *KEY* and go to sleep with afterrun mode is shown.



**Figure 5 Ramp up and down sequence diagram with wake-up by *KEY* and afterrun mode**

**5.2 Reset and Operation Modes**

## Operation Behavior

The TLE8888-1QK provides several supervision functions which lead to some dedicated reset states and special operation modes of the device and the ECU.

There are two bidirectional reset pins *MON* and *RST* implemented. For the behavior during reset of the reset pins *MON* and *RST* and the other status of the TLE8888-1QK see [Table 5](#) and [Table 6](#).

Following reset functions and special states are implemented:

- Internal power on reset: the internal power on reset detection circuit monitors the voltage level of the internal supply. For an internal supply voltage below the internal power on reset threshold the whole digital logic of the TLE8888-1QK is reset which results in the ECU sleep state or supply ramp up state depending on the state of *KEY* and wake. If the voltage level for operation is high enough the 6 V pre regulator is working. The 5 V supplies are disabled till the internal supply level is over the power on threshold level.
- ECU power on reset: this is the reset at ramp up of the power supplies and the beginning of the operation. The pins *RST* and *MON* are pulled to GND to reset the microcontroller and all devices connected to the pin *MON*. The device is reset to the initial reset status. The reset is released with a voltage at pin *V5V* higher than the **V5V Undervoltage Detection Hysteresis** after **tpu,r**.
- Reset during undervoltage of the 5 V supply *V5V*: this reset occurs during undervoltage of the 5 V ECU supply. The pins *RST* and *MON* are pulled to GND to reset the microcontroller and all devices connected to the pin *MON*. The delayed switch off function is active regarding the configuration setup. The status of the main relay is according to the status of the wake-up pins *KEY* and *WK* and the voltage level of the supply pin *BAT*.
- State during undervoltage of the 5 V supplies *T5V1* and *T5V2*: with the undervoltage detection of the tracker supplies diagnosis bits are set but there is no effect to the behavior of the device.
- Reset during overvoltage of the 5 V supply *V5V*: with the overvoltage detection of the 5 V ECU supply all functions of the device which have an effect externally or can lead to overcurrent or overtemperature are disabled (e.g. power stages, LIN/CAN/MSB/SPI communication). The pins *RST* and *MON* are low.
- State during overvoltage of the 5 V supplies *T5V1* and *T5V2*: with the detection of overvoltage of the tracker supplies diagnosis bits are set but there is no effect to the behavior of the device.
- Power stages switch off during overvoltage of the battery supply *BAT*: For voltages at the supply pin *BAT* higher than the overvoltage threshold the power stages are disabled to avoid too high clamping energy during switch off. Damage of the switches is prevented.
- Watchdog reset: If the reset counter is incremented and the reset is enabled (bit **WDREN** = 1) the microcontroller is reset with a “low” at the pin *RST*. The power stages are disabled and the LIN/CAN communication is set to receive only mode.
- Software reset from microcontroller: with the software reset command (command register **CmdSR**) the software reset is activated. The device is reset to the reset status defined in [Table 5](#) and [Table 6](#). The activation of the software reset triggers an increase of the power-down counter by 1.
- Reset with an external forced “low” at *RST*: With a detected “low” at the *RST* pin the TLE8888-1QK is reset to the reset status defined in [Table 5](#) and [Table 6](#).
- Power stages switch off with an external forced “low” at *MON*: With a detected “low” at the *MON* pin the power stages are disabled (**O1E** to **O24E**, **IGN1E** to **IGN4E** are set to “0”). After *MON*=0 event the power stages must be enabled again.
- State with time out of the MSC communication: With the time out of the MSC communication the power stages are disabled (**O1E** to **O24E**, **IGN1E** to **IGN4E** are set to “0”). After the next valid received data frame the power stages must be enabled again.
- Afterrun reset: This reset is executed if the bit **AR** of register **OpConfig0** is 1 and the transition from afterrun state to normal operation is triggered (definition see [Table 6](#)).

**Table 5 Overview Behavior at Reset and Operation Conditions (part 1)**

Effect to functions:	Conditions						
	Internal power on reset	ECU power on reset	Undervoltage V5V	Undervoltage T5V1, T5V2	Oversvoltage V5V <sup>1)</sup>	Oversvoltage T5V1, T5V2	Oversvoltage BAT
notes	forces state change	only after transition from Supply Ramp Up to Normal Operation state for <b>tpu,r</b>	timing see <b>Chapter 8.7</b> and <b>Table 7</b>	timing see <b>Chapter 8.7</b>	timing see <b>Chapter 8.7</b> and <b>Table 7</b>	timing see <b>Chapter 8.7</b>	timing see <b>Chapter 8.7</b>
V5VSTBY, V6V	en.	en.	en.	en.	en.	en.	en.
V5V, T5V1, T5V2	dis.	en.	en.	en.	en.	en.	en.
MSC/SPI communication	dis.	dis.	dis.	en.	dis.	en.	en.
Main relay	en. <sup>2)</sup>	en. <sup>2)</sup>	en. <sup>2)</sup>	en. <sup>2)</sup>	en. <sup>2)</sup>	en. <sup>2)</sup>	en. <sup>2)</sup>
Low-side switches / Half bridges / Push Pull Driver	off/dis./off	off/dis./off	off/dis./off	no change	off/dis./off	no change	off/dis./off
OUT17 and OUT21 with delayed switch off function	dis.	dis.	delayed switch off activated	en.	delayed switch off activated	en.	dis.
LIN/CAN communication	dis.	rec. only, after release setup acc. bits <b>CAN, LIN, CANWE, LINWE</b> <sup>3)</sup>	rec. only, after release setup acc. bits <b>CAN, LIN, CANWE, LINWE</b> <sup>3)</sup>	acc. bits <b>CAN, LIN, CANWE, LINWE</b>	dis., after release setup acc. bits <b>CAN, LIN, CANWE, LINWE</b>	acc. bits <b>CAN, LIN, CANWE, LINWE</b>	acc. bits <b>CAN, LIN, CANWE, LINWE</b>
MON (output function)	“low” <sup>4)</sup>	“low”	“low”	no effect <sup>5)</sup>	“low”	no effect <sup>5)</sup>	no effect <sup>5)</sup>
RST (output function)	“low” <sup>4)</sup>	“low”	“low”	no effect <sup>5)</sup>	“low”	no effect <sup>5)</sup>	no effect <sup>5)</sup>
Watchdog Sequence, Heartbeat Timer <sup>6)</sup>	reset	reset	reset	no effect	reset	no effect	no effect

**Table 5 Overview Behavior at Reset and Operation Conditions (part 1) (cont'd)**

Effect to functions:	Conditions						
	Internal power on reset	ECU power on reset	Undervoltage V5V	Undervoltage T5V1, T5V2	Overvoltage V5V <sup>1)</sup>	Overvoltage T5V1, T5V2	Overvoltage BAT
WWD Error Counter, FWD pass counter, Total error counter	reset	reset	reset	no effect	reset	no effect	no effect
PD Counter	reset	reset	reset	no effect	reset	no effect	no effect
Reset Counter; SSOT	reset	reset	reset	no effect	reset	no effect	no effect
<b>AR; CANWE; LINWE; FWDQUEST</b>	reset	reset	reset	no effect	reset	no effect	no effect
<b>AE; WWDConfig0; WDCConfig0</b> ; watchdog diagnosis bits	reset	reset	reset	no effect	reset	no effect	no effect
Logic and MSC/SPI register bits <sup>7)8)</sup>	reset	reset	reset, diagnosis bit is set	diagnosis bits are set	no effect	diagnosis bits are set	diagnosis bit is set
<b>EOTWK, CANWK, WKINT</b>	no effect	no effect	reset	no effect	no effect	no effect	no effect

- 1) for voltages greater than the maximum ratings of pin V5V behavior is not guaranteed
- 2) according the definition in [Chapter 7](#)
- 3) after release of RST (transition from low to high) there is a time delay of **tdel,r** before configuration is enabled
- 4) active pull down if supply voltage is high enough
- 5) pull up of open drain output is active
- 6) start of watchdog sequence after release of reset
- 7) valid for all register bits which are not described in [Table 5](#) or [Table 6](#)
- 8) During active delayed switch off mode some register bits related to the power stages are not reset, see [Chapter 9.4](#)



**Table 6 Overview Behavior at Reset and Operation Conditions (part 2)**

Effect to functions:	Conditions							
	Watchdog reset	Safe State	SW reset from micro-controller	MON switch off (input function)	RST reset (input function)	MSC time out	afterrun reset	
							no reset AR=0	reset AR=1
note	status during reset pulse <b>top,r</b>		status during reset pulse <b>tint,r</b>	masked by MON output function	masked by RST output function	status till next valid MSC communication		
V5VSTBY, V6V	en.	en.	en.	en.	en.	en.	en.	en.
V5V, T5V1, T5V2	en.	en.	en.	en.	en.	en.	en.	en.
MSC/SPI communication	dis.	en.	en.	en.	dis.	en.	en.	dis.
Main relay	en. <sup>1)</sup>	en.	en. <sup>1)</sup>	en. <sup>1)</sup>	en. <sup>1)</sup>	en. <sup>1)</sup>	en. <sup>1)</sup>	en. <sup>1)</sup>
Low-side switches / Half bridges / Push Pull Driver	off/dis./off	off/dis./off	off/dis./off <sup>3)</sup>	off/dis./off	off/dis./off	off/dis./off	no change	off/dis./off
OUT17 and OUT21 with delayed switch off function	no trigger if termination of delayed switch off function	no trigger if termination of delayed switch off function	dis. <sup>3)</sup>	delayed switch off activated	delayed switch off activated	delayed switch off activated	en.	dis.

**Table 6 Overview Behavior at Reset and Operation Conditions (part 2) (cont'd)**

Effect to functions:	Conditions							
	Watchdog reset	Safe State	SW reset from micro-controller	MON switch off (input function)	RST reset (input function)	MSC time out	afterrun reset	
							no reset AR=0	reset AR=1
LIN/CAN communication	acc. bits <b>CAN, LIN, CANWE, LINWE</b>	acc. bits <b>CAN, LIN, CANWE, LINWE</b>	acc. bits <b>CAN, LIN, CANWE, LINWE</b>	acc. bits <b>CAN, LIN, CANWE, LINWE</b>	rec. only, after release setup acc. bits <b>CAN, LIN, CANWE, LINWE</b> <sup>2)</sup>	acc. bits <b>CAN, LIN, CANWE, LINWE</b>	acc. bits <b>CAN, LIN, CANWE, LINWE</b>	rec. only, after release setup acc. bits <b>CAN, LIN, CANWE, LINWE</b> <sup>2)</sup>
MON	“low”	“low”	“low” <sup>3)</sup>	forced from outside	“low”	no effect <sup>4)</sup>	no effect <sup>4)</sup>	“low”
RST	“low”	no effect <sup>4)</sup>	no effect <sup>4)</sup>	no effect <sup>4)</sup>	forced from outside	no effect <sup>4)</sup>	no effect <sup>4)</sup>	“low”
Watchdog Sequence, Heartbeat Timer <sup>5)</sup>	reset	no effect	reset	no effect	reset	no effect	no effect	reset
WWD Error Counter, FWD pass counter, Total error counter	reset	no effect	reset	no effect	reset	no effect	no effect	reset
PD Counter	no effect	no effect	increment +1	no effect	no effect	no effect	no effect	no effect
Reset Counter; SSOT	no effect	no effect	no effect	no effect	no effect	no effect	no effect <sup>6)</sup>	no effect <sup>6)</sup>
<b>AR; CANWE; LINWE; FWDQUEST</b>	no effect	no effect	no effect	no effect	no effect	no effect	no effect	no effect

**TLE8888-1QK**  
**Engine Machine System IC**  
**Operation Behavior**

**Table 6 Overview Behavior at Reset and Operation Conditions (part 2) (cont'd)**

Effect to functions:	Conditions							
	Watchdog reset	Safe State	SW reset from micro-controller	MON switch off (input function)	RST reset (input function)	MSC time out	afterrun reset	
							no reset AR=0	reset AR=1
AE; WWDConfig0; WDConfig0; watchdog diagnosis bit	reset	no effect	reset	no effect	reset	no effect	no effect	reset
Logic and MSC/SPI register bits <sup>7)8)</sup>	no effect	no effect	reset	no effect	reset	diagnosis bit is set	no effect	reset
EOTWK, CANWK, WKINT	no effect	no effect	no effect	no effect	no effect	no effect	no effect	no effect

- 1) according the definition in [Chapter 7](#)
- 2) after release of RST (transition from low to high) there is a time delay of **tdel,r** before configuration is enabled
- 3) status for time **top,r**
- 4) pull up of open drain output is active
- 5) start of watchdog sequence after release of reset
- 6) SSOT reset due to **KEY=1**
- 7) valid for all register bits which are not described in [Table 5](#) or [Table 6](#)
- 8) During active delayed switch off mode some register bits related to the power stages are not reset, see [Chapter 9.4](#)

**Operation Behavior**

**Table 7 Reset Time Definition**

Reset Function		Reset Time at RST Output	Related Status Bits in Register <b>OpStat1</b>
internal power on reset			all registers are reset
ECU power on reset		$t_{pu,r}$	
Undervoltage V5V		$t_{pu,r}$	<b>V5VUVR</b>
Overvoltage V5V		$t_{pu,r}$	<b>V5VOVR</b>
Watchdog reset		$t_{op,r}$	<b>WDRES</b>
RST reset forced from outside		forced from outside	<b>RSTR</b>
Software reset from microcontroller		no effect	all registers are reset <sup>1)</sup>
Afterrun reset	<b>AR="0"</b>	no effect	
	<b>AR="1"</b>	$t_{op,r}$	<b>ARES</b>

1) internal reset with  $t_{int,r}$  active

After a reset with pin *RST* the configuration of the CAN and LIN bus is delayed by the time **tdel,r** to avoid that undefined microcontroller pins are affecting the buses. During this delay time the configuration bits can be changed by a write access to the register.

**Operation Behavior**

**5.3 Electrical Characteristics Operation Behavior**

**Table 8 Electrical Characteristics: Operation Behavior**

$V_S = 13.5\text{ V}$ ,  $V_{VSV} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to ground, positive current flowing into pin (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
Internal power on reset threshold	$V_{por,int,th}$	-	-	2.8	V	of internal supply voltage	P_5.3.1
Supply voltage range for internal supply	$V_{BATP,int}$	4.5	-	-	V	only valid if the charge pump has ramped up before voltage drop, both condition must be fulfilled to ensure no internal power on reset	P_5.3.2
	$V_{V6V,int}$	3.5	-	-	V		

**Power-Down Timer**

Power-down time 1	$t_{pd,1}$	-	100	-	ms	-	P_5.3.3
Power-down time 2	$t_{pd,2}$	-	200	-	ms	-	P_5.3.4
Power-down time 3	$t_{pd,3}$	-	300	-	ms	-	P_5.3.5
Power-down time 4	$t_{pd,4}$	-	400	-	ms	-	P_5.3.6
Power-down time accuracy	$t_{pd,a}$	-10	-	+10	%	-	P_5.3.7

**Ramp Up timer**

Ramp up time	$t_{ru}$	185	-	650	ms	-	P_5.3.8
--------------	----------	-----	---	-----	----	---	---------

**MON In- Output**

Input low level	$V_{il}$	-	-	$0.29 \cdot V_{5V}$	V	-	P_5.3.10
Input high level	$V_{ih}$	$0.7 \cdot V_{5V}$	-	-	V	-	P_5.3.11
Input hysteresis	$V_{ihys}$	0.1	-	1	V	-	P_5.3.12
Pull up current	$I_{imax}$	-100	-	-	$\mu\text{A}$	$V_{in} = 0\text{ V}$ , pull up to $V_{5V}$	P_5.3.13
Input de-glitch time for low and high level detection	$t_{i,d}$	0.5	-	3.5	$\mu\text{s}$	-	P_5.3.14
Output low level operation	$V_{ol}$	-	-	0.7	V	$I_{out} = 2\text{ mA}$ ; $V_{V5V} = 2.5\text{ V}$	P_5.3.15
Output current capability	$I_{omax}$	15 <sup>1)</sup>	-	-	mA	$V_{MON} = 5\text{ V}$	P_5.3.16

**RST In- Output**

Input low level	$V_{il}$	-	-	$0.29 \cdot V_{DDIO}$	V	-	P_5.3.17
-----------------	----------	---	---	-----------------------	---	---	----------

**Operation Behavior**

**Table 8 Electrical Characteristics: Operation Behavior (cont'd)**

$V_S = 13.5\text{ V}$ ,  $V_{VSV} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to ground, positive current flowing into pin (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
Input high level	$V_{ih}$	$0.7 \cdot V_{DDIO}$	–	–	V	–	P_5.3.18
Input hysteresis	$V_{ihys}$	0.1	–	1	V	–	P_5.3.19
Pull up current	$I_{imax}$	-100	–	–	$\mu\text{A}$	$V_{in} = 0\text{ V}$ , pull up to $V_{DDIO}$	P_5.3.20
Input de-glitch time for low and high level detection	$t_{i,d}$	0.5	–	3.5	$\mu\text{s}$	–	P_5.3.21
Output low level operation	$V_{ol}$	–	–	0.7	V	$I_{out} = 2\text{ mA}$ ; $V_{VSV} = 2.5\text{ V}$	P_5.3.22
Output current capability	$I_{omax}$	15 <sup>1)</sup>	–	–	mA	$V_{RST} = 5\text{ V}$	P_5.3.23

**Reset Times**

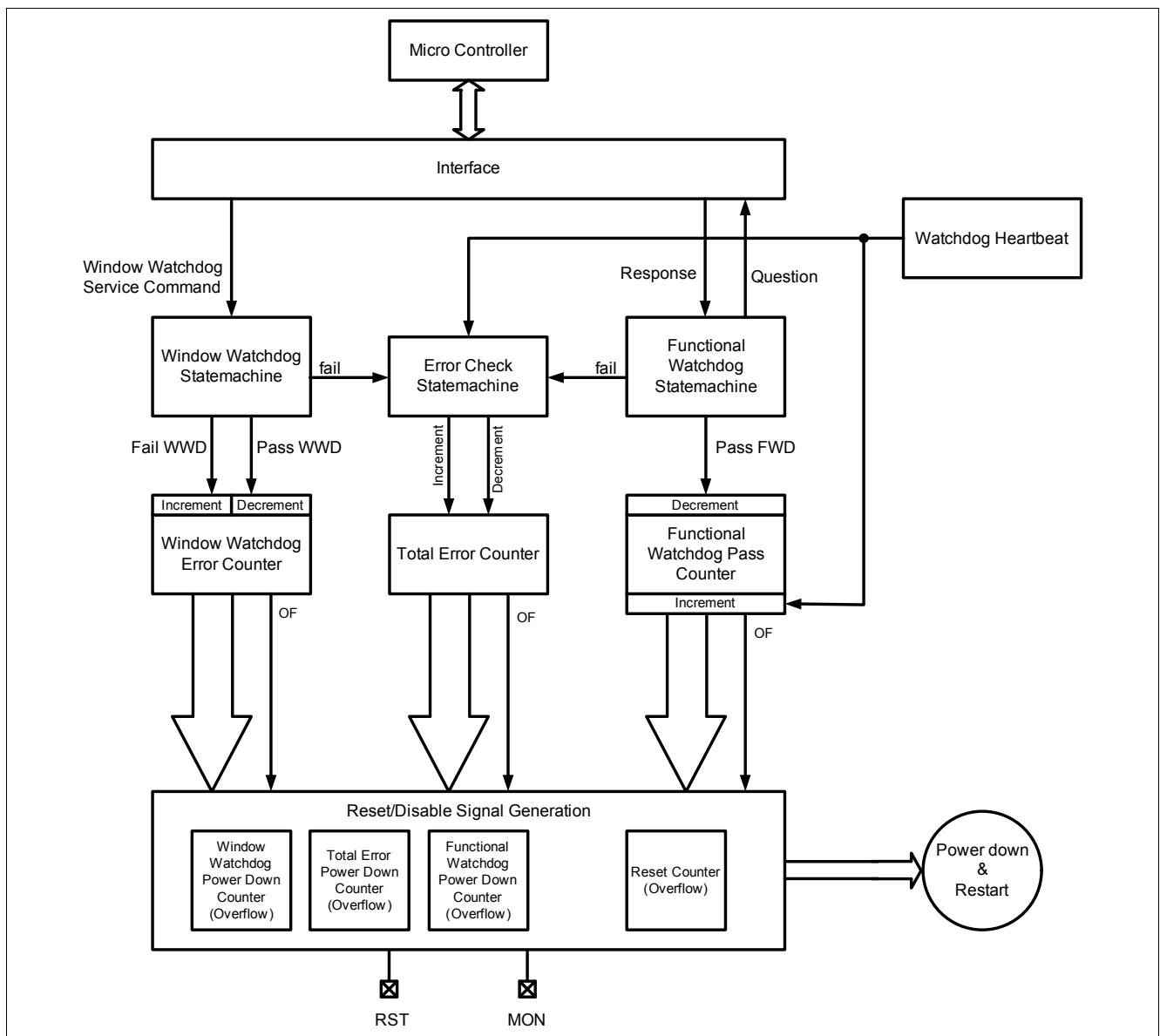
Power up reset time	$t_{pu,r}$	12	16	20	$\mu\text{s}$	–	P_5.3.24
Operation reset time	$t_{op,r}$	1	2	4	$\mu\text{s}$	–	P_5.3.25
Internal reset time	$t_{int,r}$	–	–	1	$\mu\text{s}$	–	P_5.3.26
Delay time after reset	$t_{del,r}$	6	10	14	$\mu\text{s}$	–	P_5.3.27

1) Application must ensure that current into this pin does not exceed this value.

Monitoring Watchdog Module (Signature Watchdog)

## 6 Monitoring Watchdog Module (Signature Watchdog)

The watchdog function is intended for a temporal and logical monitoring of the microcontroller's program sequence. In **Figure 6** the block diagram of the monitoring module is drawn. The module has an interface to the MSC/SPI block. The monitoring of the microcontroller is done by the separate check of the timing with the window watchdog and the logical operation check by the functional watchdog. Therefore the microcontroller must send a window watchdog service command for the window watchdog and four response bytes for the functional check. The results of the checks affect the corresponding counter (window watchdog error counter or functional watchdog pass counter). Additionally a total error counter module is implemented which detects the occurrence of watchdog errors (the timing check or the functional is not passed) and changes the status of the total error counter accordingly. For the independent functional watchdog and the total error counter a heartbeat is implemented to define the increment timing of both functions.



**Figure 6** Block diagram of the Monitoring Watchdog Function

**Monitoring Watchdog Module (Signature Watchdog)**

The status of the counters (window watchdog error counter, functional watchdog pass counter and total error counter) and the corresponding overflow signals are inputs to the watchdog reset, power-down counter and the secure shut off timer. This information is used to affect the operation status of the TLE8888-1QK and the status of the pins *MON* and *RST*.

The software of the microcontroller has to make sure that the program sequence and any safety critical parts of the microcontroller are self tested by performing related routines according to the received questions.

**Table 9**

Bit Name	Register	Type	Description
<b>General</b>			
<b>WDRES</b>	<b>OpStat1</b>	status	reset caused by watchdog (general status bit)
<b>RESC</b>	<b>WdStat0</b>	status	reset counter value
<b>SSOTS</b>	<b>WdStat0</b>	status	Secure shut off timer start status
<b>WDHBTPRE</b>	<b>WDHBT0</b>	status	heartbeat timer pre divider value
<b>WDHBT</b>	<b>WDHBT1</b>	status	heartbeat timer value
<b>WDHBTP</b>	<b>WDConfig0</b>	configuration	definition of heartbeat period for functional watchdog and total error counter
<b>CANWE</b>	<b>WDConfig1</b>	configuration	CAN operation mode during safe state
<b>LINWE</b>	<b>WDConfig1</b>	configuration	LIN operation mode during safe state
<b>WDREN</b>	<b>WDConfig1</b>	configuration	watchdog reset enable
<b>FWDQG</b>	<b>WDConfig1</b>	configuration	Functional watchdog question generation pattern setup
	<b>MSCReadWd0</b>	command	Multi read command for <b>WdStat0</b> , <b>TECStat</b> , <b>FWDStat0</b> , <b>FWDStat1</b> , <b>WdDiag</b> , <b>WWDStat</b> , <b>WDConfig0</b> and <b>WWDConfig0</b>
	<b>MSCReadWd1</b>	command	Multi read command for <b>WDHBT0</b> , <b>WDHBT1</b> , <b>WdStat0</b> and <b>WdStat1</b>
	<b>WDHBTPSyncCmd</b>	command	heartbeat period synchronization command
<b>WDHBTS</b>	<b>Cmd0</b>	command	watchdog heartbeat timer sample command
<b>Window Watchdog</b>			
<b>WWDEC</b>	<b>WWDStat</b>	status	value of error counter for window watchdog
<b>WWDSCR</b>	<b>WdStat0</b>	status	Window watchdog service command received status
<b>WWDPDC</b>	<b>WdStat0</b>	status	power-down counter value of window watchdog
<b>WWDECI</b>	<b>WWDConfig1</b>	configuration	definition of the increment value of error counter for window watchdog
<b>WWDECD</b>	<b>WWDConfig1</b>	configuration	definition of the decrement value of error counter for window watchdog
<b>WWDCWT</b>	<b>WWDConfig0</b>	configuration	closed window time
<b>WWDOWT</b>	<b>WWDConfig0</b>	configuration	open window time
	<b>WWDServiceCmd</b>	command	window watchdog service command
<b>WWDSCCE</b>	<b>WdDiag</b>	diagnosis	window watchdog service command too early
<b>WWDTO</b>	<b>WdDiag</b>	diagnosis	window watchdog time out



Monitoring Watchdog Module (Signature Watchdog)

Table 9 (cont'd)

Bit Name	Register	Type	Description
<b>WWDRES</b>	<b>WdDiag</b>	diagnosis	reset caused by window watchdog
<b>Functional Watchdog</b>			
<b>FWDQUEST</b>	<b>FWDStat1</b>	status	question definition
<b>FWDRESPC</b>	<b>FWDStat1</b>	status	response counter
<b>FWDPC</b>	<b>FWDStat0</b>	status	pass counter value of functional watchdog
<b>FWDPCD</b>	<b>WdStat1</b>	status	power-down counter value of functional watchdog
<b>FWDPCI</b>	<b>FWDConfig</b>	configuration	definition of the increment value of pass counter for functional watchdog
<b>FWDPCD</b>	<b>FWDConfig</b>	configuration	definition of the decrement value of pass counter for functional watchdog
<b>FWDKQ</b>	<b>WDConfig1</b>	configuration	Keep question function set up
	<b>FWDRespCmd</b>	command	response write command
	<b>FWDRespSync Cmd</b>	command	response write command with heartbeat synchronization at received response byte 0
<b>FWDREA</b>	<b>WdDiag</b>	diagnosis	response error of actual question
<b>FWDREL</b>	<b>WdDiag</b>	diagnosis	response error of last answer
<b>FWDRES</b>	<b>WdDiag</b>	diagnosis	reset caused by functional watchdog
<b>Total Error Counter</b>			
<b>TEC</b>	<b>TECStat</b>	status	total error counter value
<b>TECPDC</b>	<b>WdStat1</b>	status	power-down counter value of total error counter part
<b>TECI</b>	<b>TECConfig</b>	configuration	definition of the increment value of total error counter
<b>TECD</b>	<b>TECConfig</b>	configuration	definition of the decrement value of total error counter
<b>TECRES</b>	<b>WdDiag</b>	diagnosis	reset caused by total error counter

## 6.1 Window Watchdog

For the timing check the microcontroller has to send periodically the window watchdog service command **WWDServiceCmd**. The window watchdog is triggered correctly if the command is received inside the open window of the window watchdog sequence. The check result is used to change the value of the window watchdog error counter. If the check is passed the counter will be decremented and for errors it will be incremented. Additionally a write access to configuration register **WWDConfig0** causes also an incrementation of the window watchdog error counter. The incrementation of the window watchdog error counter (error is occurred) is an input for the total error counter (**Chapter 6.3**). In **Figure 7** the state machine of the window watchdog is shown.

The values for incrementation or decrementation can be set in the configuration register **WWDConfig1**. The window watchdog error counter is a 6 bit counter. The influence of the counter values to the operation behavior is shown in **Table 11** and **Table 12**.

The window watchdog sequence for the timing check consists of a closed window followed by an open window (see **Figure 8**). A watchdog sequence starts with:

- the release of a reset of the monitoring module (see **Table 5** and **Table 6** in **Chapter 5.2**)
- a window watchdog service command

**Monitoring Watchdog Module (Signature Watchdog)**

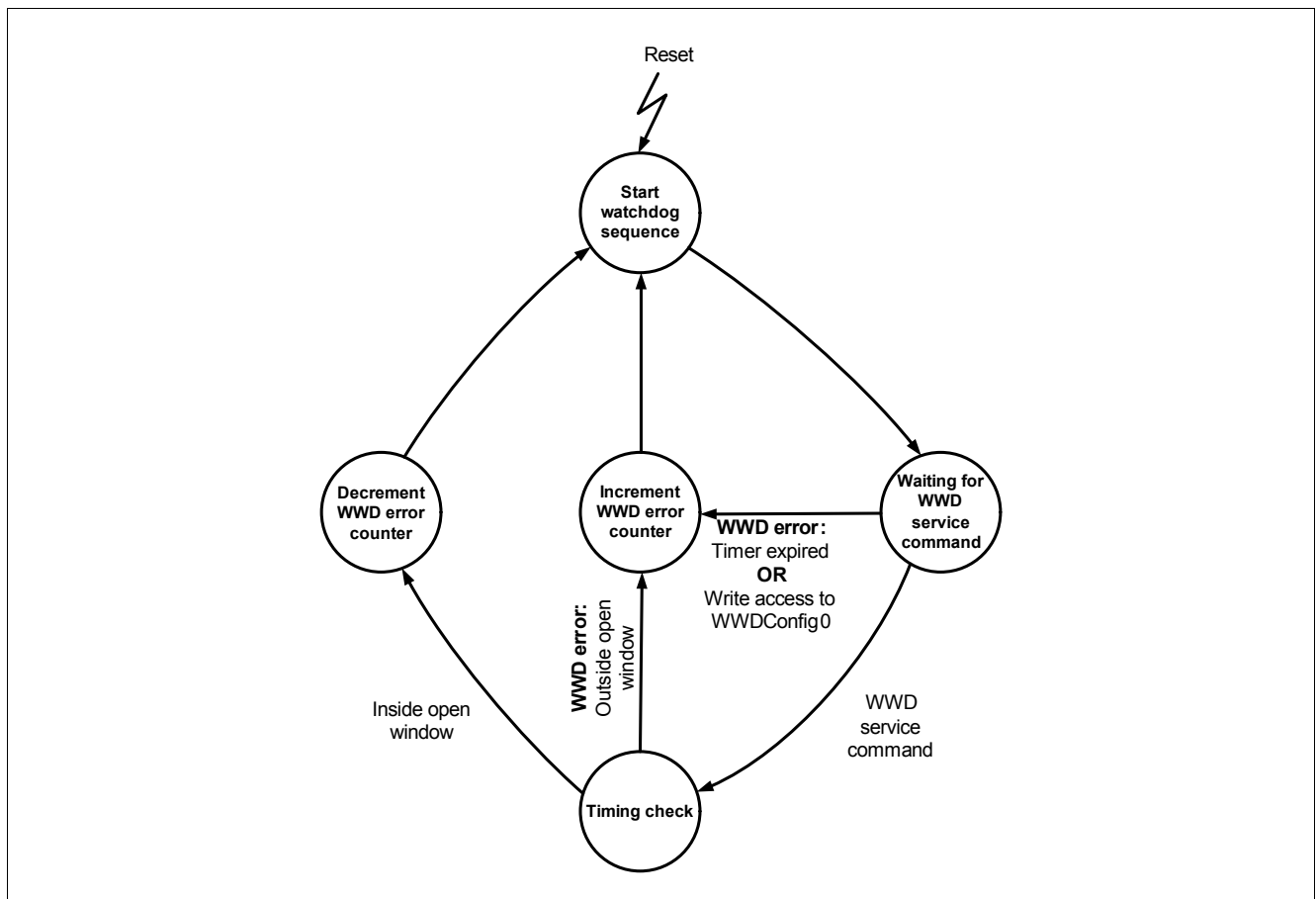
- a write to the window time configuration register **WWDConfig0**
- a timer overflow of the watchdog timer

In **Figure 8** the two parts of one watchdog sequence are shown. After the power on reset it is running in an endless loop with the defined time for the open and closed window. It is only stopped at active reset signals or outside normal operating conditions **Table 5** and **Table 6** in **Chapter 5.2**.

The timing of the window watchdog sequence can be set with a write command to the configuration register **WWDConfig0** or directly with the data bits of the **WWDServiceCmd**. With a write access to the configuration register **WWDConfig0** the watchdog window sequence is started and the window watchdog error counter is incremented.

The check is passed if the command is received inside the open window. A command send too early or a missing command leads to an error. In the diagnosis register **WdDiag** the bit **WWDSC** signalizes a window watchdog service command received too early and the bit **WWDTO** signalizes a time out (no window watchdog service command received before end of open window) of the last sequence. The diagnosis information is not cleared with the read out.

The bit **WWDSCR** in the status register **WdStato** signalizes a received window watchdog service command at the last watchdog sequence. The reset of this bit is done with a readout of the bit or with the window watchdog time-out.



**Figure 7 State Diagram of the Window Watchdog Module**

Monitoring Watchdog Module (Signature Watchdog)

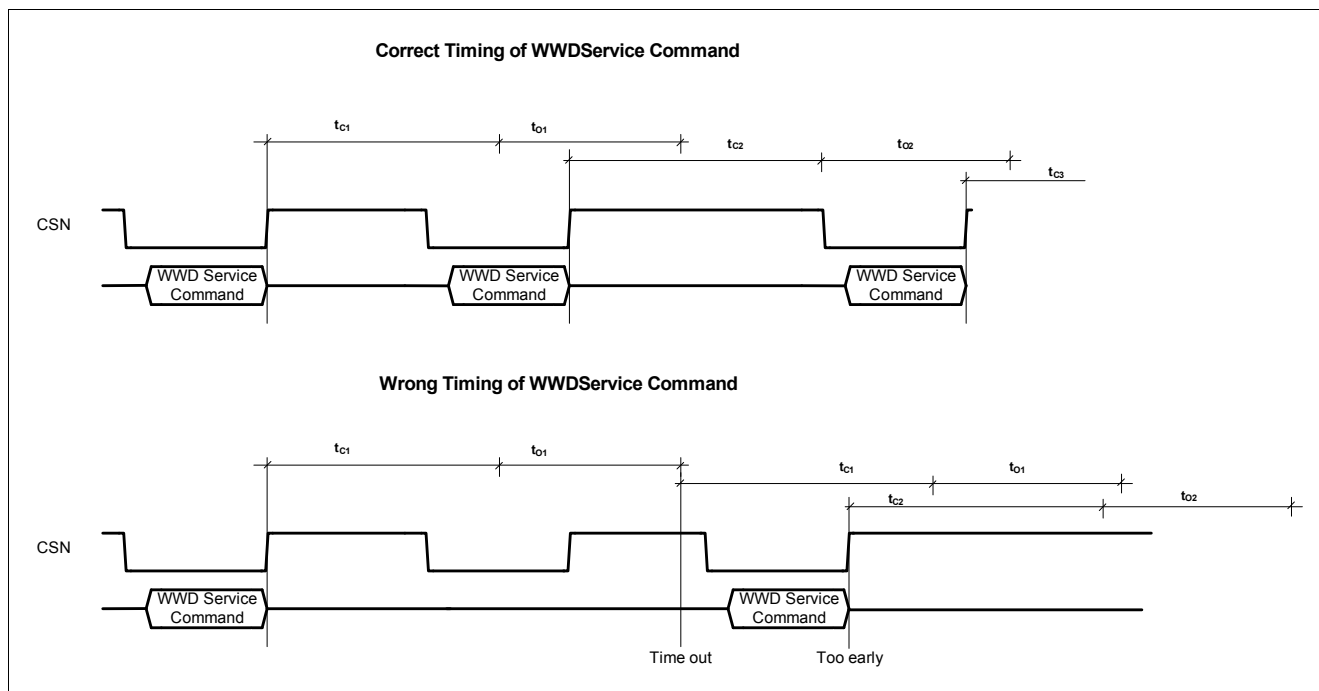


Figure 8 Watchdog Sequence Timing

## 6.2 Functional Watchdog

For the functional check the microcontroller has to send with the commands **FWDRespCmd** (functional watchdog response command) or **FWDRespSyncCmd** (functional watchdog response and synchronisation command) the right four response bytes to the actual question defined by the TLE8888-1QK. The response bytes are checked for correctness.

A pass of the check triggers a decrement of the functional watchdog pass counter. A functional watchdog error (FWD error) is not affecting the functional watchdog pass counter but it is used for the total error counter as an input signal (see [Chapter 6.3](#)). A FWD error is defined as:

- received response byte 0 with **FWDRespCmd** and minimum one of the response bytes are wrong
- received response byte 0 with **FWDRespSyncCmd** and minimum one of the response bytes are wrong
- the watchdog heartbeat timer period synchronisation command **WDHBTPSyncCmd** is received

In the diagnosis register **WdDiag** the bit **FWDREA** signalizes an error of the received response bytes to the actual question and the bit **FWDREL** signalizes an error of the response bytes of the last answer. With a read out the diagnosis bits are not cleared.

To detect that the functional check is missing a heartbeat is implemented. With an heartbeat event the functional watchdog pass counter is incremented. An heartbeat event occurs:

- with expiring of the heartbeat period timer or
- with receiving the watchdog heartbeat period synchronisation command **WDHBTPSyncCmd** (response counter is also reset) or
- with receiving the functional watchdog response and synchronisation command **FWDRespSyncCmd** if response byte 0 is received

The heartbeat period can be set by a write access to the configuration register **WDConfig0** or by the watchdog heartbeat period synchronisation command **WDHBTPSyncCmd**. If the data is 000 0000<sub>b</sub> the value of the

## Monitoring Watchdog Module (Signature Watchdog)

heartbeat period is not changed.

Behavior of the heartbeat period in case of changing the period time:

- **WDHBTPSyncCmd**: the response counter and the heartbeat timer are reset and a heartbeat event is triggered, the new value of the period is executed with next period.
- write access to the configuration register **WDConfig0**: the new value of the period is effective after the write command. If the new value is lower than the actual heartbeat timer value then the heartbeat event is immediately triggered otherwise the actual period length is immediately changed to the new value.

The functional watchdog pass counter is a six bit counter (see status register **FWDStat0**). The values for incrementation or decrementation can be set in the configuration register **FWDConfig**. The influence of the counter values to the operation behavior is shown in **Table 11** and **Table 12**.

In **Figure 9** the state machine of the functional watchdog is shown. There are two possible principles available to serve the function watchdog:

- unsynchronized heartbeat and use of functional watchdog response command **FWDRespCmd** and write access to the configuration register **WDConfig0** to change the heartbeat period time or
- heartbeat is started with receiving the functional watchdog response and synchronisation command **FWDRespSyncCmd** and use of the watchdog heartbeat period synchronisation command **WDHBTPSyncCmd** for changing the heartbeat period

The commands can be used in all possible combinations without restrictions. Using **FWDRespCmd** has the advantage that with fast correct responses the decrement of the functional watchdog pass counter can be speed up.

The bit **FWDKQ** in the configuration register **WDConfig1** is used to enable the keep question function for the functional watchdog. If the bit is set in case of a passed functional check the next functional check procedure is done with the same question if minimum one of the bits **WWDSCE** or **WWDTO** is set (window watchdog error).

Monitoring Watchdog Module (Signature Watchdog)

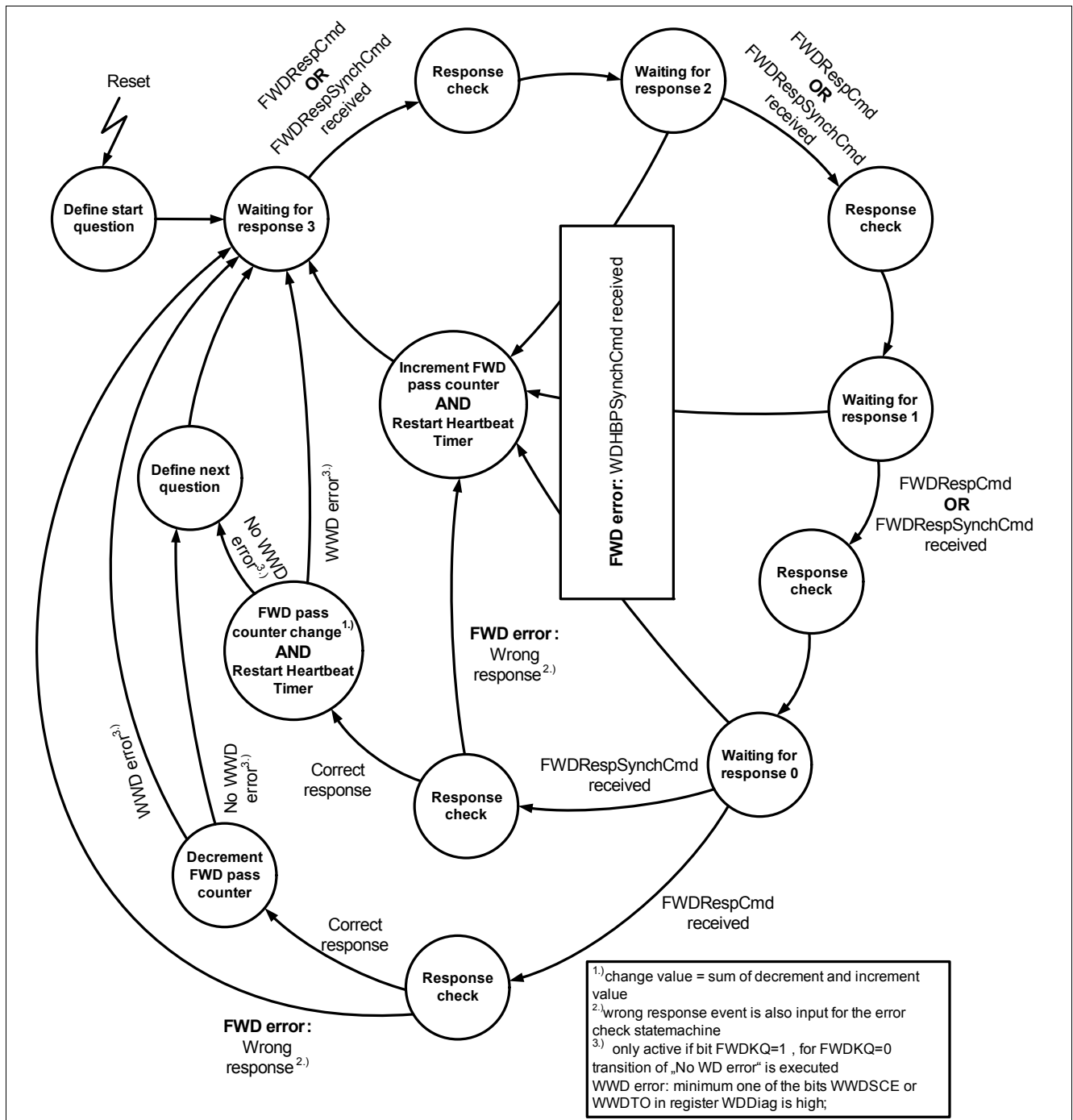


Figure 9 Functional Watchdog State diagram

6.2.1 Question and Response Definition

The bits **FWDQUEST** in the watchdog status register **FWDStat1** represent the actual valid question. The reset value is 0000<sub>b</sub> and it will be changed regarding the definition of the state machine for the monitoring module (see **Figure 7**). The expected response is shown in **Table 10**. The answer of the microcontroller is done by a write access to the command registers **FWDRespCmd** or **FWDRespSynchCmd**. The actual value of the bits **FWDRESPC** in the watchdog status register **FWDStat1** defines the interpretation of the 8 bit content of these commands as RESP3 to RESP0 (definition see **FWDRESPC**).

**Monitoring Watchdog Module (Signature Watchdog)**

The definition of the next question is done with a pseudo random algorithm. With the bit **FWDQG** in the configuration register **WDConfig1** the generation algorithm for the questions is defined. There are two settings:

- question pattern length 16: 16 question repeated every 16th watchdog sequence with a minimum hamming distance of 3
- question pattern length 256: every 256 question the order of the 16 questions is repeated, minimum hamming distance is 1

**Table 10 Questions and related Response**

<b>QUEST[3:0]</b>	<b>RESP3</b>	<b>RESP2</b>	<b>RESP1</b>	<b>RESP0</b>
0	FF	0F	F0	00
1	B0	40	BF	4F
2	E9	19	E6	16
3	A6	56	A9	59
4	75	85	7A	8A
5	3A	CA	35	C5
6	63	93	6C	9C
7	2C	DC	23	D3
8	D2	22	DD	2D
9	9D	6D	92	62
A	C4	34	CB	3B
B	8B	7B	84	74
C	58	A8	57	A7
D	17	E7	18	E8
E	4E	BE	41	B1
F	01	F1	0E	FE

**6.3 Total Error Counter Module**

The total error module is used to count the errors of the window watchdog and the functional watchdog. In **Figure 10** the error check state machine is shown. If a watchdog error of the functional or the window watchdog occurs the state machine enters the state “error occurred” and with the next heartbeat event (definition see **Chapter 6.2**) the total error counter is incremented.

The counter is also incremented if a functional watchdog error or at the same time a window watchdog error occurs by using the **FWDRespSyncCmd**. With the **WDHBTPSyncCmd** always an increment of the total error counter is done. A decrement of the total error counter is only possible by using the **FWDRespSyncCmd** and no errors are occurred.

The decrement and increment value of the total error counter can be set with the configuration register **TECConfig**. The status of the total error counter is available in the status register **TECStat**.

Monitoring Watchdog Module (Signature Watchdog)

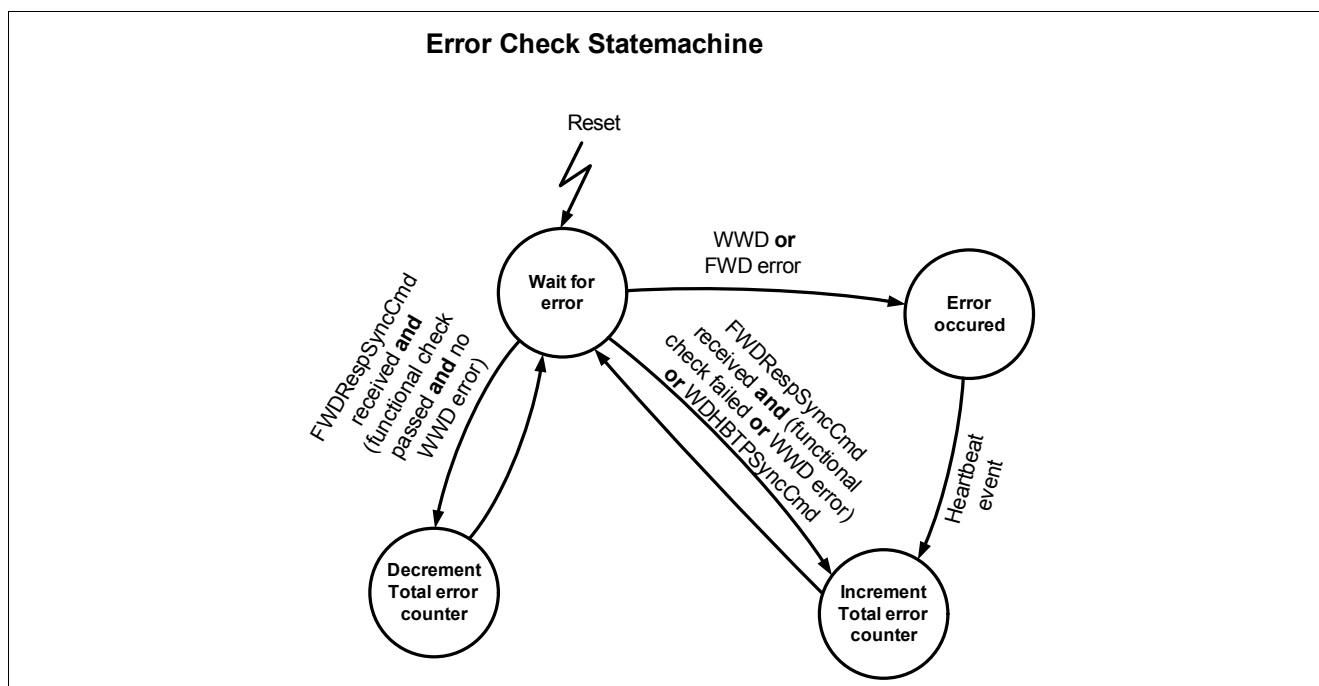


Figure 10 State diagram of the Error check State machine for the Total Error Counter Module

### 6.4 Watchdog Reset Counter

The watchdog reset counter is a three bit counter (bits **RESC** in **WdStat0**) and is triggered by an overflow of one of the three counters of the monitoring functions (see **Figure 11**). The reset counter can only be incremented by 1. Each time the watchdog reset counter changes the value a watchdog reset occurs depending on the status of watchdog reset enable bit **WDREN** in the configuration register **WDConfig1**. The counter stops counting if **WDREN** = “0” or at full scale. There are no further resets if full scale is reached. The behavior at the different reset conditions is defined in **Chapter 5.2 Table 5** and **Table 6**.

### 6.5 Power-Down Counter

There are three power-down counters with three bits implemented. The window watchdog power-down counter (bits **WWDPC** in status register **WdStat0**) is triggered by an overflow of the window watchdog error counter, the functional watchdog power-down counter (bits **FWDPC** in status register **WdStat1**) is triggered by an overflow of the functional watchdog pass counter and the total error power-down counter (bits **TEPC** in status register **WdStat1**) is triggered by an overflow of the total error counter (see **Figure 11**).

If a trigger occurs the dedicated power-down counter is incremented by 1. Additionally all three power-down counters are incremented by 1 if a software reset occurs. The power-down counters are reset if the ready state is reached (see **Table 11** and **Table 12**).

With an overflow of minimum one of the three power-down counters a power-down of the TLE8888-1QK is performed if **KEY** is “low” (see **Chapter 5.1**). This function can not be disabled. The behavior at the different reset conditions is defined in **Chapter 5.2 Table 5** and **Table 6**.

### 6.6 Secure Shut Off Timer

The secure shut off timer (SSOT) is reset with **KEY** = 1 and the timer starts with an overflow of one of the three counters of the monitoring functions (see **Figure 11**) if it is enabled with **KEY** = 0. If the timer is expired after the **Secure shut off time** a power-down of the TLE8888-1QK is performed (see **Chapter 5.1**). The behavior at the different reset conditions is defined in **Chapter 5.2 Table 5** and **Table 6**.

**Monitoring Watchdog Module (Signature Watchdog)**

**6.7 Operation State Definition and Reset Generation**

The values of the three counter of the monitoring module are affecting the operation state of the TLE8888-1QK. There are three states defined:

- the safe state: this is the reset state. The bits **O1E** to **O24E** and **IGN1E** to **IGN4E** in the configuration register **OEConfig0** to **OEConfig3** are set to “0” to ensure that all actuators are switched off.
- ready state: the device can be operated without restrictions.
- watchdog reset: a reset is performed according the definition in **Table 5** and **Table 6**.

The definition of the three states is shown in **Table 11**. The states are affecting the status of the pins *MON* and *RST*, the power-down counter, the secure shut off timer and the reset counter (definition see **Table 12**).

**Table 11 Definition of Reset, Safe and Ready State**

Safe State	WWDEC > 32 <sub>D</sub> <b>OR</b> FWDPC > 32 <sub>D</sub> <b>OR</b> TEC > 32 <sub>D</sub>
Ready State	WWDEC < 33 <sub>D</sub> <b>AND</b> FWDPC < 33 <sub>D</sub> <b>AND</b> TEC < 33 <sub>D</sub>
Watchdog Reset	WWDEC overflow <b>OR</b> FWDPC overflow <b>OR</b> TEC overflow (for all counters > 63 <sub>D</sub> )

**Table 12 System Reaction to the watchdog status**

	Ready State	Safe State	Watchdog Reset
<i>RST</i>	1	1	0 <sup>1)</sup>
<i>MON</i>	1	0	0
Power stages	no influence of normal operation	disabled	disabled
<b>O1E</b> to <b>O24E</b> , <b>IGN1E</b> to <b>IGN4E</b>	X	0	0
WWD error counter FWD pass counter Total error counter	no effect	no effect	reset <sup>1)</sup>
Reset counter	no effect	no effect	increment by 1
Window watchdog power-down counter Total error power-down counter Functional watchdog power-down	reset	no effect	increment by 1 regarding the overflow source
Secure shut off timer	no effect	no effect	start of timer with the first overflow if <i>KEY</i> = 0

1) occurs for the defined reset time if watchdog reset is enabled



Monitoring Watchdog Module (Signature Watchdog)

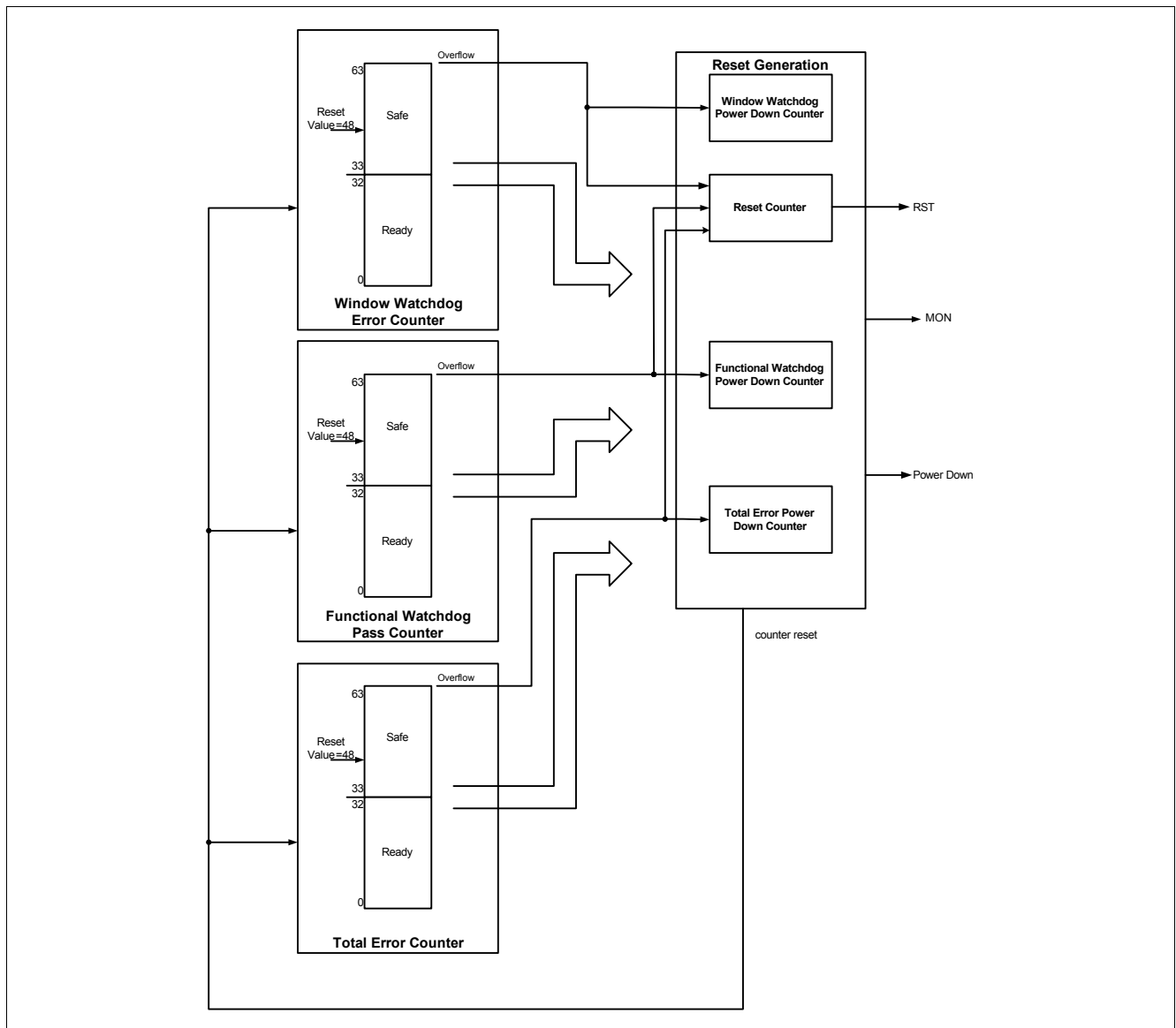


Figure 11 Block diagram of the Reset Generation

**Behavior of the WWD error counter, the FWD pass counters and the total error counter in case of over and underflow:**

The counters are designed to keep the same value:

- at incrementation if the new counter value is higher than the full scale value of the counter and
- at decrementation if the new counter value is lower than zero.

In [Figure 12](#) an example is shown.

Monitoring Watchdog Module (Signature Watchdog)

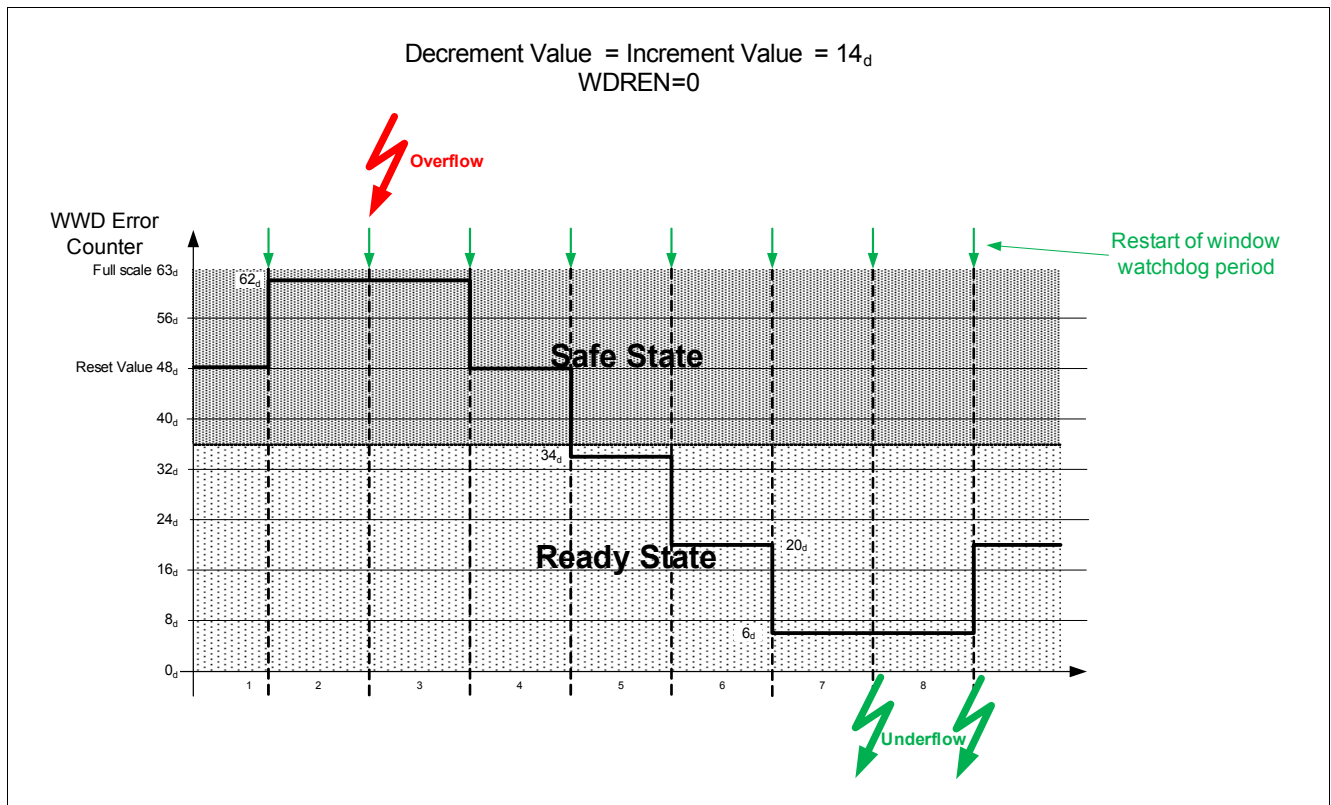


Figure 12 Example of WWD error counter behavior with decrement and increment value of 14d

### 6.8 Synchronisation of Window Watchdog Sequence and Heartbeat

In **Figure 13** the relation between the heartbeat clock generation, the total error counter and the window watchdog sequence generation is shown. The window watchdog sequence generation and the heartbeat period generation have the same clock base with the accuracy of  $tw,a$ .

The value of the pre-divider and the heartbeat timer can be read out with the status registers **WDHBT0** and **WDHBT1**. This can be used to measure the actual internal clock frequency. Therefore the value of the pre-divider and the heartbeat period counter must be sampled by sending a **Cmd0** command with an activated **WDHBTS** bit. With this command the value of the two registers are stored in the related status registers and the readout can be done.

With two sampled values the microcontroller can correct the time information by the value of the actual frequency of the TLE8888-1QK. With such a correction of the microcontroller timing check it is possible to use smaller open window times to improve the performance of the timing check. Additional it is possible to use this information for synchronization purpose for the check of the monitoring function of the TLE8888-1QK inside the microcontroller.

Monitoring Watchdog Module (Signature Watchdog)

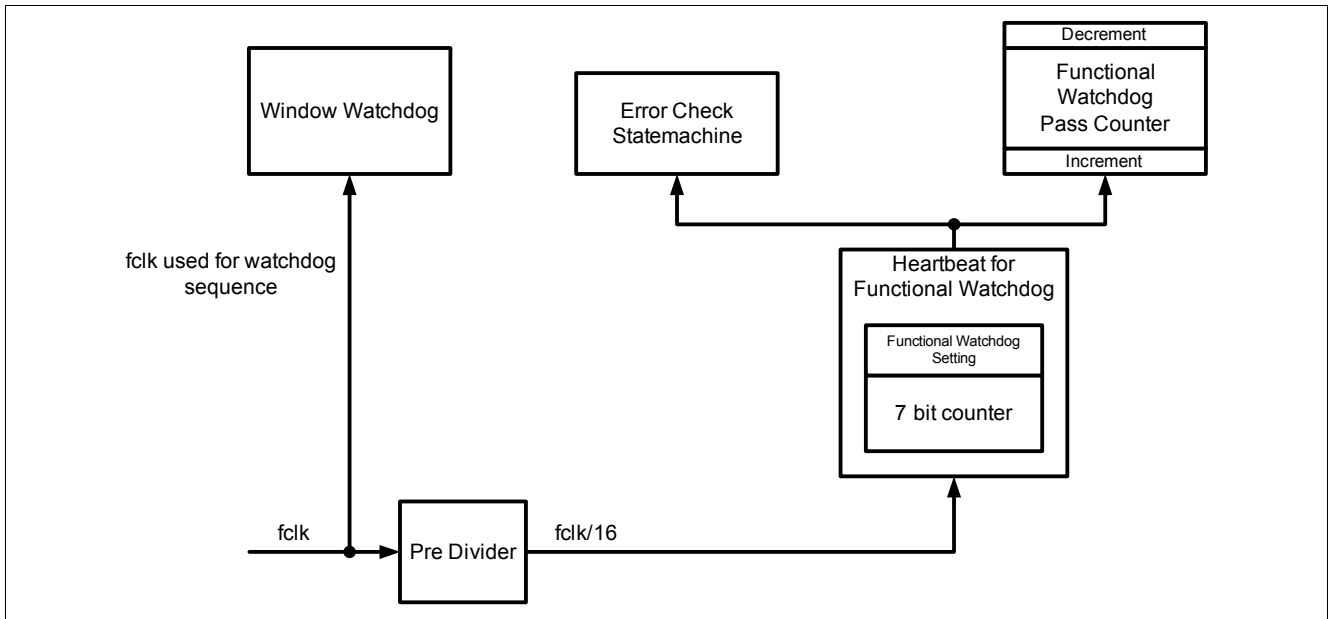


Figure 13 Clock Generation for the Watchdog Module

**Monitoring Watchdog Module (Signature Watchdog)**

**6.9 Electrical Characteristics Monitoring Watchdog Module**

**Table 13 Electrical Characteristics: Monitoring Watchdog Module**

$V_S = 13.5\text{ V}$ ,  $V_{VSV} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to ground, positive current flowing into pin (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
Window watchdog closed window time	$t_{\text{WWD,ct}}$	1.6	–	100.8	ms	63 values	P_6.8.1
Window watchdog closed window time step	$t_{\text{WWD,ct}}$	–	1.6	–	ms	–	P_6.8.2
Window watchdog open window time 1	$t_{\text{WWD,ot1}}$	–	3.2	–	ms		P_6.9.1
Window watchdog open window time 2	$t_{\text{WWD,ot2}}$	–	6.4	–	ms		P_6.9.2
Window watchdog open window time 3	$t_{\text{WWD,ot3}}$	–	9.6	–	ms		P_6.9.3
Window watchdog open window time 4	$t_{\text{WWD,ot4}}$	–	12.8	–	ms	–	P_6.8.3
Clock frequency accuracy for window watchdog sequence and heartbeat	$t_{\text{w,a}}$	-5	–	+5	%	–	P_6.8.4
Heartbeat time period	$t_{\text{HBT,pt}}$	1.6	–	203.2	ms	127 values	P_6.9.4
Secure shut off time	$t_{\text{SSOT}}$	18	20	22	min	–	P_6.8.5



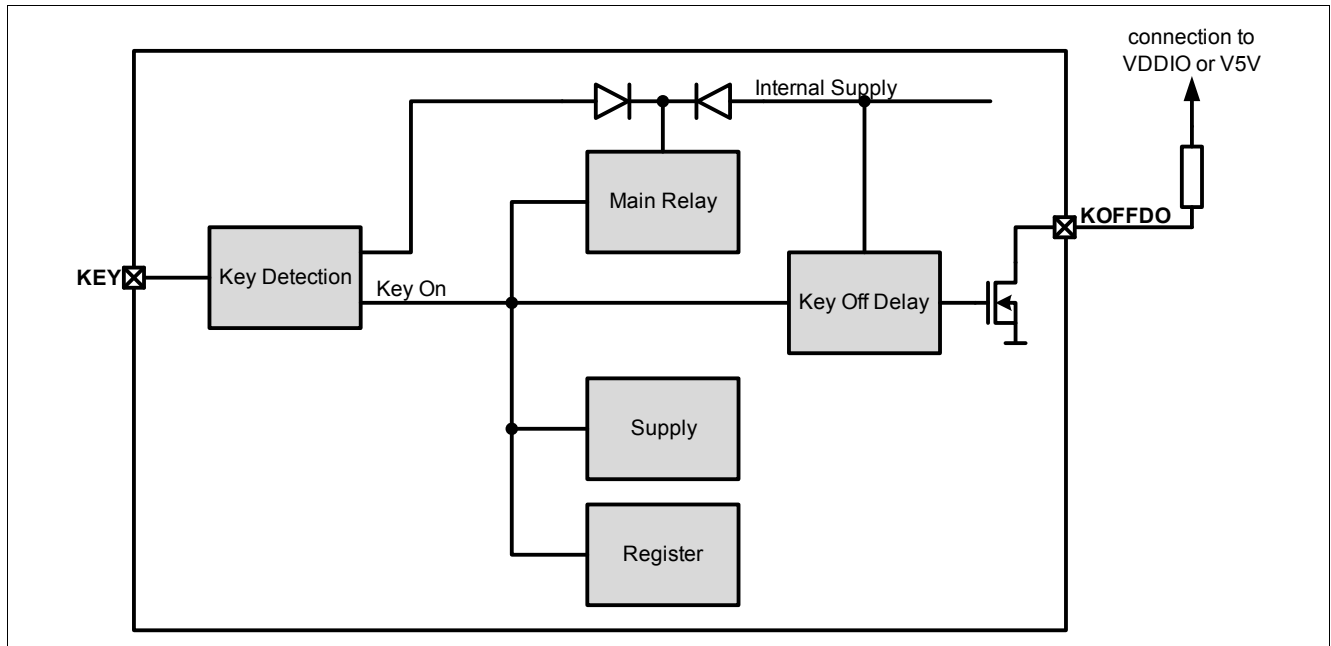
**Wake-Up Detection and Main Relay Driver**

**Table 14 Switching Behavior of Main Relay at Start Up (Transition ECU Sleep to Supply Ramp Up Mode)**

$KEY=0, WK = EOTWK = CANWK=0$	-	$MR$ is switched off	Supply is off
$KEY=1, WK = EOTWK = CANWK= X$	-	$MR$ is switched on	Supply is switched on
$KEY=0, WK$ or $EOTWK$ or $CANWK=1$	$BAT < V_{BAT,th}$	$MR$ is switched on	
$KEY=0, WK$ or $EOTWK$ or $CANWK=1$	$BAT > V_{BAT,th}$	$MR$ is switched off	

**7.1 Wake-up Detection by Pin KEY and Key Off Delay**

The input pin *KEY* is implemented to detect the status of the key switch in the car. With a high signal the start up of the TLE8888-1QK is initiated. During start up the implemented circuitry provides also the supply for switching the main relay. A deglitch filter is implemented to be robust against disturbances (see [Figure 16](#)). After ramp up the supply of the main relay is provided by the internal supply. To provide a direct access from the *KEY* signal to actuators a key off delay function is implemented.



**Figure 15 Block Diagram of the Key Detection**

In [Figure 16](#) the effect of the filter time is shown. The status of the pin *KEY* including the filter time is reflected in bit **KEY** in the status register **OpStat0**.

Wake-Up Detection and Main Relay Driver

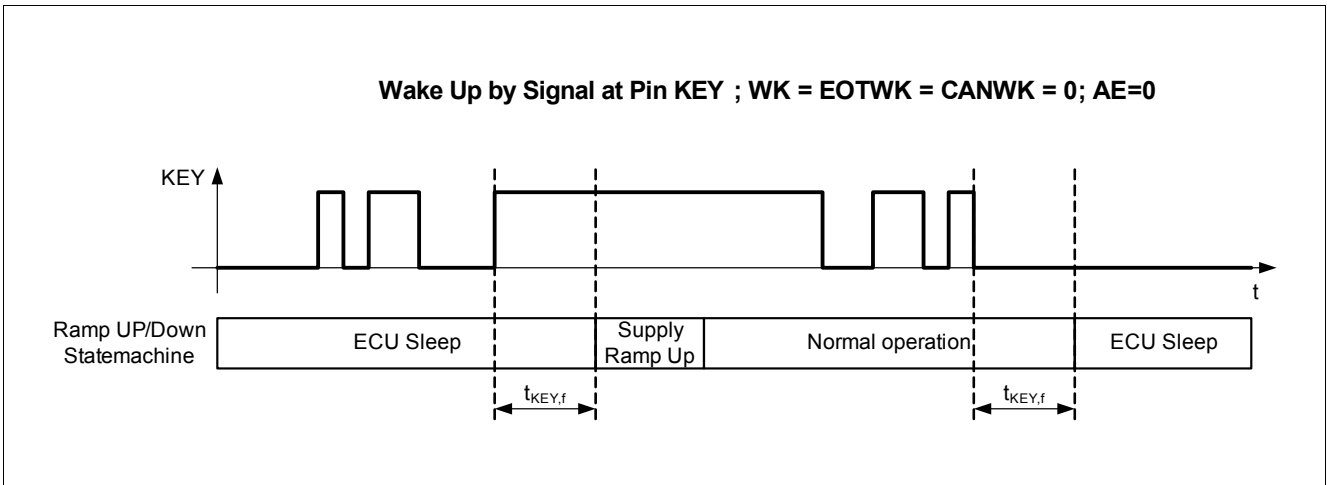


Figure 16 Function of Key detection filter time

The key off delay function provides the *KEY* signal at the open drain output *KOFFDO*. The positive edge is delayed by the **Key Detection Filter Time** and the negative edge by the **Key Off Delay Time 1 to Key Off Delay Time 4** (according to setup of the bits *KOD* in register *OpConfig0*) if the supply is available.

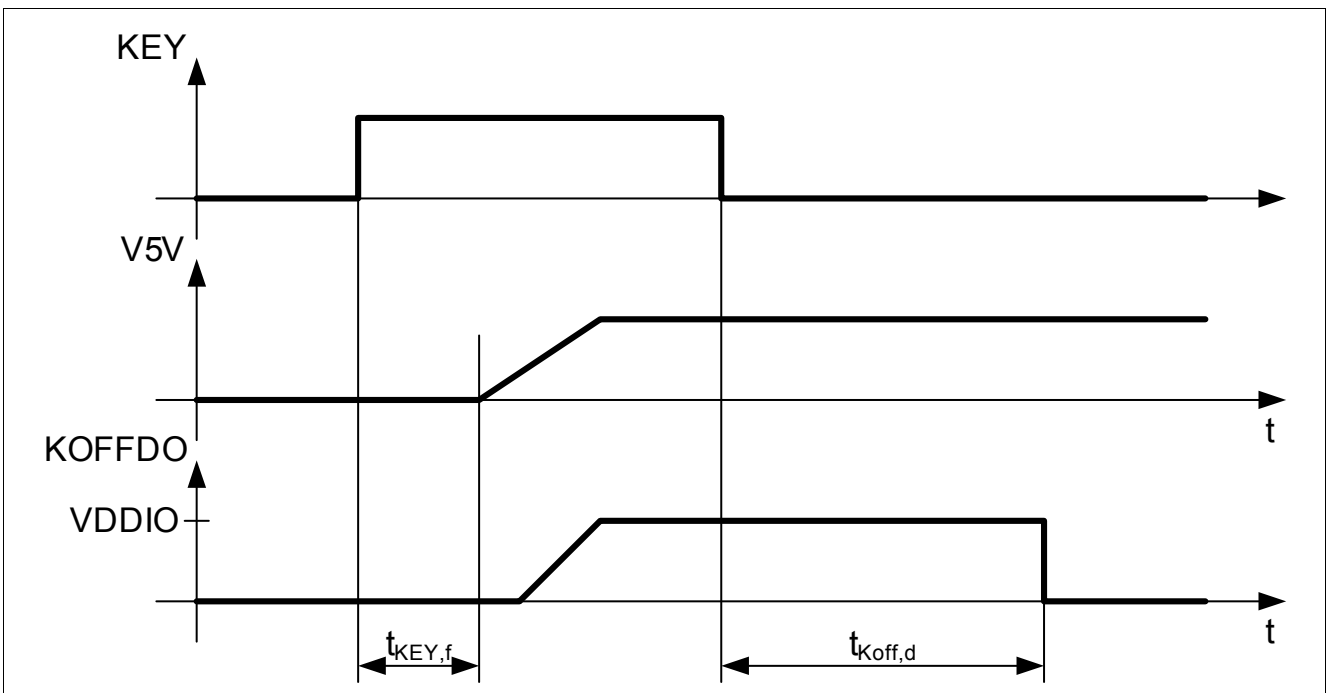


Figure 17 Timing Diagram of the Key Off Delay

### 7.2 Wake-up Detection by Pin *WK*

The pin *WK* is used e.g. for an external CAN device with wake-up function on the ECU. With a high signal the start up of the TLE8888-1QK is initiated. During ramp up the supply for the main relay circuit is provided by the active wake-up pin *WK*. After ramp up the supply of the main relay circuit is provided by the internal supply. In **Figure 18** the block diagram of the wake-up detection by pin *WK* is shown.

Wake-Up Detection and Main Relay Driver

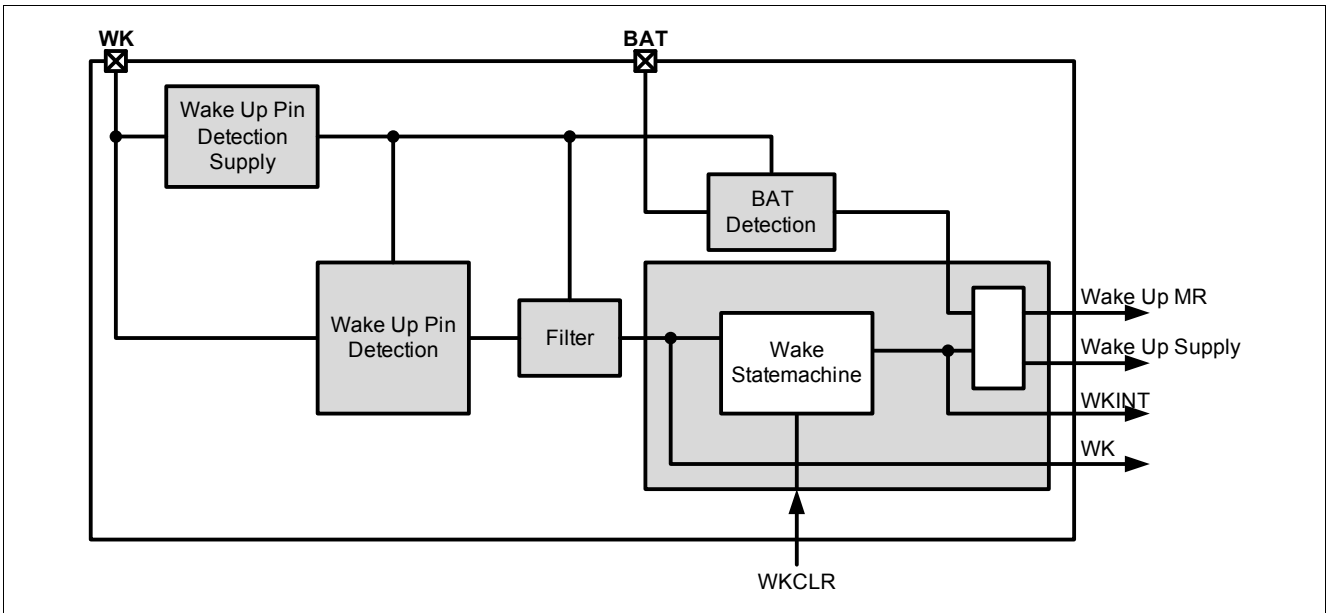


Figure 18 Block Diagram of the Wake-up Detection

For wake-up by pin *WK* special functions are implemented.

- main relay is switched on depending on the voltage level at pin *BAT* (see [Table 14](#))
- power-down procedure in case of a permanent *WK* = “1” and a blocked micro-controller (see description in [Chapter 5.1 Operation States](#))
- wake clear bit *WKCLR* in the command register *Cmd0* to clear the internal wake-up signal in case of permanent *WK* = “1” signal
- deglitch filter of  $t_{WK,f}$  for positive and negative edge at pin *WK*

In [Figure 19](#) the effect of the filter time is shown. The status of the pin *WK* including the filter time is reflected in bit *WK* in the status register *OpStat0*.

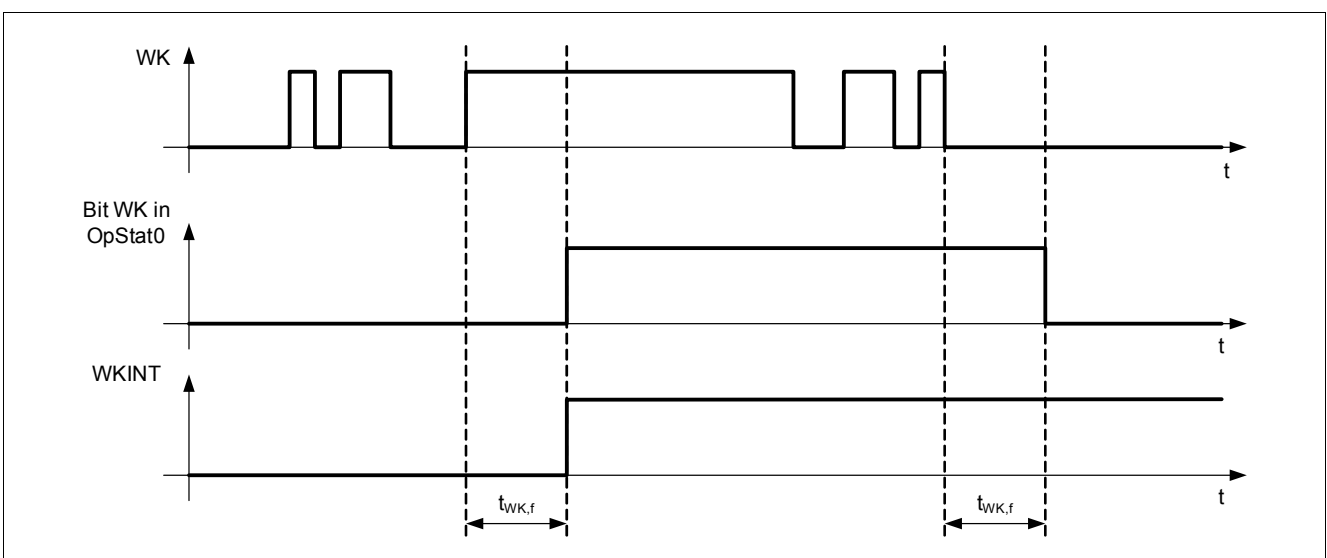


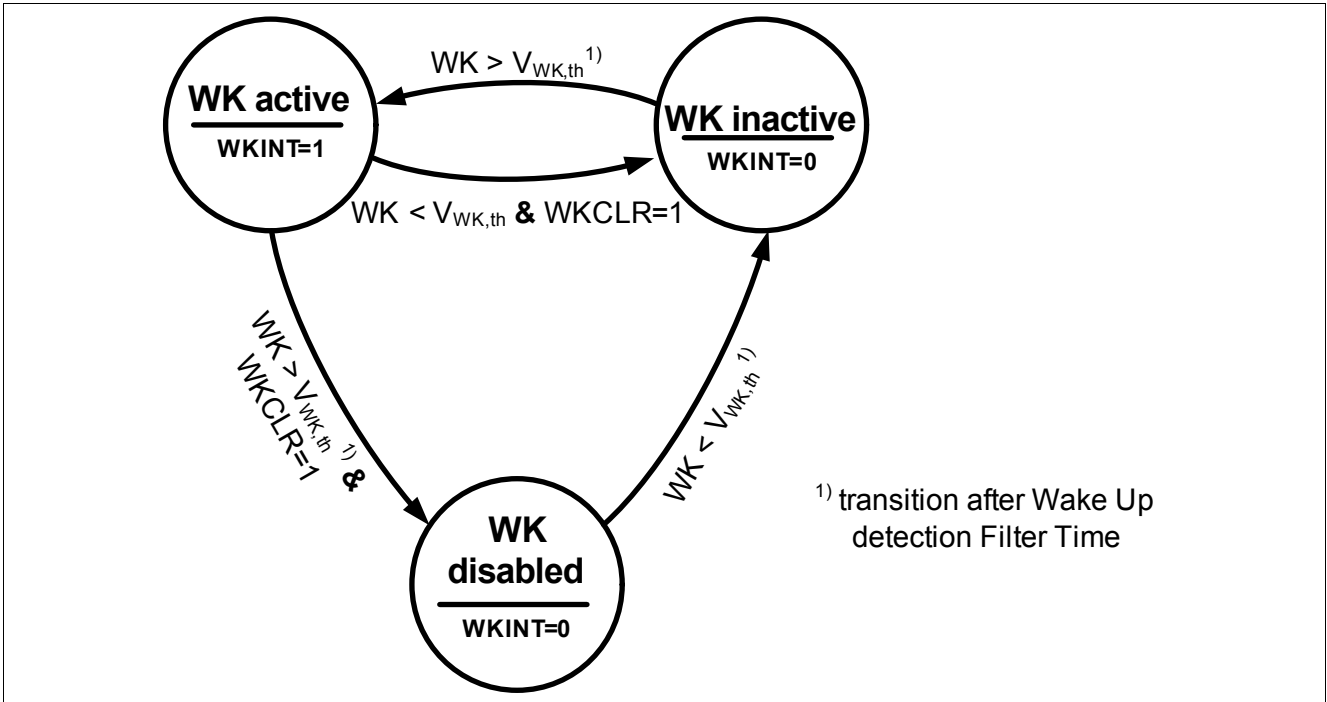
Figure 19 Function of WK detection filter time

To realize the power-down procedure an internal wake-up signal *WKINT* is used (status see bit *WKINT* in the status register *OpStat0*). In [Figure 20](#) the state diagram of the internal wake signal generation is shown. With



**Wake-Up Detection and Main Relay Driver**

a positive edge at pin *WK* the internal signal *WKINT* is set to “1” and a wake-up is triggered. With a wake-up clear command (set bit **WKCLR** to “1” in command register **Cmd0**) *WKINT* is reset (see **Figure 22**). The next wake-up by pin *WK* is only detected with a positive edge at pin *WK*. A permanent high level at pin *WK* doesn’t lead to permanent wake-up situation. Details of the operation behavior see **Chapter 5.1 Operation States**.



**Figure 20 State Diagram of the Wake State Machine for Internal Wake Signal**

At the beginning of the functional diagram of **Figure 21** a normal wake-up sequence with a wake signal of the pin *WK* is shown. In the second part of the diagram the signal of pin *WK* stick at high (e.g. short to battery) and the microcontroller must send a wake clear command (bit **WKCLR** = 1 in command register **Cmd0**) for entering the ECU sleep mode. With a low at pin *WK* the wake state machine is set to the state “WK inactive” and a wake-up by pin *WK* is enabled.

Wake-Up Detection and Main Relay Driver

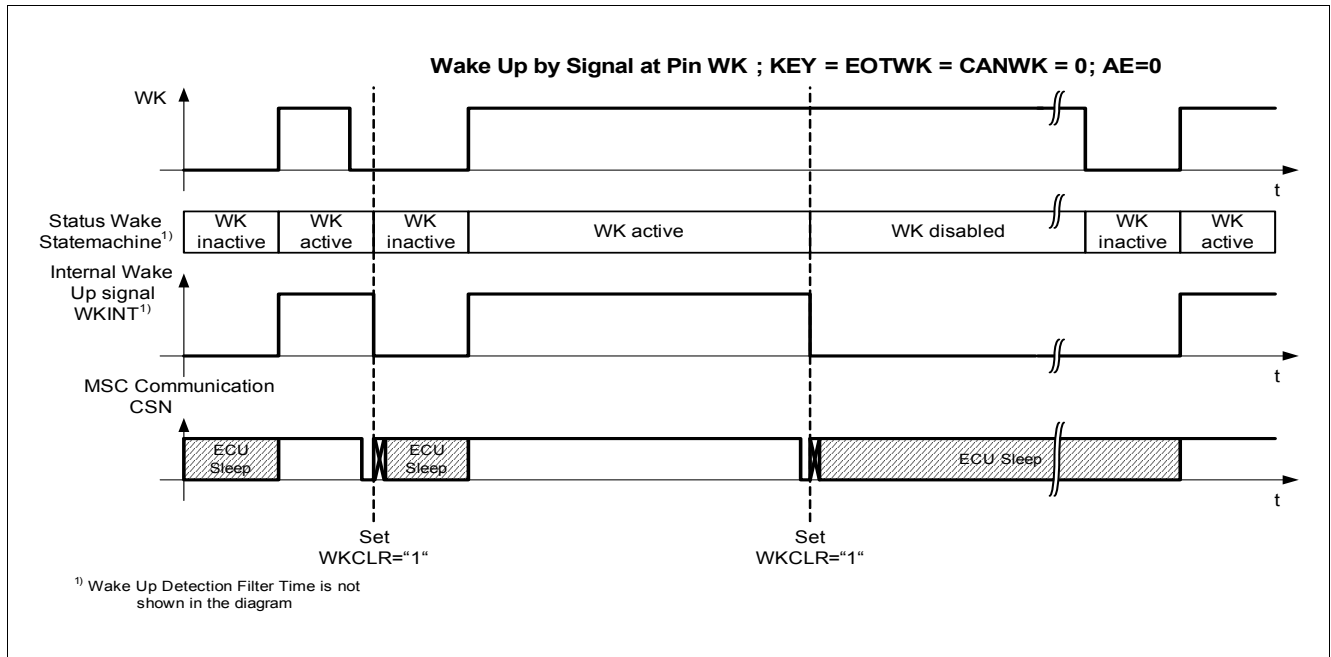


Figure 21 Functional Diagram for Internal Wake Signal

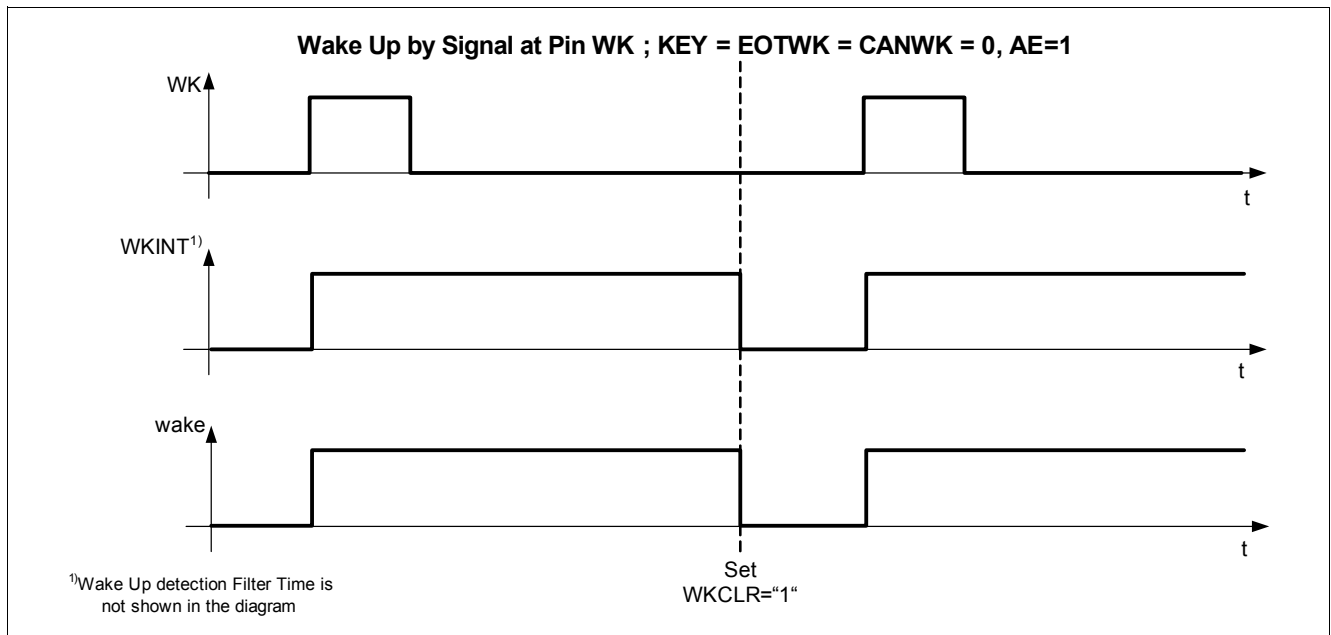


Figure 22 Functional Diagram of Detection of Two Internal Wake Signals

### 7.3 Main Relay Driver

The main relay driver is designed to switch on the main relay of engine management applications. It integrates a reverse protected low-side switch with active clamping freewheeling. The output is protected against overload with an overtemperature detection and an overcurrent protection circuit. At low battery voltage ( $V_{5V}$  main supply is below undervoltage detection threshold e.g. during cranking) the main relay stays on. The on resistance is related to the supply voltage at pin *BAT* and is defined down to 4.5 V. The main relay is automatically switched on with a wake-up signal according to [Table 14](#). The main relay is normally switched off automatically according the power-down procedure defined in [Chapter 5](#). With write access to the command bit **MRON** of the command register **Cmd0** the main relay can be switched

**Wake-Up Detection and Main Relay Driver**

additionally by MSC/SPI control according to the status of *KEY*, *WK*, *EOTWK* and *CANWK* (see [Table 15](#)). The status of the main relay is available in the status register **OpStato** bit **MR**.

**Table 15 Effect of MSC/SPI Write Command Bit MRON**

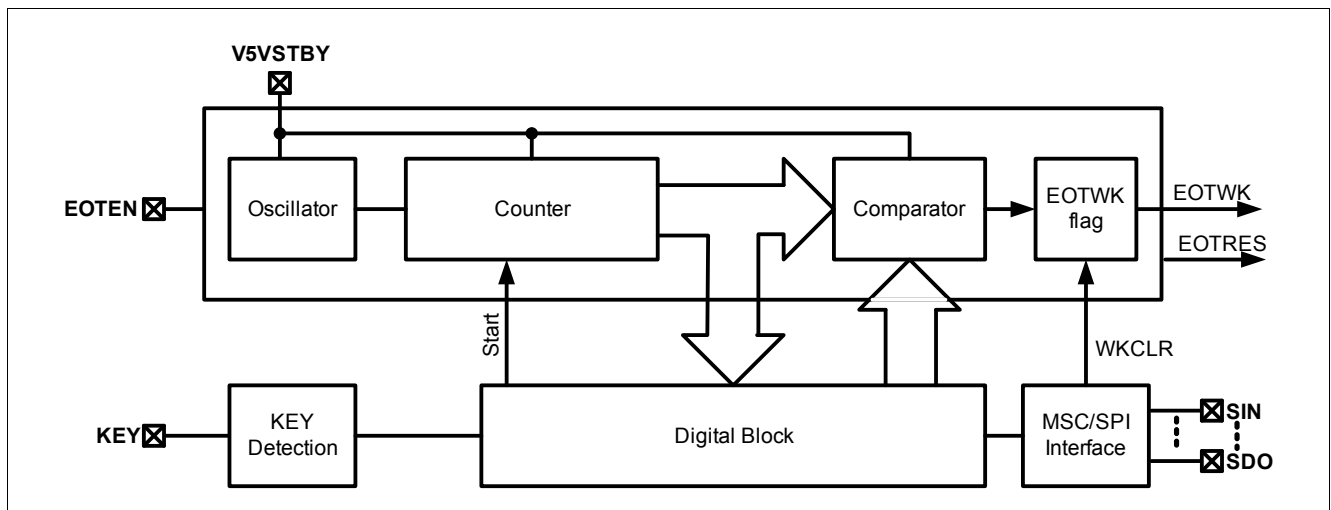
<i>KEY</i> = 0, <i>WK</i> = <i>EOTWK</i> = <i>CANWK</i> = X	<i>MR</i> is switched according to write command
<i>KEY</i> = 1, <i>WK</i> = <i>EOTWK</i> = <i>CANWK</i> = X	<i>MR</i> is always switched on

The main relay driver is protected against overcurrent and overtemperature. In the case of overcurrent and/or overtemperature the output is switched off and is switched on again after release of the failure condition. This leads to a repetitive switching. A minimum off time **tMR,off** is implemented to ensure no destruction due to repetitive switching.

**7.4 Engine Off Timer**

The engine off timer is integrated to measure the time in ECU sleep mode. Additionally the comparator mode is implemented to wake-up the TLE8888-1QK after a defined time. It is internally supplied out of the standby supply pin *V5VSTBY*. With the pin *EOTEN* the function is enabled with a connection to *V5VSTBY* and disabled with a connection to *AGND*. It consists of an oscillator optimized for low current operation, a counter and a comparator. The counter counts up to 36 hours and if the counter value reaches the comparator threshold an internal wake-up signal is generated. The activation of the comparator mode is done with a definition of a comparator threshold greater than 0000H in configuration registers **EOTConfig0** and **EOTConfig1**. There are two operation modes implemented:

- Counter Mode: only counter is working, no wake-up with comparator threshold
  - Comparator Mode: counter operation like counter mode, additional wake-up with comparator threshold
- In comparator mode the internal *EOTWK* flag is set if the counter is equal to compare value in the configuration registers **EOTConfig0** and **EOTConfig1**. The reset of the *EOTWK* flag is done with the bit **WKCLR** in the command register **Cmd0** if the counter value is not equal to the compare value.



**Figure 23 Block Diagram Engine Off Timer**

The start of the counter can be configured with the bit **EOTCONF** in the configuration register **OpConfig0** to

- start by *KEY* signal (reset value) and
- start by MSC command

**Wake-Up Detection and Main Relay Driver**

With the falling edge of the *KEY* signal or with the execution of the MSC command the counter is reset and starts counting (see [Figure 24](#)). The start command is performed with setting the bit **EOTS** to “1” in the command register **Cmd0**.

The status bit **EOTRES** (register **OpStat1**) is implemented to highlight that a standby reset has happened. With the start of the counter this bit is reset. Therefore the status of this bit must be readout before the start of the engine off timer.

The 24 bits of the counter are available in the status register **EOTStat0**, **EOTStat1** and **EOTStat2**. For easier access to the engine off timer status the multiple read command **MSCReadDiag0EOT** is implemented.

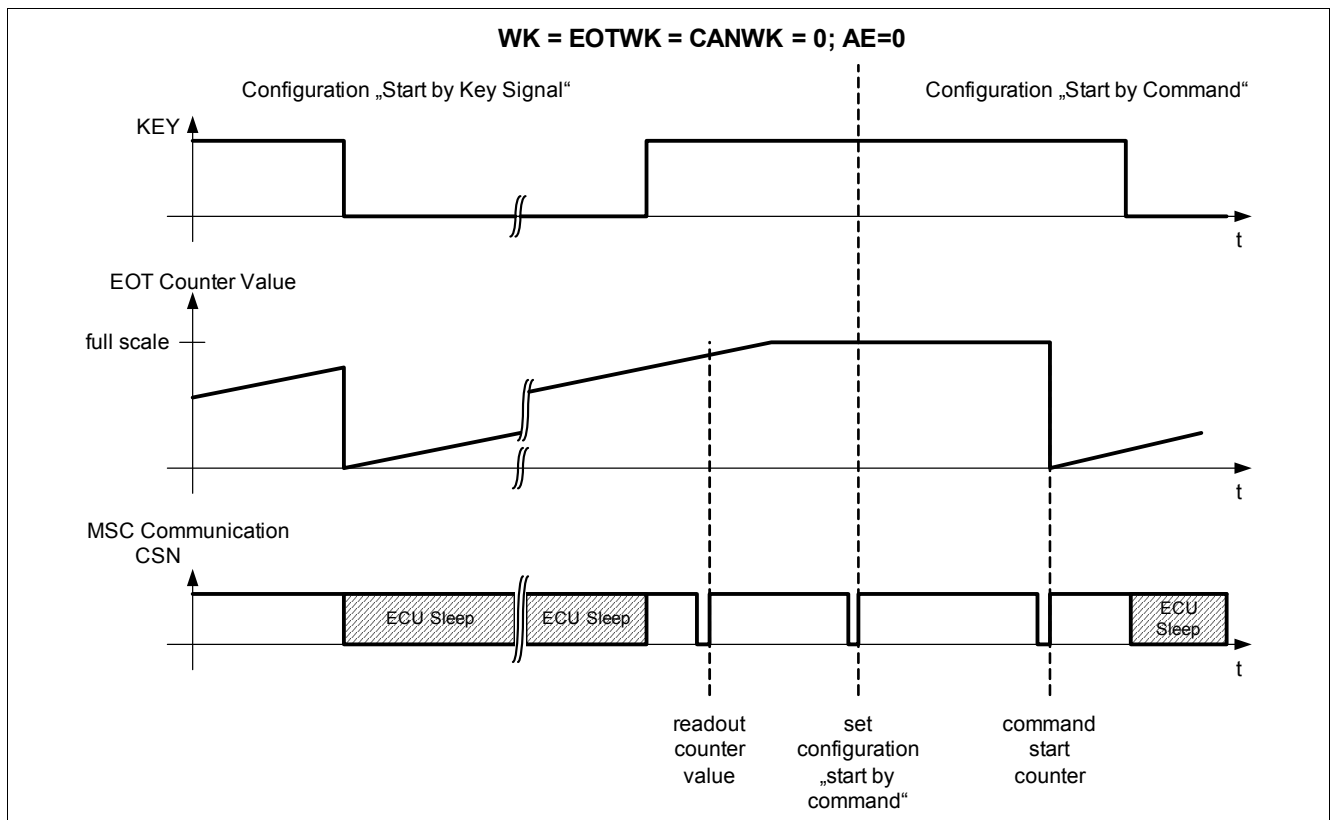
After wake-up the counter doesn't stop counting. A readout of the counter value doesn't stop counting. With this behavior it is possible to measure the counting time with the microcontroller (see [Figure 25](#)).

With a read out of two counter values in a defined time a correction factor can be calculated (difference of counter values divided by the time between the two read outs). With this measurement of the correction factor only the variation caused by the temperature of the timer are effective. The absolute variations are corrected by the correction factor. There are no restrictions for the measurement time but due to the resolution of the counter a minimum measurement time  $\Delta t$  of 1 s is recommended.

After power-up of the engine off timer circuit with a supply ramp up at pin *V5VSTBY* the counter value and the comparator threshold are reset to the reset value. Additionally the bit **EOTRES** in the status register **OpStat1** is set to “1”.

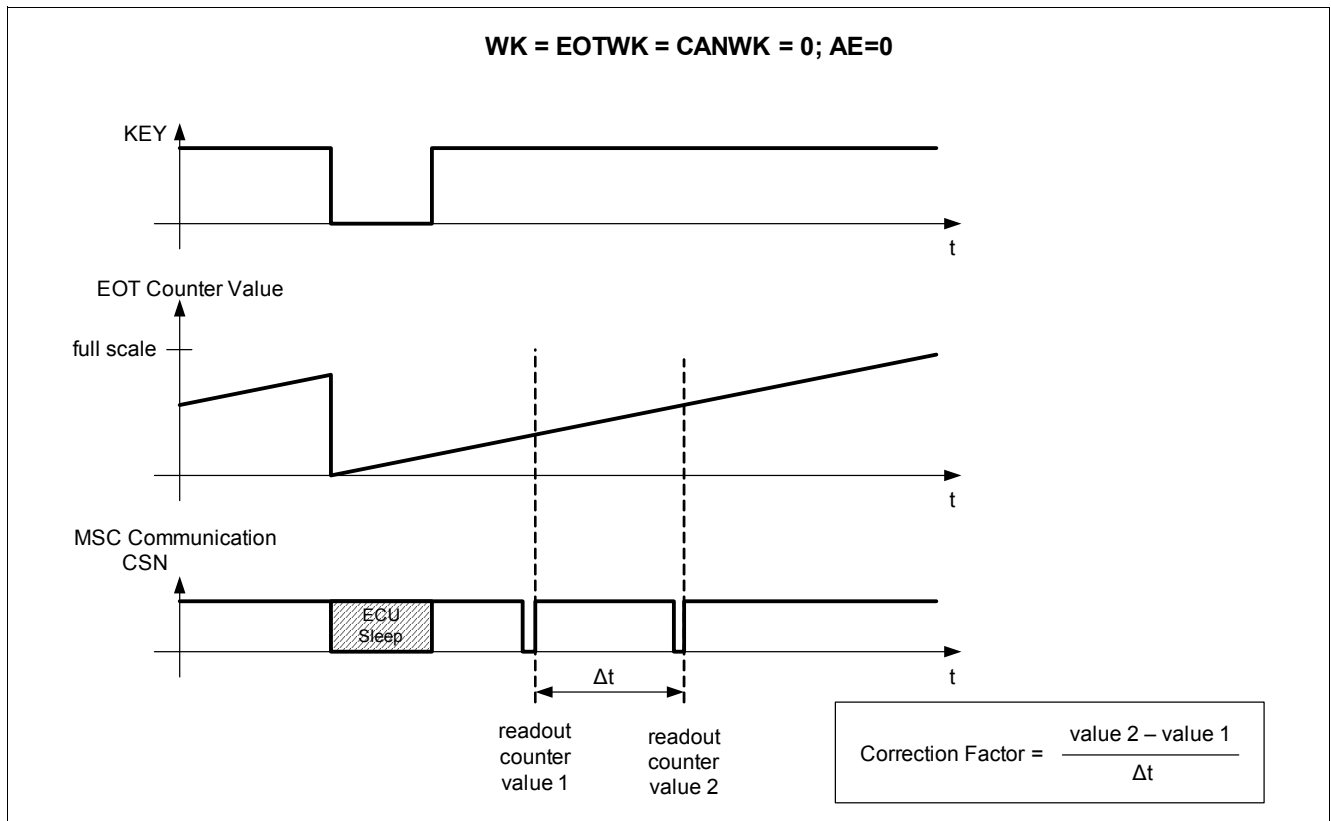
Any other resets like ECU power on reset have no impact to the engine off timer counter. The compare configuration register **EOTConfig0** and **EOTConfig1** are cleared with an ECU power on reset.

The counter stops counting at full scale. If a standby supply reset occurs the counter stops counting and is reset to “0”.



**Figure 24 Function Diagram Engine Off Timer Counter Mode**

**Wake-Up Detection and Main Relay Driver**



**Figure 25 Function Diagram Engine Off Timer Correction Factor Measurement**

In comparator mode there is no difference in the behavior of the counter as described above. Additionally a comparator threshold different to 0000H for wake-up is defined in the configuration register **EOTConfig0** and **EOTConfig1**. The comparator mode is enabled with a threshold value different to 0000<sub>H</sub>. If the counter value is equal to the comparator threshold the internal wake-up signal EOTWK (status see bit **EOTWK** in the status register **OpStato**) of the TLE8888-1QK is active (see **Figure 26**).

With a wake-up clear command (set bit **WKCLR** to “1” in command register **Cmd0**) the internal EOTWK signal is reset.

**Table 16 Counter Definition**

<b>EOTC[23:0]</b>		
000000 <sub>H</sub>	reset value	
000001 <sub>H</sub> to FFFFFFF <sub>H</sub>	1/128 s to 131071 s = 36 h + 24 min + 31 s	time resolution 1/128 s

**Table 17 Comparator Threshold Definition**

<b>EOTTH[15:0]</b>		
0000 <sub>H</sub>	reset value	comparator mode disabled
0001 <sub>H</sub> to FFFF <sub>H</sub>	2 s to 131070 s = 36 h + 24 min + 30 s	comparator mode enabled, time resolution 2 s

Wake-Up Detection and Main Relay Driver

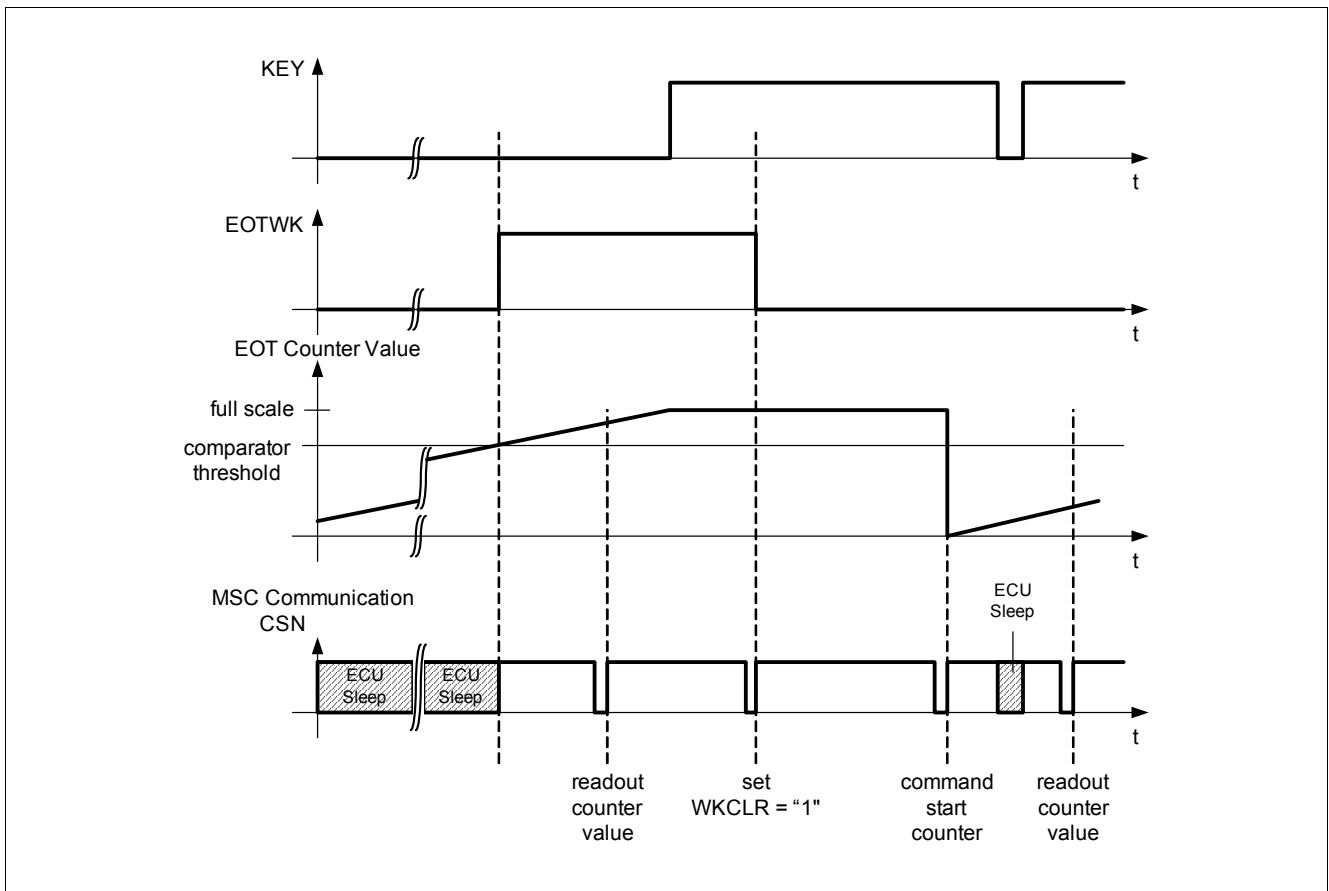


Figure 26 Function Diagram Engine Off Timer Comparator Mode

**Wake-Up Detection and Main Relay Driver**

**7.5 Electrical Characteristics Key Detection, Wake-up Detection and Main Relay Driver**

**Table 18 Electrical Characteristics Key Detection**

$V_S = 13.5\text{ V}$ ,  $V_{VSV} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to GND, positive current flowing into pin, (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
Key On Detection Threshold	$V_{KEY,th}$	3.6	–	4.5	V	rising edge	P_7.5.1
Key On Detection Hysteresis	$V_{KEY,h}$	140	250	400	mV	–	P_7.5.2
Input Current during wake-up	$I_{KEY}$	–	–	0.55	mA	$V_{KEY} = 5\text{ V}^{1)}$	P_7.5.3
Input Current after wake-up	$I_{KEY}$	–	–	0.7	mA	$V_{KEY} = V_{BAT} = 4.5\text{ V}$	P_7.5.31
Key Detection Filter Time	$t_{KEY,f}$	7.5	16	24	ms	$V_{KEY} = 5\text{ V}$	P_7.5.4
Key Off Delay Time 1	$t_{KEYoff,d,1}$	100	–	200	ms	–	P_7.5.5
Key Off Delay Time 2	$t_{KEYoff,d,2}$	200	–	400	ms	–	P_7.5.6
Key Off Delay Time 3	$t_{KEYoff,d,3}$	400	–	800	ms	–	P_7.5.7
Key Off Delay Time 4	$t_{KEYoff,d,4}$	800	–	1600	ms	–	P_7.5.8

**Output KOFFDO**

Output Current Capability	$I_{KOFFDO}$	15 <sup>2)</sup>	–	–	mA	$V_{KOFFDO} = 5\text{ V}$	P_7.5.9
KOFFDO Output Low Level	$V_{KOFFDO,low}$	–	–	0.4	V	$I_{KOFFDO} < 1\text{ mA}$	P_7.5.30

1) not subject to production test, specified for design

2) Application must ensure that current into this pin does not exceed this value.

**Table 19 Electrical Characteristics Wake-up Detection**

$V_S = 13.5\text{ V}$ ,  $V_{VSV} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to GND, positive current flowing into pin, (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
Wake-up Detection Threshold	$V_{WK,th}$	3.6	–	4.5	V	rising edge	P_7.5.10
Wake-up Detection Hysteresis	$V_{WK,h}$	140	250	400	mV	–	P_7.5.11
Input Current during Wake-up	$I_{WK}$	–	–	0.55	mA	$V_{WK} = 5\text{ V}^{1)}$	P_7.5.12
Wake-up Detection Filter Time	$t_{WK,f}$	1	2	3.5	ms	$V_{WK} = 5\text{ V}$	P_7.5.13
Battery Detection Threshold	$V_{Bat,th}$	3.5	–	5	V	$V_{WK} = 5\text{ V}$	P_7.5.14

1) not subject to production test, specified by design

**Wake-Up Detection and Main Relay Driver**

**Table 20 Electrical Characteristics Main Relay Driver**

$V_S = 13.5\text{ V}$ ,  $V_{VSV} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to GND, positive current flowing into pin, (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
MR Operation Current	$I_{MR}$	–	–	0.8	A	–	P_7.5.15
MR Overcurrent Limitation	$I_{MR,OC}$	0.8	–	1.5	A	–	P_7.5.16
MR On Voltage	$V_{MR}$	–	–	1.35	V	$I_{MR} = 0.3\text{ A}$	P_7.5.17
MR switch off time in failure case	$t_{MR,off}$	16	27	–	ms	in case of overcurrent and/or over-temperature	P_7.5.32
MR On Voltage at Low Battery Voltage, low temperature	$V_{MR,L,LT}$	–	–	1.1	V	$I_{MR} = 0.1\text{ A}$ , $V_{BAT} = 4.5\text{ V}$ (decreasing) $T_j < 25^\circ\text{C}$	P_7.5.18
MR On Voltage at Low Battery Voltage, high temperature	$V_{MR,L,HT}$	–	–	1.05	V	$I_{MR} = 0.1\text{ A}$ , $V_{BAT} = 4.5\text{ V}$ (decreasing) $T_j > 25^\circ\text{C}$	P_7.5.19
MR Clamping Voltage	$V_{MR,cl}$	40	–	60	V	$I_{MR} = 0.2\text{ A}$	P_7.5.20
MR Clamping Energy <sup>1)</sup>	$E_{MR,cl}$	–	–	6.5	mJ	$I_{MR} < 0.3\text{ A}$ , $T_j = 150^\circ\text{C}$ , 40*106 cycles	P_7.5.21
MR leakage current in off mode, positive voltage	$I_{MR,leak,pos}$	–	–	5	$\mu\text{A}$	$V_{MR} = 13.5\text{ V}$ , $V_{KEY} = 0\text{ V}$ and $V_{WK} = 0\text{ V}$	P_7.5.22
MR leakage current in off mode, negative voltage	$I_{MR,leak,neg}$	-100	–	–	$\mu\text{A}$	$V_{MR} = -13.5\text{ V}$ , $V_{KEY} = 0\text{ V}$ and $V_{WK} = 0\text{ V}$	P_7.5.23

1) not subject to production test

**Table 21 Electrical Characteristics Engine Off Timer**

$V_S = 13.5\text{ V}$ ,  $V_{VSV} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to GND, positive current flowing into pin, (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
Oscillator Accuracy	$\Delta f_{osc,a}$	-30	–	+30	%	$V_{VSVSTBY} = 5\text{ V}$	P_7.5.24
Oscillator Frequency Variation over Temperature	$\Delta f_{osc,T}$	-5	–	+5	%	$V_{VSVSTBY} = 5\text{ V}$ , $T_j = -40^\circ\text{C}$ to $85^\circ\text{C}$ , one single device	P_7.5.25
Counter Resolution	$C_{EOT,r}$	–	1/128	–	s	–	P_7.5.26



**Wake-Up Detection and Main Relay Driver**

**Table 21 Electrical Characteristics Engine Off Timer (cont'd)**

$V_S = 13.5\text{ V}$ ,  $V_{SV} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to GND, positive current flowing into pin, (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
Counter Full Scale	$C_{EOT,fs}$	-	-	24	bit	-	P_7.5.27
		-	131071	-	s	-	
Additional current consumption at pin <i>BATSTBY</i> for enabled engine off timer function	$I_{EOTSUP}$	-	-	10	$\mu\text{A}$	$V_{V5VSTBY} = 5\text{ V}$ and no wake-up	P_7.5.28
Additional current consumption at pin <i>BATSTBY</i> for enabled engine off timer function and wake-up <sup>1)</sup>	$I_{EOTSUP,w}$	-	-	450	$\mu\text{A}$	$V_{V5VSTBY} = 5\text{ V}$ and wake-up	P_7.5.29

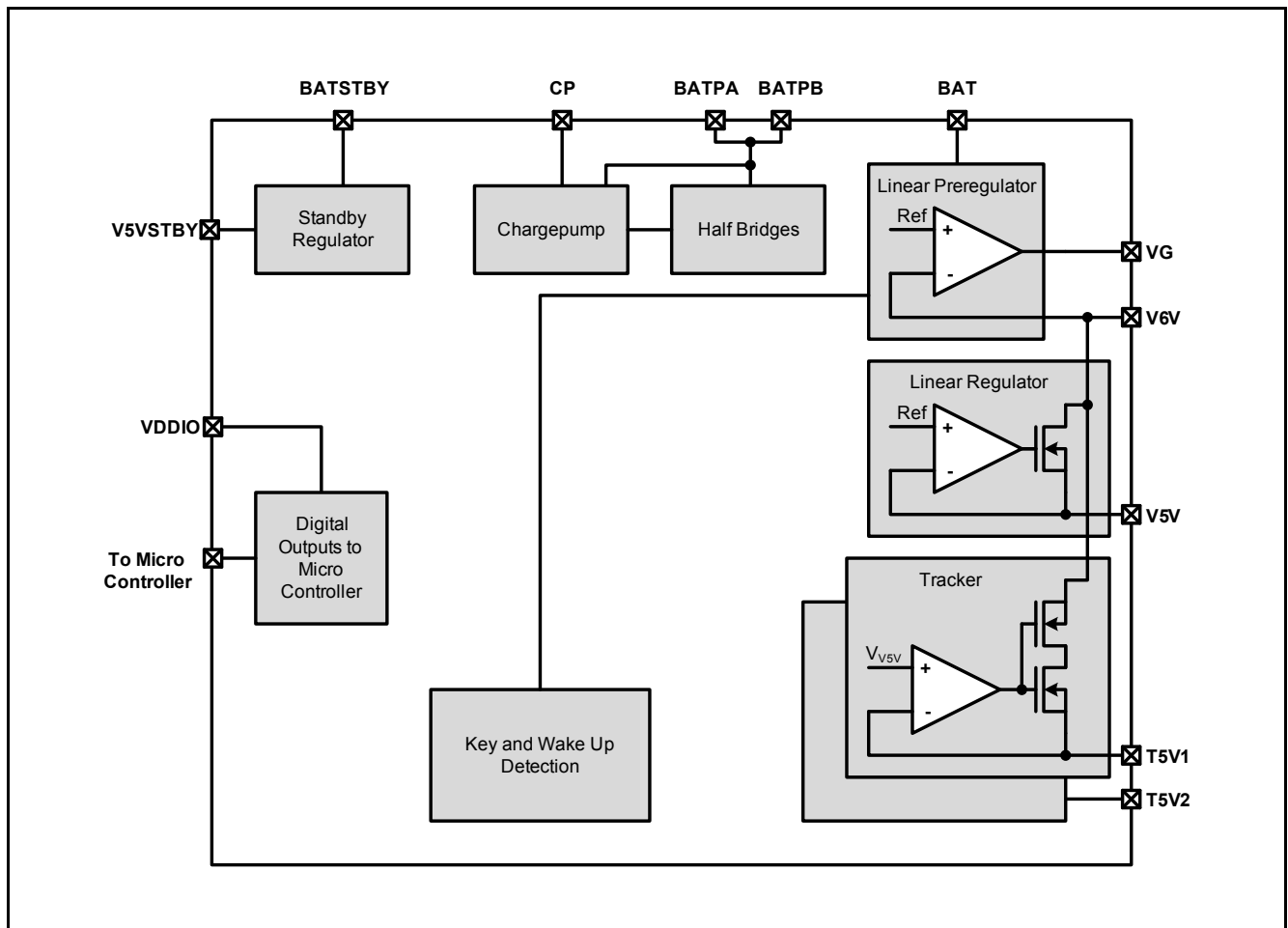
1) not subject to production test, specified by design

**Power Supply**

**8 Power Supply**

The power supply unit generates the internal supply (including supply for CAN and pre-drivers, voltage reference and current biasing), the main supply voltage for the ECU (*V5V*) and sensor supplies for off-board sensors (*T5V1* and *T5V2*). All supplies start working by the wake-up signal generated by the key and wake-up detection (see [Chapter 7.2](#) for details).

A linear pre-regulator with an external logic level power MOSFET is implemented to keep the power dissipation of the TLE8888-1QK low. The precise voltage supplies for the ECU and the sensor supplies are integrated inclusive the power transistor. All supplies with low drop functionality (main supply *V5V*, pre-regulator, sensor supplies *T5V1/T5V2*) are using an integrated charge pump to provide low drop behavior at low battery voltages.



**Figure 27 Block diagram of the power supply**

**8.1 Pre-Regulator**

The pre-regulator uses an external logic level power MOSFET and regulates the voltage at pin *V6V*. The voltage at the pin is also the input voltage for the main supply of the ECU (*V5V*), the sensor supplies (*T5V1*, *T5V2*) and the internal supply. The circuit is designed for low drop operation.

It's not allowed to load the external MOSFET with anything else than *V6V*. The function of the pre-regulator is guaranteed with the MOSFET IPD30N06S2L-23 of Infineon.

## Power Supply

### 8.2 5 V Main Supply

The 5 V main supply is designed to supply the ECU including microcontroller and e.g. other power chips. Out of *V6V* a high accurate voltage is provided at the pin *V5V*. The pin and the circuit is protected against overload and short circuit. For stabilization and ripple reduction an external buffer capacitor is required. For low drop operation of the regulator the pins *BATPA* and *BATPB* must be supplied.

### 8.3 Sensor Supply

There are two sensor supplies integrated providing an output voltage based on *V5V* as reference. Out of *V6V* a high accurate voltage is provided at the pins *T5V1* and *T5V2*. The pins and the circuits are protected against overload, short circuit and reverse supply back to *V6V*. For stabilization and ripple reduction external buffer capacitors are required. For low drop operation of the regulator the pins *BATPA* and *BATPB* must be supplied.

### 8.4 IO Supply

The TLE8888-1QK provides an IO supply pin *VDDIO* for 3.3 V and 5 V microcontroller interfaces. This pin is used for the supply of the output driver and defines the output level of all logical interface pins.

### 8.5 Standby Supply

The TLE8888-1QK integrates a standby supply which is supplied by the pin *BATSTBY* and provides a 5 V output supply at pin *V5VSTBY*. It is not allowed to connect this pin to any other supply.

### 8.6 Charge Pump

There is a charge pump integrated to supply the half bridges out of *BATPA* and *BATPB*. A capacitor has to be connected on the PCB (between *CP* and *BATPA/BATPB*) to buffer the voltage and reduce the ripple. It's not allowed to apply any external load to the pin *CP*.

### 8.7 Voltage Monitoring

The TLE8888-1QK provides voltage monitoring of the main ECU supply *V5V*, the sensor supplies *T5V1* and *T5V2* and the battery voltage. In [Chapter 5.2](#) the effect to the status of the TLE8888-1QK is described. All detection thresholds are implemented with a hysteresis and a filter time to suppress disturbances.

The status of the over- and undervoltage detection of *BAT*, *T5V1* and *T5V2* are available in the diagnosis register [Diag0](#) and the bits [BATOV](#), [T1UV](#), [T1OV](#), [T2UV](#) and [T2OV](#).

Under- and overvoltage of *V5V* leads to a reset of the microcontroller (see [Table 5](#) in [Chapter 5.2](#)). After release of the reset the cause of the reset is available in the status register [OpStat1](#) (bits [V5VUVR](#) and [V5VOVR](#)).

**Power Supply**

**8.8 Electrical Characteristics Power Supply**

**Table 22 Electrical Characteristics Power Supply**

$V_S = 13.5\text{ V}$ ,  $V_{V5V} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to GND, positive current flowing into pin, (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ	Max.			
current consumption at pins <i>BATPA</i> , <i>BATPB</i> , <i>BAT</i> and <i>V6V</i>	$I_{\text{BAT,sum}}$	–	–	50	mA	static, all “off”, no PWM and MSC/SPI communication	P_8.8.1

**Pre-Regulator**

Pre-Driver Output Voltage <i>V6V</i>	$V_{V6V}$	5.5	6	6.5	V	with respect to <i>AGND</i> , with external MOS FET IPD30N06S2L-23	P_8.8.2
Gate Output Voltage <i>VG</i>	$DV_{VG}$	4	–	7.5	V	$V_{V6V} = 5.5\text{ V}$ ; $DV_{VG} = V_{VG} - V_{V6V}$	P_8.8.3
Gate Output Voltage <i>VG</i> at low Supply	$DV_{VG,l}$	1.7	–	–	V	$V_{\text{BATPX}} = 4.5\text{ V}$ , $I_{VG} = 1\ \mu\text{A}$ ; $DV_{VG} = V_{VG} - V_{V6V}$	P_8.8.4
Buffer Capacitor at <i>V6V</i> <sup>1)</sup>	$C_{V6V}$	1	20	1000	$\mu\text{F}$	<sup>2) 3)</sup>	P_8.8.37
ESR of Buffer Capacitance at <i>V6V</i> <sup>1)</sup>	$ESR_{V6V}$	0.01		2	$\Omega$	for $C_{V6V} < 15\ \mu\text{F}$ , $f_{\text{ESR}} = 10\text{ kHz}$	P_8.8.38
ESR of Buffer Capacitance at <i>V6V</i> <sup>1)</sup>	$ESR_{V6V}$	0.5		2	$\Omega$	for $15\ \mu\text{F} < C_{V6V} < 20\ \mu\text{F}$ , $f_{\text{ESR}} = 10\text{ kHz}$	P_8.8.39
ESR of Buffer Capacitance at <i>V6V</i> <sup>1)</sup>	$ESR_{V6V}$	1		2	$\Omega$	for $20\ \mu\text{F} < C_{V6V} < 1000\ \mu\text{F}$ , $f_{\text{ESR}} = 10\text{ kHz}$	P_8.8.40
Buffer Capacitor at <i>VG</i> <sup>1)</sup>	$C_{VG}$	–	4.7	15	nF	<sup>2)3)</sup>	P_8.8.41
ESR of Buffer Capacitance at <i>VG</i> <sup>1)</sup>	$ESR_{VG}$	–	–	1	$\Omega$	$f_{\text{ESR}} = 10\text{ kHz}$	P_8.8.42

**5 V Main Supply *V5V***

Output Voltage <i>V5V</i>	$V_{V5V}$	4.9	–	5.1	V	$-5\text{ mA} < I_{V5V} < -500\text{ mA}$ , with respect to <i>AGND</i>	P_8.8.5
Voltage Drop <i>V6V-V5V</i> at low Supply	$V_{V5V,d}$	–	–	0.6	V	$I_{V5V} = -500\text{ mA}$ ; $V_{\text{BAT}} = V_{\text{BATPX}} = V_{\text{KEY}} = V_{V6V} = 4.5\text{ V}$	P_8.8.6
Voltage Drop <i>V6V-V5V</i> at low Supply and low temperature	$V_{V5V,d,CT}$	–	–	0.45	V	$T_j = -40^\circ\text{C}$ ; $I_{V5V} = -500\text{ mA}$ ; $V_{\text{BAT}} = V_{\text{BATPX}} = V_{\text{KEY}} = V_{V6V} = 4.5\text{ V}^{1)}$	P_8.8.7
Current Limitation	$I_{V5V,lim}$	-1200	–	-500	mA	–	P_8.8.8

**Power Supply**

**Table 22 Electrical Characteristics Power Supply (cont'd)**

$V_S = 13.5\text{ V}$ ,  $V_{V5V} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to GND, positive current flowing into pin, (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ	Max.			
Buffer Capacitor at $V5V^{1)}$	$C_{V5V}$	0.1	10	220	$\mu\text{F}$	<sup>2)3)</sup>	P_8.8.9
ESR of Buffer Capacitance at $V5V^{1)}$	$ESR_{V5V}$	0.01		2	$\Omega$	for $C_{V5V} < 10\ \mu\text{F}$ , $f_{\text{ESR}} = 10\ \text{kHz}$	P_8.8.43
ESR of Buffer Capacitance at $V5V^{1)}$	$ESR_{V5V}$	0.1		2	$\Omega$	for $10\ \mu\text{F} < C_{V5V} < 47\ \mu\text{F}$ , $f_{\text{ESR}} = 10\ \text{kHz}$	P_8.8.44
ESR of Buffer Capacitance at $V5V^{1)}$	$ESR_{V5V}$	0.5		2	$\Omega$	for $47\ \mu\text{F} < C_{V5V} < 220\ \mu\text{F}$ , $f_{\text{ESR}} = 10\ \text{kHz}$	P_8.8.45

**Sensor Supplies  $T5V1$  and  $T5V2$**

Output voltage tracking accuracy	$DV_{T5Vx}$	-10	-	10	mV	$DV_{T5Vx} = V_{V5V} - V_{T5Vx}$ , $4\text{ V} < V_{V5V} < 5.1\text{ V}$ , $V_{V6V} > 5.5\text{ V}$ , $V_{\text{IGNx}} \geq 0\text{ V}$	P_8.8.10
Current Limitation	$I_{T5Vx,\text{lim}}$	-300	-	-100	mA		P_8.8.11
Buffer Capacitor at $T5V1$ and $T5V2^{1)}$	$C_{T5Vx}$	-	-	400	nF		P_8.8.12

**IO Supply  $VDDIO$**

IO Supply Voltage Range	$V_{VDDIO}$	3	-	5.5	V	-	P_8.8.13
Current Consumption at pin $VDDIO$	$I_{DDIO}$	-	-	2	mA	$V_{VDDIO} = 5\text{ V}$ , $I_{\text{NX}} = 0\text{ V}$ , $\text{CSN} = \text{LINTX} =$ $\text{CANTX} = 5\text{ V}$ , $\text{MON}$ and $\text{RST}$ open <sup>1)</sup>	P_8.8.14

**Standby Supply  $V5VSTBY$**

Output Voltage $V5VSTBY$	$V_{V5VSTBY}$	4.75	-	5.25	V	$-10\ \mu\text{A} < I_{V5VSTBY} < -15\ \text{mA}$	P_8.8.15
Total Standby Current Consumption at pins $BATSTBY$ , $BAT$ , $V6V$ and $MR$	$I_{\text{STBY}}$	-	-	120	$\mu\text{A}$	ECU sleep mode, $T_j = 25^\circ\text{C}$ , $I_{V5VSTBY} = 0\ \text{mA}$ , $V_{\text{BATSTBY}} = V_{\text{BAT}} =$ $V_{\text{MR}} = 13.5\text{ V}$ , $EOTEN = \text{CANWK}$ $EN = 0\text{ V}$	P_8.8.16
Buffer Capacitor at $V5VSTBY^{1)}$	$C_{V5VSTBY}$	27	100	270	nF	<sup>2)3)</sup>	P_8.8.46
ESR of Buffer Capacitance at $V5VSTBY^{1)}$	$ESR_{V5VSTBY}$	0.01	-	1	$\Omega$		P_8.8.47

**Charge Pump**

**Power Supply**

**Table 22 Electrical Characteristics Power Supply (cont'd)**

$V_S = 13.5\text{ V}$ ,  $V_{V5V} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to GND, positive current flowing into pin, (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ	Max.			
Charge pump Output Voltage	$DV_{CP}$	4	5	7	V	$DV_{CP} = V_{CP} - V_{BAT}$ no external load currents	P_8.8.17
Charge pump Output Voltage at low supply	$DV_{CP}$	3.5	–	–	V	$V_{BAT} = 4.5\text{ V}$ after start up, $DV_{CP} = V_{CP} - V_{BATPx}$	P_8.8.18
Buffer Capacitor at $CP^{1)}$	$C_{CP}$	–	4.7	–	nF		P_8.8.19

**Voltage Monitoring**

V5V Undervoltage Detection Threshold, decreasing	$V_{UV,V5V,dec}$	4.45	–	4.7	V	$V_{V5V}$ decreasing	P_8.8.20
V5V Undervoltage Detection Threshold, increasing	$V_{UV,V5V,inc}$	4.45	–	4.8	V	$V_{V5V}$ increasing	P_8.8.21
V5V Undervoltage Detection Hysteresis	$V_{Hys,UV,V5V}$	10	50	–	mV	–	P_8.8.22
V5V Undervoltage Filter Time	$t_{f,UV,V5V}$	5	10	15	$\mu\text{s}$	–	P_8.8.23
T5V1 and T5V2 Undervoltage Detection Threshold	$V_{UV,T5Vx,dec}$	4.45	–	4.7	V	$V_{T5Vx}$ decreasing	P_8.8.24
T5V1 and T5V2 Undervoltage Detection Threshold	$V_{UV,T5Vx,inc}$	4.45	–	4.8	V	$V_{T5Vx}$ increasing	P_8.8.25
T5V1 and T5V2 Undervoltage Detection Hysteresis	$V_{Hys,UV,T5Vx}$	10	50	–	mV	–	P_8.8.26
T5V1 and T5V2 Undervoltage Filter Time	$t_{f,UV,T5Vx}$	5	10	15	$\mu\text{s}$	–	P_8.8.27
V5V Overvoltage Detection Threshold	$V_{OV,V5V}$	5.2	–	5.6	V	$V_{V5V}$ increasing	P_8.8.28
V5V Overvoltage Detection Hysteresis	$V_{Hys,OV,V5V}$	10	–	100	mV	–	P_8.8.29
V5V Overvoltage Filter Time	$t_{f,OV,V5V}$	5	10	15	$\mu\text{s}$	–	P_8.8.30
T5V1 and T5V2 Overvoltage Detection Threshold	$V_{OV,T5Vx}$	5.2	–	5.6	V	$V_{T5Vx}$ increasing	P_8.8.31
T5V1 and T5V2 Overvoltage Detection Hysteresis	$V_{Hys,OV,T5Vx}$	10	–	100	mV	–	P_8.8.32
T5V1 and T5V2 Overvoltage Filter Time	$t_{f,OV,T5Vx}$	5	10	15	$\mu\text{s}$	–	P_8.8.33
BAT Overvoltage Detection Threshold	$V_{OV,BAT}$	28	–	30.4	V	$V_{BAT}$ increasing	P_8.8.34

**Power Supply**

**Table 22 Electrical Characteristics Power Supply (cont'd)**

$V_S = 13.5\text{ V}$ ,  $V_{\text{SV}} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to GND, positive current flowing into pin, (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
BAT Overvoltage Detection Hysteresis	$V_{\text{Hys,BAT}}$	50	–	500	mV	–	P_8.8.35
BAT Overvoltage Filter Time	$t_{\text{f,OV,BAT}}$	5	10	15	$\mu\text{s}$	–	P_8.8.36

- 1) not subject to production test, specified by design
- 2) Defined minimum value is needed for regulator stability. Application might need higher value than minimum.
- 3) additionally in parallel a capacitance up to  $0.1 \cdot C_{\text{VxV}}$  and low ESR is allowed

Power Stages

## 9 Power Stages

In the TLE8888-1QK there are 14 low-side power stages, 4 half bridges, 4 push-pull outputs for on board and external ignition driver and 6 push-pull outputs for on board MOSFETs implemented. The 14 low-side power stages are designed for various inductive and resistive loads, 4 stages to drive especially injectors, 3 with a higher operating current to drive e.g. O2-heaters and 7 stages to drive relays.

For the injector output stages (*OUT1* to *OUT4*) the common enable input *INJEN* and for the ignition outputs the common enable input *IGNEN* are implemented. The half bridges can be used with high or low-side load, with active or passive freewheeling or in full bridge configuration.

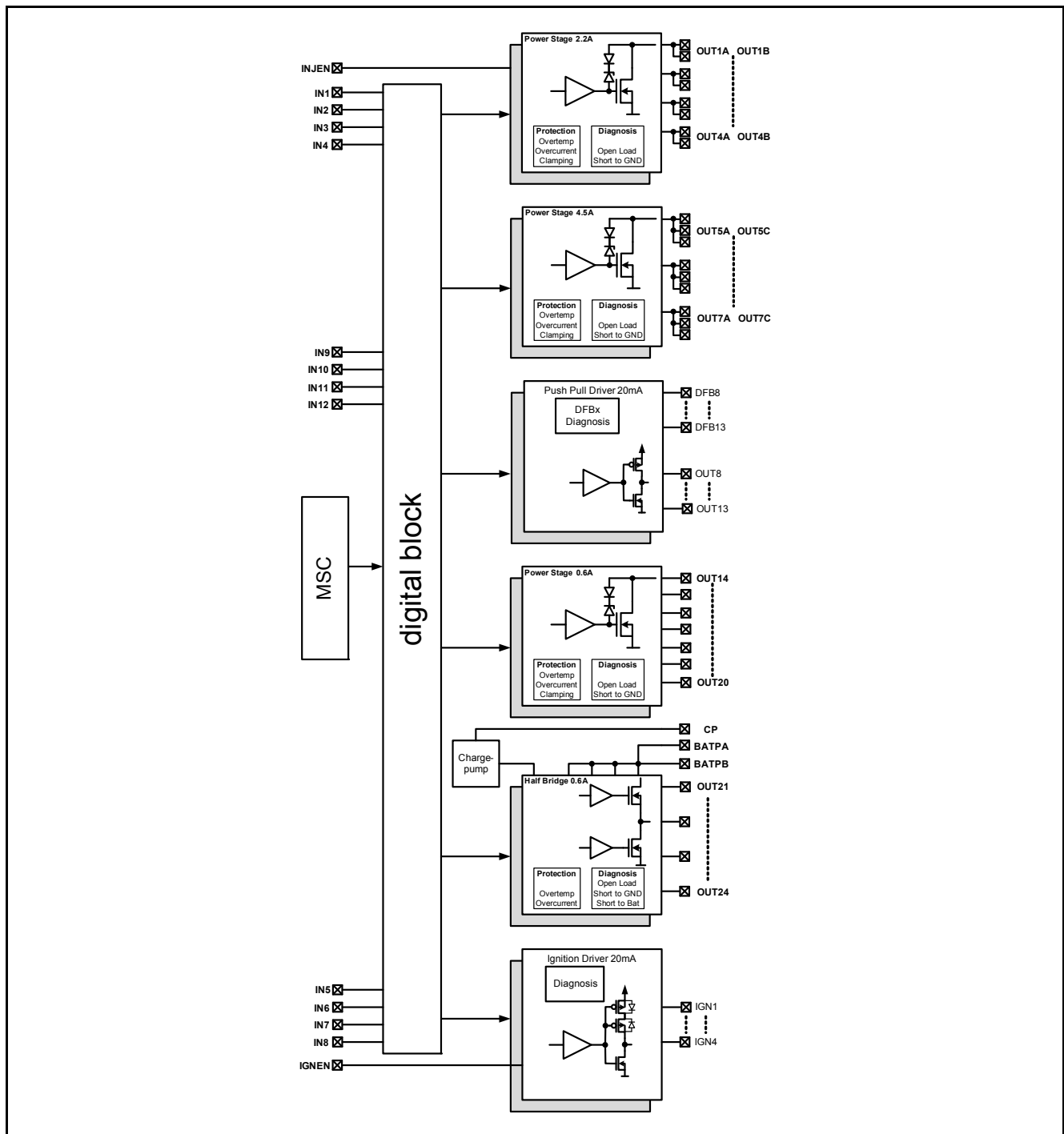


Figure 28 Block Diagram of the Power stages



**Power Stages**

**Table 23 Overview Power Stages**

	Type	maximum operation current	Ron	active clamping	Diagnosis in on	Diagnosis in off
<i>OUT1 to OUT4</i>	Low-side switch	2.2 A	550 mW	yes	overcurrent (short to battery) overtemperature	open load short to GND overtemperature
<i>OUT5 to OUT7</i>	Low-side switch	4.5 A	350 mW	yes	overcurrent (short to battery) overtemperature	open load short to GND overtemperature
<i>OUT8 to OUT13</i>	5 V push pull output	20/- 20 mA	–	no	at pin DFBx: short to battery  at pin OUTx: overvoltage	at pin DFBx: open load short to GND  at pin OUTx: overvoltage
<i>OUT14 to OUT20</i>	Low-side switch	0.6 A	1.5 W	yes	overcurrent (short to battery) overtemperature	open load short to GND overtemperature
<i>OUT21 to OUT24</i>	Half bridge	0.6 A	2.4 W	no	overcurrent (short to battery/short to GND) overtemperature	open load short to battery/short to GND overtemperature
<i>IGN1 to IGN4</i>	5 V push pull output	20/- 20 mA	–	no	short to battery short to GND open load	short to battery

### 9.1 Power Stage Control

The output stages will be controlled either by the MSC/SPI data frame or command frame and the control register **Cont0** to **Cont3** (see [Chapter 14.1.5](#)) or the direct drive inputs *IN1* to *IN12*. The configuration which control mode is active is done in the configuration register **DDConfig0** to **DDConfig3** (see [Chapter 14.1.4](#)). A “1” in the control register/data frame bit or a “high” at the direct drive inputs switches on the corresponding output.

In [Table 24](#) the assignment of the direct drive inputs to the output stages is shown. The set up is valid for MSC and SPI operation.

The status of the power stages is also affected by the operation state and conditions of the TLE8888-1QK and is described in [Chapter 5](#). All power stages are switched off if a micro channel time out occurs. Description of the effect to the control of the power stages see [Chapter 13.1.1, Downstream Supervisory Functions](#).

**Power Stages**

**Table 24 Direct Drive Input Assignment to Output Stages**

<b>Input</b>	<b>Output</b>	<b>Note</b>
<i>IN1 to IN4</i>	<i>OUT1 to OUT4</i>	configuration for direct drive: bits <b>O1DD</b> to <b>O4DD</b> of the configuration register <b>DDConfig0</b>  fix assignment of the inputs to the outputs
<i>IN5 to IN8</i>	<i>IGN1 to IGN4</i>	configuration for direct drive: bits <b>IGN1DD</b> to <b>IGN4DD</b> of the configuration register <b>DDConfig3</b>  fix assignment of the inputs to the outputs
<i>IN9 to IN12</i>	<i>OUT5 to OUT24</i>	configuration for direct drive: bits <b>O5DD</b> to <b>O24DD</b> of the configuration registers <b>DDConfig0</b> to <b>DDConfig2</b> assignment of input pins: configuration register <b>InConfig0</b> to <b>InConfig3</b> only 4 of this output stages can be switched directly

All direct drive inputs have implemented a pull down current source to define the input voltage. For a multiple assignment of two direct drive inputs for one output stage (wrong configuration) the output is switched off independent of the status of the direct drive inputs.

## 9.2 Power Stages Enable

To enable the power stages a central output enable bit **OE** is defined. The status of the bit is shown in the status register **OpStat1** and can be set with the command register **CmdOE**. Additionally a dedicated output enable bit for each output is defined (see register **OEConfig0** to **OEConfig3**) to avoid uncontrolled repetitive switching in failure case. These enable bits are reset by the protection function of each channel and block switch on of the channels. The bits could not be set if a protection function is active.

With setting the central enable bit to “1” all dedicated output enable bits are set to “1” (if no protection function is active) and all channels are enabled and can be controlled according their configuration.

With setting the central enable bit to “0” all dedicated output enable bits are set to “0” and all channels are disabled.

For the injector channels *OUT1* to *OUT4* the common enable input *INJEN* must be set to “high” and for the ignition outputs *IGN1* to *IGN4* the common enable input *IGNEN* must be set to “high” to enable the channels.

Procedure to switch on after failure condition occurred:

- Read out of diagnosis bits
- Second read out to verify that the failure conditions are not remaining
- Set of the dedicated output enable bit of the affected channel if the diagnosis bit is not active anymore
- Switch on of the channel

### Switch off during battery overvoltage:

To protect the power stages against high energy during freewheeling they are switched off for battery voltages greater than the “**BAT Overvoltage Detection Threshold**” (see **Table 22** in **Chapter 8.8**).

**Power Stages**

**9.3 Power Stages Configuration**

The power stages can be configured according the configuration bits in the configuration registers **OutConfig0** to **OutConfig5**, **BriConfig0**, **BriConfig1** and **IGNConfig**. The direct drive input configuration is described in **Table 24**.

**Table 25 Configuration Overview Power Stages**

	<b>Configuration</b>	<b>Configuration Register</b>
<i>OUT1</i> to <i>OUT4</i>	overcurrent: current limitation or switch off diagnosis in off: pull down current activated/deactivated	<b>OutConfig0</b>
<i>OUT5</i> to <i>OUT7</i>	overcurrent: current limitation or switch off diagnosis in off: pull down current activated/deactivated	<b>OutConfig1</b>
<i>OUT8</i> to <i>OUT13</i>	at pin DFBx: diagnosis in off: pull down current activated/deactivated diagnosis in on: short to battery detection thresholds	<b>OutConfig2</b> and <b>OutConfig3</b> bits 0 to 3
<i>OUT14</i> to <i>OUT20</i>	mode set up: delayed switch off mode for <i>OUT17</i> overcurrent: current limitation or switch off diagnosis in off: pull down current activated/deactivated ( <i>OUT14</i> to <i>OUT17</i> ) pull up and down current activated/deactivated ( <i>OUT18</i> to <i>OUT20</i> )	<b>OutConfig3</b> bits 4 and 5, <b>OutConfig4</b> , <b>OutConfig5</b>
<i>OUT21</i> to <i>OUT24</i>	mode set up: active or passive freewheeling high- or low-side switch mode half or full bridge mode delayed switch off mode for <i>OUT21</i>	<b>BriConfig0</b> and <b>BriConfig1</b>
<i>IGN1</i> to <i>IGN4</i>	open load in activation/deactivation open load current setting open load detection time	<b>IGNConfig</b>

**9.4 Special Function “Delayed Switch Off” for *OUT17* and *OUT21***

A special set up for the control behavior of *OUT17* and *OUT21* is implemented. With the delayed switch off functionality the outputs are suited to drive loads (e.g. starter relay) which must be on during very low battery voltages even if the microcontroller is in reset e.g. due to undervoltage. In this operation conditions all other power stages are normally switched off.

With the bits **O17D** in the configuration register **OutConfig4** and **O21D** in the configuration register **BriConfig1** both outputs can be configured to:

- normal control mode according description in **Chapter 9.1**
- delayed switch off mode

For delayed switch off mode *OUT17* and *OUT21* must be configured as controlled by MSC/SPI (bits **O17DD/O21DD** in configuration register **DDConfig2** are set to “0”)

Delayed switch off mode for *OUT21* is only allowed in high- or low-side switch configuration. Fullbridge configuration is not allowed.

The delayed switch off mode keeps the two outputs on for the time **ton,del** after an trigger event. With the trigger events in normal control mode the outputs are switched off.

## Power Stages

In delayed switch off mode the delayed switch off timer starts with following trigger events:

The channel must be on before a trigger event, switch on of all channels during the delayed switch off mode is not possible

- undervoltage of the main supply *V5V* is detected
- or overvoltage of the main supply *V5V* is detected
- or the MSC time out occurs
- or an active signal (“0”) at pin *MON*
- or an active signal (“0”) at pin *RST*

With the bit **RDOT** in the command register **Cmd0** the delayed switch off timer is restarted and the on time is increased.

The delayed off mode is terminated with following events:

- overflow of delayed off timer
- *O17/O21* are switched off with command **CmdOE**, set control register bits **O17ON/O21ON** or the configuration register bits **O17E/O21E** to “0”
- **O17D/O21D** are set to “0”
- Ready State is active and no trigger event is active

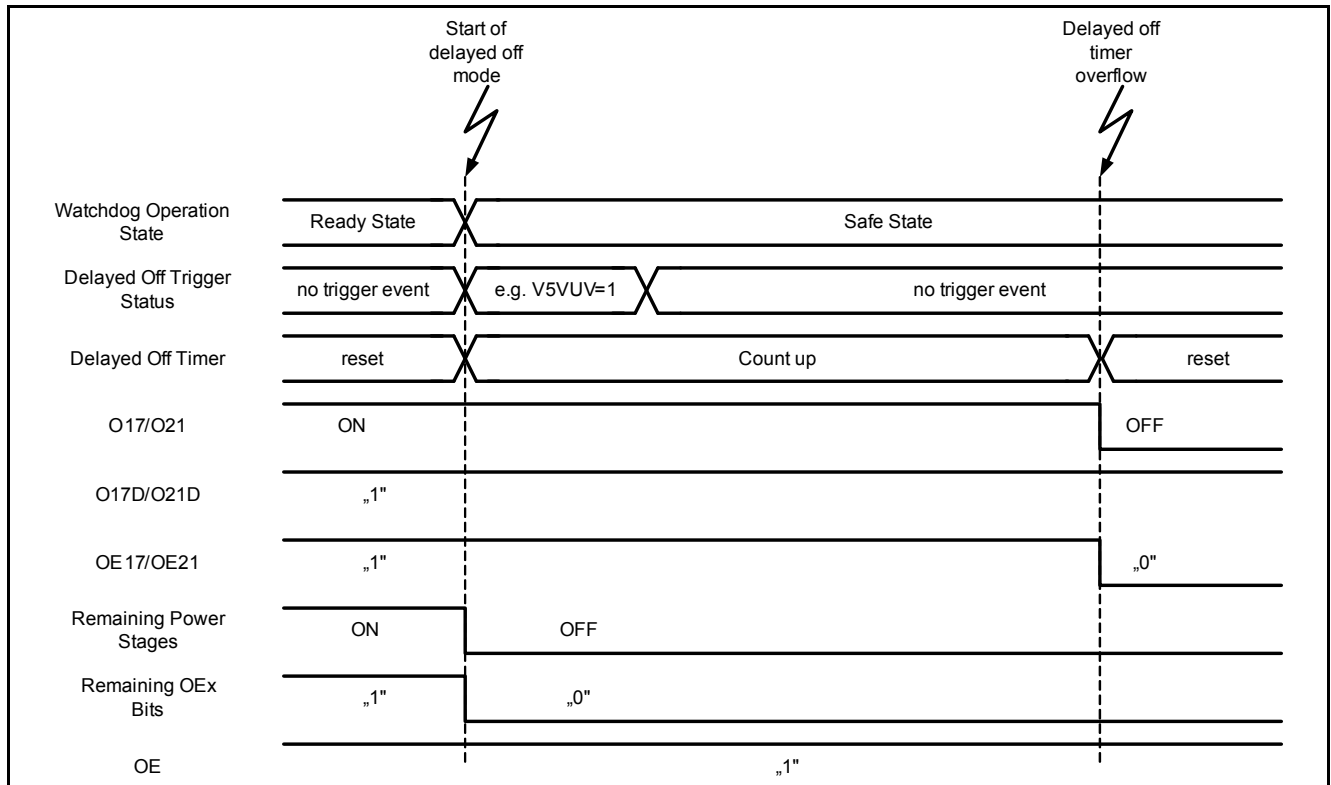
The outputs are switched off immediately if an internal power on reset occurs. According to the definition in **Chapter 5.1** if the conditions for a state change to ECU sleep mode are fulfilled the delayed off is terminated and the transition is executed.

Normally the related register bits of *OUT17* and *OUT21* are reset during undervoltage of the main supply *V5V* or an active signal (“0”) at pin *RST* (definition see **Table 5** and **Table 6** in **Chapter 5.2**). In delayed switch off configuration following register bits are not reset:

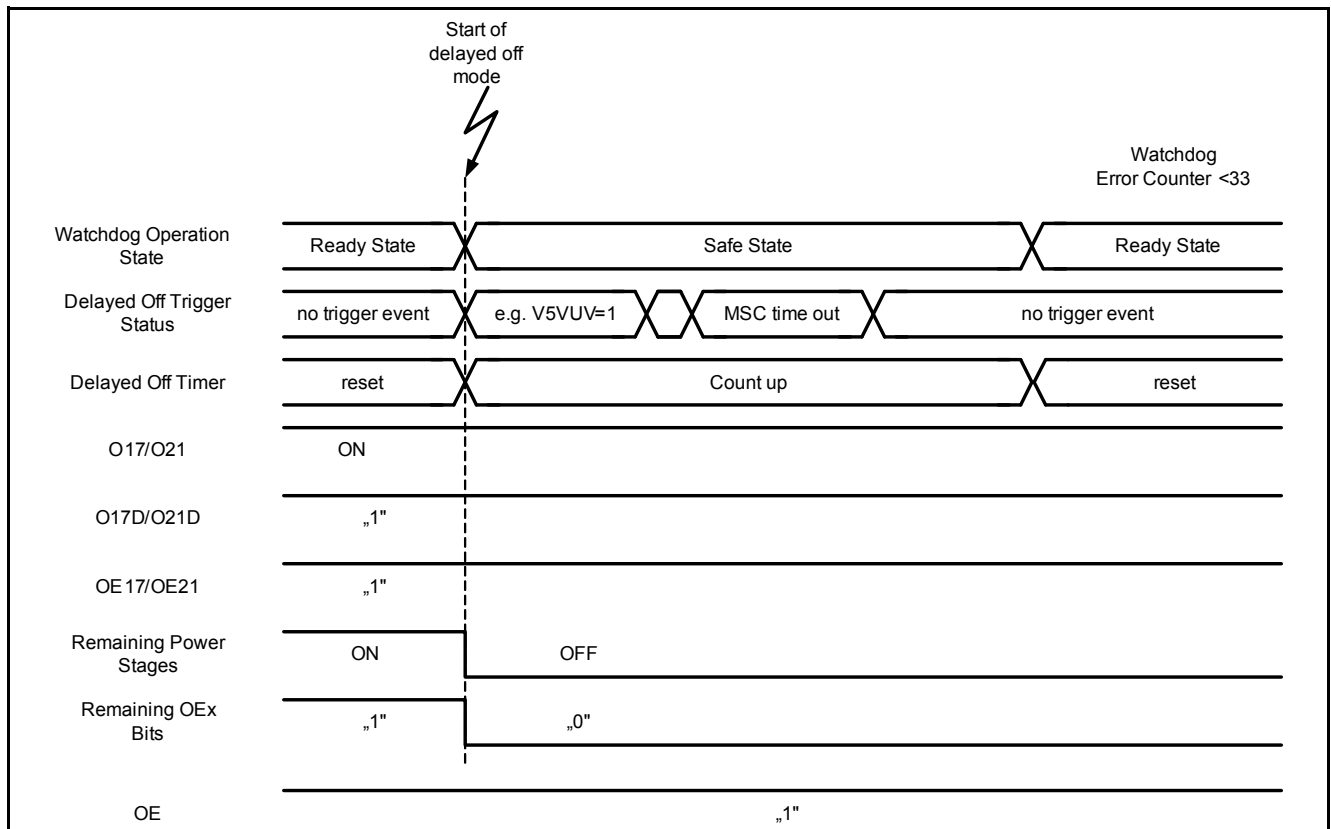
- **OE** in status register **OpStat1**
- **O17E, O21E** in configuration register **OEConfig2**
- **O17D, O17OL, O17OC** in configuration register **OutConfig4**
- **O21F, O21M** in configuration register **BriConfig0**
- **O21D** in configuration register **BriConfig1**

For illustration in **Figure 29** and **Figure 30** two examples for the delayed switch off mode for are shown.

**Power Stages**



**Figure 29 Example for Delayed Off Behavior: Overflow of Delayed Off Timer**



**Figure 30 Example for Delayed Off Behavior: Stop of Delayed Off Timer with Ready State**

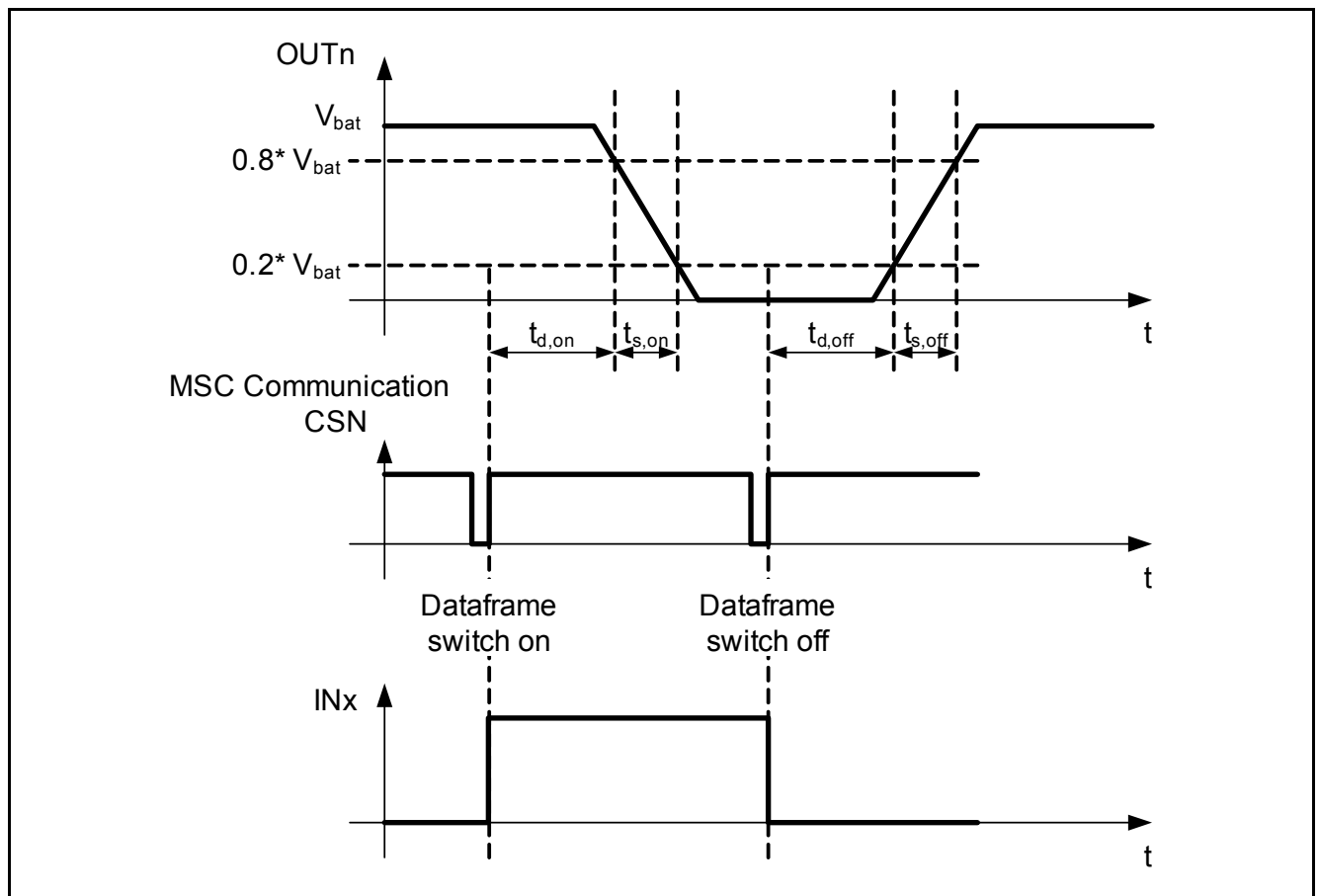
Power Stages

9.5 Electrical Characteristics Direct Drive Inputs

**Table 26 Electrical Characteristics Direct Drive Inputs**

$V_S = 13.5\text{ V}$ ,  $V_{VSV} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to GND, positive current flowing into pin, (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
<b>Direct Drive Inputs <i>IN1</i> to <i>IN12</i></b>							
Low Level Input Voltage	$V_{IN,l}$	-0.3	-	0.9	V	-	P_9.5.1
High Level Input Voltage	$V_{IN,h}$	2	-	$V_{VDDIO}$	V	-	P_9.5.2
Input Voltage Hysteresis	$V_{IN,hys}$	50	200	-	mV	-	P_9.5.3
Pull Down Current	$I_{IN,pd}$	25	-	100	$\mu\text{A}$	$V_{IN} = V_{VDDIO}$	P_9.5.4
Pull Down Current	$I_{IN,pd}$	2.4	-	-	$\mu\text{A}$	$V_{IN} = 0.6\text{ V}$	P_9.5.5
<b>Delayed Switch Off for <i>OUT17</i> and <i>OUT21</i></b>							
Switch On Time in Delayed Switch Off Mode	$t_{on,del}$	400	-	800	ms	-	P_9.5.6



**Figure 31 Switching Behavior**

## **9.6 Low-Side Switches *OUT1* to *OUT7* and *OUT14* to *OUT20***

The low-side switches are designed to withstand repetitive clamping events which occurs in automotive applications. The outputs are fully protected and various diagnosis functions are implemented.

They are controlled and enabled like all power stages according the description in [Chapter 9.1](#) and [Chapter 9.2](#). To enable the low-side switches *OUT1* to *OUT4* additionally the enable pin *INJEN* must be “high”.

The outputs are fully protected against overcurrent and overtemperature and various diagnosis functions are implemented. For the description of the diagnosis function see [Chapter 9.6.2](#).

All power stages are switched off if a micro channel time out occurs. Description of the effect to the control of the power stages see [Chapter 13.1.1, Downstream Supervisory Functions](#).

### **9.6.1 Protection of *OUT1* to *OUT7* and *OUT14* to *OUT20***

The outputs are fully protected against overcurrent and overtemperature.

The current protection of the power stages *OUT1* to *OUT7* and *OUT14* to *OUT20* can be configured to current limitation or switch off in case of overcurrent (configuration register [OutConfig0](#), [OutConfig1](#), [OutConfig3](#) to [OutConfig5](#) bits [O10C](#) to [O70C](#) and [O140C](#) to [O200C](#)). In failure case (e.g. short to battery) the output current of the low-side switches are always limited and an overcurrent condition is detected if the overcurrent signal is valid longer than the “[Overcurrent Detection Filter Time](#)”. With the detection the corresponding diagnosis bits are set according the priority shown in [Table 27](#) and for switch off configuration additionally the output is switched off.

To cover all failure conditions the overtemperature protection is implemented. Especially for the overcurrent limitation configuration the overtemperature is the only protection function against overload. After exceeding the temperature threshold the outputs are switched off till the temperature is decreased by the “[Overtemperature Hysteresis](#)”.

For the procedure to switch on an affected channel after failure condition see [Chapter 9.2](#).

### **9.6.2 Diagnosis of *OUT1* to *OUT7* and *OUT14* to *OUT20***

For the low-side outputs various diagnosis function are implemented. For short to battery in on diagnosis the protection function overcurrent and overtemperature are used to set the diagnosis information and for open load and short to GND (SCG) in off a special circuit is implemented.

To detect the open load/short to GND a push pull circuits is active which leads to the function of the voltage and currents of the outputs shown in [Figure 32](#). With the defined detection threshold the load condition can be detected.

With the off signal of the output stage the open load/short to GND detection circuit is enabled. To suppress disturbances the output of the detection circuit is stored in the diagnosis register [OutDiag0](#) to [OutDiag4](#) after the “[Diagnosis Filter Time for open load and short to GND in off](#)”  $t_{diag,f}$  and according the priority shown in [Table 27](#). With the readout of the diagnosis register the content is updated to the actual diagnosis.

For the outputs *OUT1* to *OUT7* and *OUT14* to *OUT17* the diagnosis pull down current of the open load/short to GND in off detection could be switched off (see configuration register [OutConfig1](#) to [OutConfig4](#)). With deactivated pull down current open load in off detection is not active and the diagnosis information 10B will never occur and is deactivated. With deactivated pull down current the short to GND detection is active.

For the outputs *OUT18* to *OUT20* the diagnosis pull up and down currents could be switched off (bits [O180L](#) and [O200L](#) in configuration register [OutConfig5](#)). In this case no diagnosis information in off is active and the bits [O18DIAG1](#), [O19DIAG1](#) and [O20DIAG1](#) are “0”.

In [Figure 32](#) the behavior open load/short to GND in off detection of the output current as a function of the output voltage is shown.

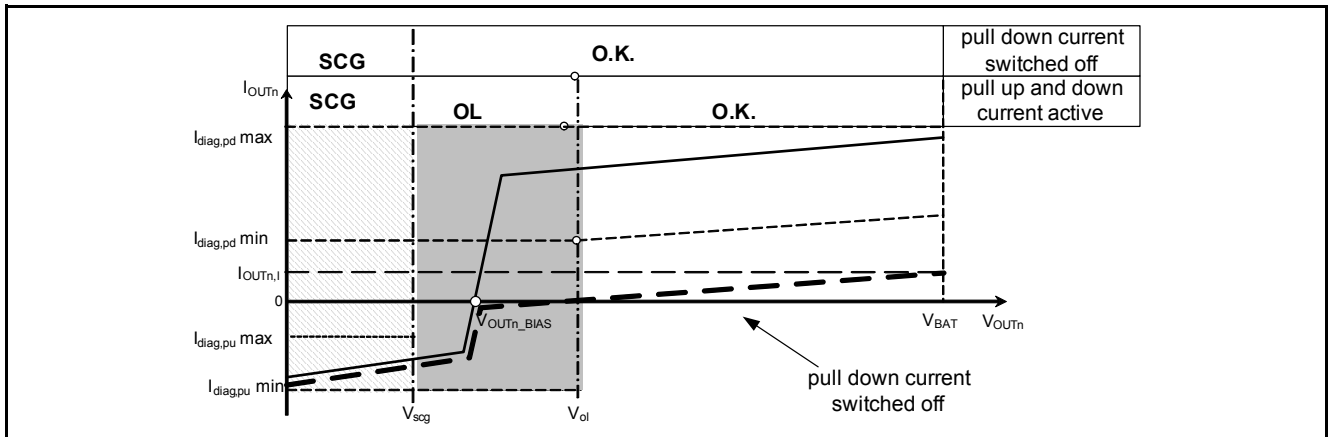


Figure 32 Output behavior with active diagnosis in off

Table 27 Description of Diagnosis Information

OnDIAG[1:0]	Priority (1 = highest priority)	Description
00	4	no failure
01	1	short circuit to battery (overcurrent) or overtemperature
10	2	open load in off <sup>1) 2)</sup>
11	3	short circuit to ground in off <sup>2)</sup>

1) no open load in off detection with deactivated pull down current

2) no open load and short to GND in off signalization for *OUT18* to *OUT20* if pull up and down currents are switched off

### 9.6.3 Electrical Characteristics Low-Side Switches *OUT1* to *OUT7* and *OUT14* to *OUT20*

Table 28 Electrical Characteristics Low-Side Switches *OUT1* to *OUT7* and *OUT14* to *OUT20*

$V_S = 13.5\text{ V}$ ,  $V_{SV} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to GND, positive current flowing into pin, (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
<b>OUT1...4, n = 1 to 4</b>							
Operation Current	$I_{OUTn}$	-	-	2.2	A		P_9.6.1
Limitation Current in Overcurrent condition	$I_{OUTn,lim}$	2.2	-	4	A		P_9.6.2
Overcurrent Detection Filter Time	$t_{oc,f}$	40	-	70	$\mu\text{s}$		P_9.6.3
On Resistance	$R_{OUTn,on}$		-	550	m $\Omega$	$I_{OUTn} = 2.2\text{ A}$	P_9.6.4
Clamping Voltage	$V_{OUTn,cv}$	50	-	60	V	$I_{OUTn} = 0.2\text{ A}$	P_9.6.5
Repetitive Clamping Energy	$E_{OUTn,cl}$	-	-	4	mJ	$I_{OUTn} < 1.4\text{ A}$ , $T_j = 125^\circ\text{C}$ , 648*106 cycles <sup>1)</sup>	P_9.6.6



**Table 28 Electrical Characteristics Low-Side Switches *OUT1* to *OUT7* and *OUT14* to *OUT20* (cont'd)**

$V_S = 13.5\text{ V}$ ,  $V_{SV} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to GND, positive current flowing into pin, (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
Leakage Current 1	$I_{OUTn,l,1}$	–	–	5	$\mu\text{A}$	$V_{OUTn} = 13.5\text{ V}$ , $V_{BAT} = 0\text{ V}$ , $T_j = 60^\circ\text{C}^{1)2)}$	P_9.6.7
Leakage Current 2	$I_{OUTn,l,2}$	–	–	10	$\mu\text{A}$	$V_{OUTn} = 28\text{ V}$ , $V_{BAT} = 0\text{ V}$ , $T_j = 60^\circ\text{C}^{1)2)}$	P_9.6.8
Leakage Current 3	$I_{OUTn,l,3}$	–	–	20	$\mu\text{A}$	$V_{OUTn} < 28\text{ V}$ , $V_{BAT} = 0\text{ V}$ , $T_j = 150^\circ\text{C}^2)$	P_9.6.9
Turn On Delay Time	$t_{d,on}$	1	–	7	$\mu\text{s}$	$V_{OUTn} = 13.5\text{ V}$ , $I_{OUTn} = 2.2\text{ A}$ , resistive load <sup>3)</sup>	P_9.6.10
Turn Off Delay Time	$t_{d,off}$	1	–	8	$\mu\text{s}$	$V_{OUTn} = 13.5\text{ V}$ , $I_{OUTn} = 2.2\text{ A}$ , resistive load <sup>3)</sup>	P_9.6.11
Switch On Time	$t_{s,on}$	1.8	–	7	$\mu\text{s}$	$V_{OUTn} = 13.5\text{ V}$ , $I_{OUTn} = 2.2\text{ A}$ , resistive load <sup>3)</sup>	P_9.6.12
Switch Off Time	$t_{s,off}$	1.8	–	7	$\mu\text{s}$	$V_{OUTn} = 13.5\text{ V}$ , $I_{OUTn} = 2.2\text{ A}$ , resistive load <sup>3)</sup>	P_9.6.13

**OUT5...7, n = 5 to 7**

Operation Current	$I_{OUTn}$	–	–	4.5	A		P_9.6.14
Limitation Current in Overcurrent condition	$I_{OUTn,lim}$	4.5	–	8	A		P_9.6.15
Overcurrent Detection Filter Time	$t_{oc,f}$	40	–	70	$\mu\text{s}$		P_9.6.16
On Resistance	$R_{OUTn,on}$		–	350	m $\Omega$	$I_{OUTn} = 3\text{ A}$	P_9.6.17
Clamping Voltage	$V_{OUTn,cv}$	50	–	60	V	$I_{OUTn} = 0.2\text{ A}$	P_9.6.18
Repetitive Clamping Energy	$E_{OUTn,cl}$	–	–	22	mJ	$I_{OUTn} < 1.05\text{ A}$ , $T_j = 125^\circ\text{C}$ , $1 \cdot 10^9\text{ cycles}^1)$	P_9.6.19
Leakage Current 1	$I_{OUTn,l,1}$	–	–	5	$\mu\text{A}$	$V_{OUTn} = 13.5\text{ V}$ , $V_{BAT} = 0\text{ V}$ , $T_j = 60^\circ\text{C}^{1)2)}$	P_9.6.20
Leakage Current 2	$I_{OUTn,l,2}$	–	–	10	$\mu\text{A}$	$V_{OUTn} = 28\text{ V}$ , $V_{BAT} = 0\text{ V}$ , $T_j = 60^\circ\text{C}^{1)2)}$	P_9.6.21
Leakage Current 3	$I_{OUTn,l,3}$	–	–	30	$\mu\text{A}$	$V_{OUTn} < 28\text{ V}$ , $V_{BAT} = 0\text{ V}$ , $T_j = 150^\circ\text{C}^2)$	P_9.6.22

**Table 28 Electrical Characteristics Low-Side Switches *OUT1* to *OUT7* and *OUT14* to *OUT20* (cont'd)**

$V_S = 13.5\text{ V}$ ,  $V_{VSV} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to GND, positive current flowing into pin, (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
Turn On Delay Time	$t_{d,on}$	1	–	7	$\mu\text{s}$	$V_{OUTn} = 13.5\text{ V}$ , $I_{OUTn} = 2.2\text{ A}$ , resistive load <sup>3)</sup>	P_9.6.23
Turn Off Delay Time	$t_{d,off}$	1	–	7	$\mu\text{s}$	$V_{OUTn} = 13.5\text{ V}$ , $I_{OUTn} = 2.2\text{ A}$ , resistive load <sup>3)</sup>	P_9.6.24
Switch On Time	$t_{s,on}$	1.4	–	7	$\mu\text{s}$	$V_{OUTn} = 13.5\text{ V}$ , $I_{OUTn} = 2.2\text{ A}$ , resistive load <sup>3)</sup>	P_9.6.25
Switch Off Time	$t_{s,off}$	1.4	–	7	$\mu\text{s}$	$V_{OUTn} = 13.5\text{ V}$ , $I_{OUTn} = 2.2\text{ A}$ , resistive load <sup>3)</sup>	P_9.6.26

**OUT14...20, n = 14 to 20**

Operation Current	$I_{OUTn}$	–	–	0.6	A		P_9.6.27
Limitation Current in Overcurrent condition	$I_{OUTn,lim}$	0.6	–	1.5	A		P_9.6.28
Overcurrent Detection Filter Time	$t_{oc,f}$	40	–	70	$\mu\text{s}$		P_9.6.29
On Resistance	$R_{OUTn,on}$		–	1.5	$\Omega$	$I_{OUTn} = 0.6\text{ A}$	P_9.6.30
<i>OUT17</i> On Resistance at Low Battery Voltage	$R_{OUT17,on,l}$		–	1.7	$\Omega$	$I_{OUTn} = 0.1\text{ A}$ , $V_{BATPx} = 4.5\text{ V}$	P_9.6.31
Clamping Voltage	$V_{OUTn,cv}$	50	–	60	V	$I_{OUTn} = 0.2\text{ A}$	P_9.6.32
Repetitive Clamping Energy	$E_{OUTn,cl}$	–	–	6.5	mJ	$I_{OUTn} < 0.3\text{ A}$ , $T_j = 125^\circ\text{C}$ , $40 \cdot 10^6\text{ cycles}^1)$	P_9.6.33
Leakage Current 1	$I_{OUTn,l,1}$	–	–	5	$\mu\text{A}$	$V_{OUTn} = 13.5\text{ V}$ , $V_{BAT} = 0\text{ V}$ , $T_j = 60^\circ\text{C}^{1)2)}$	P_9.6.34
Leakage Current 2	$I_{OUTn,l,2}$	–	–	15	$\mu\text{A}$	$V_{OUTn} = 28\text{ V}$ , $V_{BAT} = 0\text{ V}$ , $T_j = 60^\circ\text{C}^{1)2)}$	P_9.6.35
Leakage Current 3	$I_{OUTn,l,3}$	–	–	35	$\mu\text{A}$	$V_{OUTn} = 28\text{ V}$ , $V_{BAT} = 0\text{ V}$ , $T_j = 150^\circ\text{C}^2)$	P_9.6.36
Turn On Delay Time	$t_{d,on}$	1	–	7	$\mu\text{s}$	$V_{OUTn} = 13.5\text{ V}$ , $I_{OUTn} = 0.3\text{ A}$ , resistive load <sup>3)</sup>	P_9.6.37
Turn Off Delay Time	$t_{d,off}$	1	–	7	$\mu\text{s}$	$V_{OUTn} = 13.5\text{ V}$ , $I_{OUTn} = 0.3\text{ A}$ , resistive load <sup>3)</sup>	P_9.6.38

**Table 28 Electrical Characteristics Low-Side Switches *OUT1* to *OUT7* and *OUT14* to *OUT20* (cont'd)**

$V_S = 13.5\text{ V}$ ,  $V_{SV} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to GND, positive current flowing into pin, (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
Switch On Time	$t_{s,on}$	1.1	–	5.6	$\mu\text{s}$	$V_{OUTn} = 13.5\text{ V}$ , $I_{OUTn} = 0.3\text{ A}$ , resistive load <sup>3)</sup>	P_9.6.39
Switch Off Time	$t_{s,off}$	1.1	–	5.6	$\mu\text{s}$	$V_{OUTn} = 13.5\text{ V}$ , $I_{OUTn} = 0.3\text{ A}$ , resistive load <sup>3)</sup>	P_9.6.40
Delayed Off Time after trigger event for <i>OUT17</i>	$t_{off,del}$	400	–	800	ms		P_9.6.41

**Diagnosis *OUT1* to *7* and *OUT14* to *20***

Overtemperature Switch Off Threshold	$T_{OUTn,ot}$	150	–	200	$^\circ\text{C}$	1)	P_9.6.42
Overtemperature Hysteresis	$T_{OUTn,ot,hy}$ s	–	10	–	$^\circ\text{C}$	1)	P_9.6.43
Open Load in Off Detection Threshold	$V_{ol}$	$5V-0.15$	$5V$	$5V+0.15$	V		P_9.6.44
Short to GND in Off Detection Threshold	$V_{scg}$	$0.6*V5V-0.15$	$0.6*V5V$	$0.6*V5V+0.15$	V		P_9.6.45
Diagnosis Pull Up Current	$I_{diag,pu}$	-270	–	-150	$\mu\text{A}$	$V_{OUTn} = 0\text{ V}$ , $V_{IGNx} \geq 0\text{ V}$	P_9.6.46
Diagnosis Pull Down Current	$I_{diag,pd}$	280	–	500	$\mu\text{A}$	$V_{ol} < V_{OUTn} < V_{BAT}$ , $V_{IGNx} \geq 0\text{ V}$	P_9.6.47
Diagnosis Filter Time for open load and short to GND in off	$t_{diag,f}$	60	–	135	$\mu\text{s}$		P_9.6.48

**Direct Drive Inputs *INJEN***

Low Level Input Voltage	$V_{IN,l}$	-0.3	–	0.9	V		P_9.6.49
High Level Input Voltage	$V_{IN,h}$	2	–	$V_{VDDIO}$	V		P_9.6.50
Input Voltage Hysteresis	$V_{IN,hys}$	50	200	–	mV		P_9.6.51
Pull Down Current	$I_{IN,pd}$	25	–	100	$\mu\text{A}$	$V_{IN} = V_{VDDIO}$	P_9.6.52
Pull Down Current	$I_{IN,pd}$	2.4	–	–	$\mu\text{A}$	$V_{IN} = 0.6\text{ V}$	P_9.6.53

- 1) Parameter is not subject of production test, specified by design
- 2) additionally diagnosis currents are active in operation mode; exception *OUT18* to *OUT20* in diagnosis current switch off configuration
- 3) see [Figure 31](#)

## 9.7 Half Bridges *OUT21* to *OUT24*

The TLE8888-1QK integrates 4 half bridges which can be used as half bridge, full bridge, low-side power stage or high-side power stage. They are fully protected against overload and overtemperature and diagnosis fits to the chosen setup of the load. For the description of the diagnosis function see [Chapter 9.7.2](#).

They are controlled and enabled like all power stages according the description in [Chapter 9.1](#) and [Chapter 9.2](#). In [Table 29](#) the effect of **O21E** to **O24E** and **O21ON** to **O24ON** to the high-side and low-side switch of the half bridge is shown.

The half bridges can be configured via MSC/SPI for high- or low-side loads (setup see [Figure 33](#)) and for passive or active freewheeling (freewheeling is done with bulk diode or actively with switching on the freewheeling path). In [Table 29](#) the configuration is shown. With the bits **O21M** to **O24M** of the configuration register **BriConfig0** the switching mode is defined. With this configuration the low or the high-side transistor is defined to switch on the load. For low-side switch mode the load is connected to the battery, for high-side switch mode the load is connected to GND (see [Figure 33](#)). With the bits **O21F** to **O24F** of the configuration register **BriConfig0** the freewheeling behavior is defined. The freewheeling is done for low-side switch mode with the high-side transistors. For passive freewheeling the bulk diode is used and the freewheeling transistor is always off. For the active freewheeling mode the freewheeling transistor is on during an off signal. This is the so called half bridge mode. The alternate switching of the high-side and low-side switch is done with a break before make phase. The definition of the switching mode is important for the correct diagnosis in off (see [Chapter 9.7.2](#)). The bits **FB1E** and **FB2E** (full bridge enable) are only used for the diagnosis in off for full bridge set up. **FB1E** = "1" is used for loads connected between *OUT21* and *OUT22*. **FB2E** = "1" is used for loads connected between *OUT23* and *OUT24*. The diagnosis in off setup is changed to the special situation of full bridge mode. The setting with **O21M** to **O24M** and **O21F** to **O24F** are valid.

Note: for full bridge set up the same set up for the two half bridges is recommended!

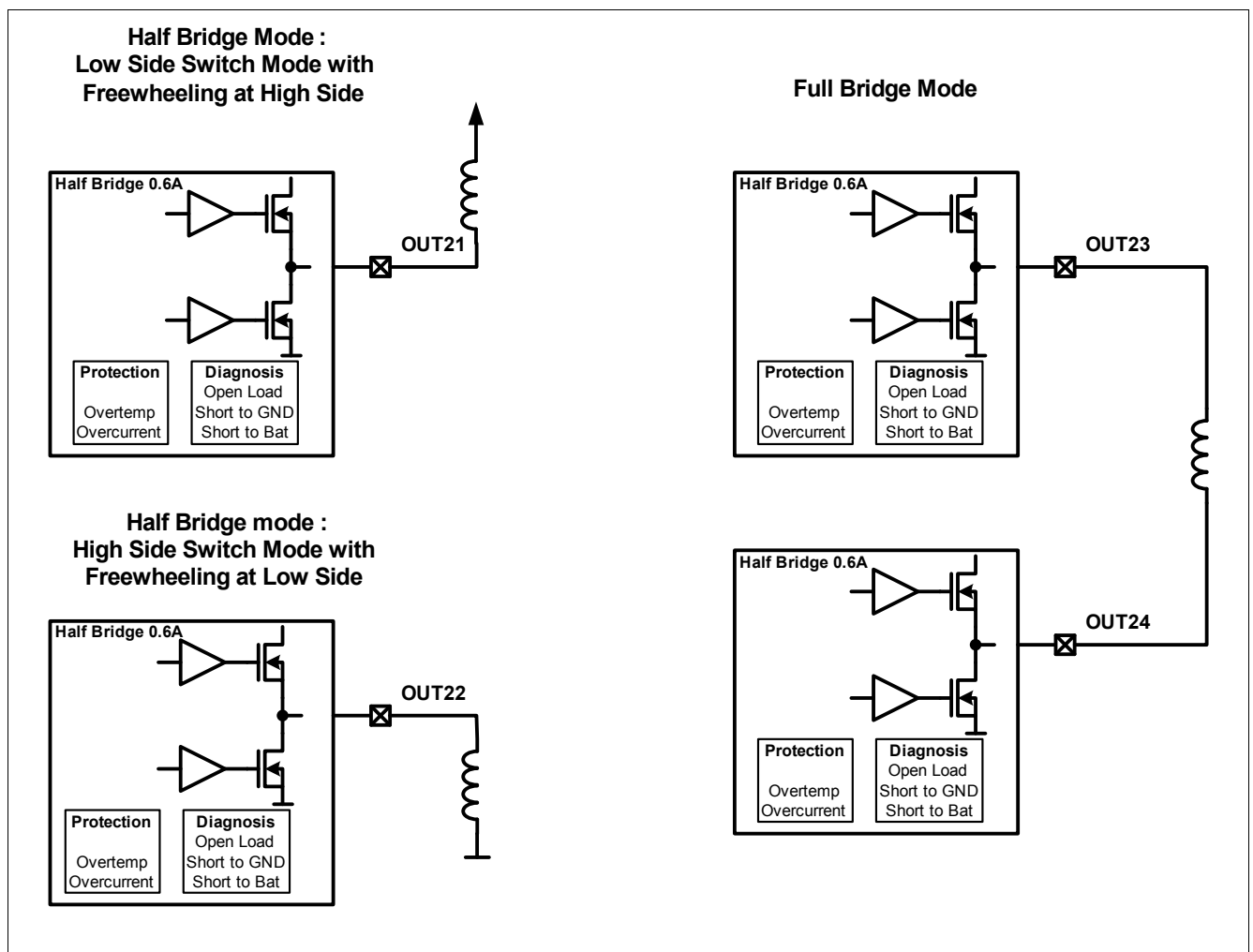
**Table 29 Configuration of the Half Bridge**

OnM <sup>1)</sup>	OnF <sup>1)</sup>	OnE <sup>1)</sup>	OnON = 1 <sup>1)</sup>	OnON = 0 <sup>1)</sup>	Description
0	0	0	high-side =off low-side = off	high-side =off low-side = off	low-side switch mode and passive freewheeling at high-side: <sup>2)</sup> both switches are disabled
0	0	1	high-side =off low-side = on	high-side =off low-side = off	low-side switch mode and passive freewheeling at high-side: <sup>2)</sup> high-side switch always off, bulk diode of high-side switch is used for passive freewheeling
0	1	0	high-side =off low-side = off	high-side =off low-side= off	low-side switch mode and active freewheeling at high-side: <sup>2)</sup> both switches are disabled
0	1	1	high-side =off low-side = on	high-side =on low-side= off	low-side switch mode and active freewheeling at high-side: <sup>2)</sup> high-side switch on during freewheeling
1	0	0	high-side =off low-side= off	high-side =off low-side= off	high-side switch mode and passive freewheeling at low-side: <sup>2)</sup> both switches are disabled

**Table 29 Configuration of the Half Bridge (cont'd)**

OnM <sup>1)</sup>	OnF <sup>1)</sup>	OnE <sup>1)</sup>	OnON = 1 <sup>1)</sup>	OnON = 0 <sup>1)</sup>	Description
1	0	1	high-side =on low-side= off	high-side =off low-side= off	high-side switch mode and passive freewheeling at low-side: <sup>2)</sup> low-side switch always off, bulk diode of low-side switch is used for passive freewheeling
1	1	0	high-side =off low-side= off	high-side =off low-side= off	high-side switch mode and active freewheeling at low-side: <sup>2)</sup> both switches are disabled
1	1	1	high-side =on low-side= off	high-side =off low-side= on	high-side switch mode and active freewheeling at low-side: <sup>2)</sup> low-side switch on during freewheeling

- 1) n=21 to 24 for the selected half bridge channel
- 2) setup definition see [Figure 33](#)



**Figure 33 Load setups for half and full bridge mode**

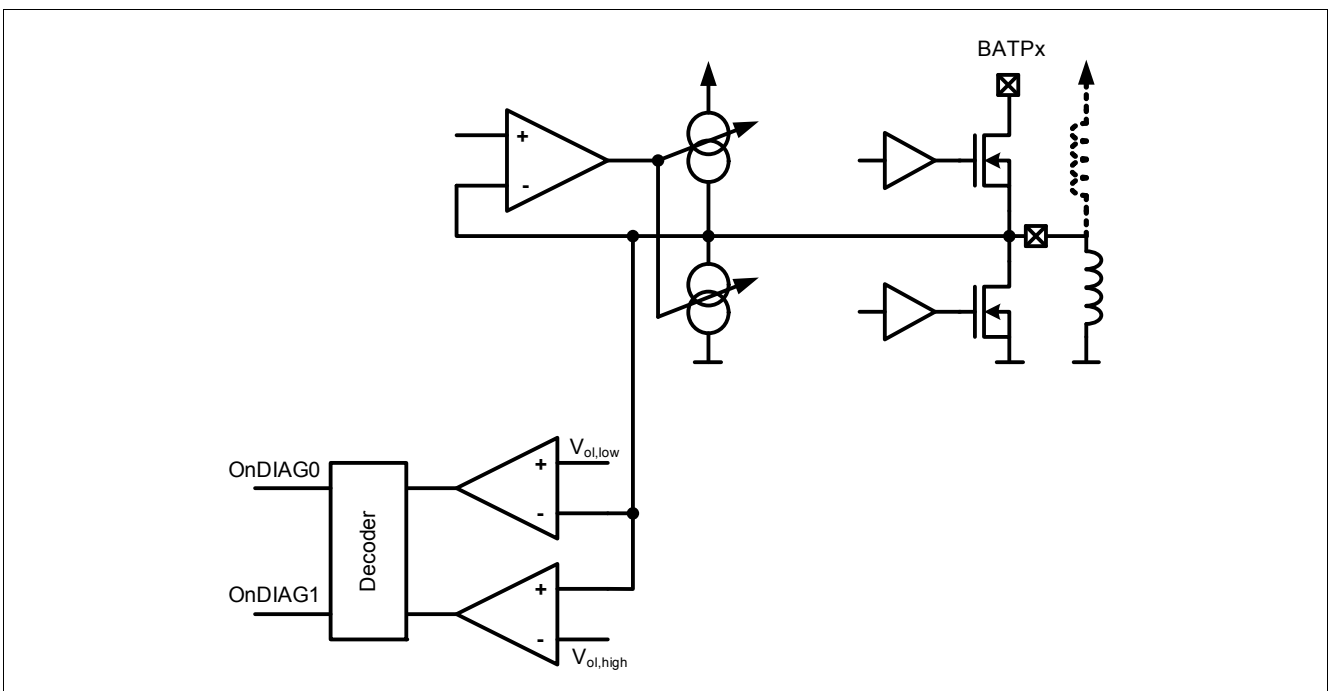
### 9.7.1 Protection of Half Bridges *OUT21* to *OUT24*

The half bridge outputs are fully protected against overcurrent and overtemperature. In failure case (e.g. short to GND) the affected transistor is switched off after the “**Overcurrent Switch Off Filter Time**” and the diagnosis bit is set. The half bridge output is high ohmic (tristate). To cover all failure conditions the overtemperature protection is implemented. After exceeding the temperature threshold the half bridge outputs are switched off till the temperature is decreased by the “**Overtemperature Hysteresis**”.

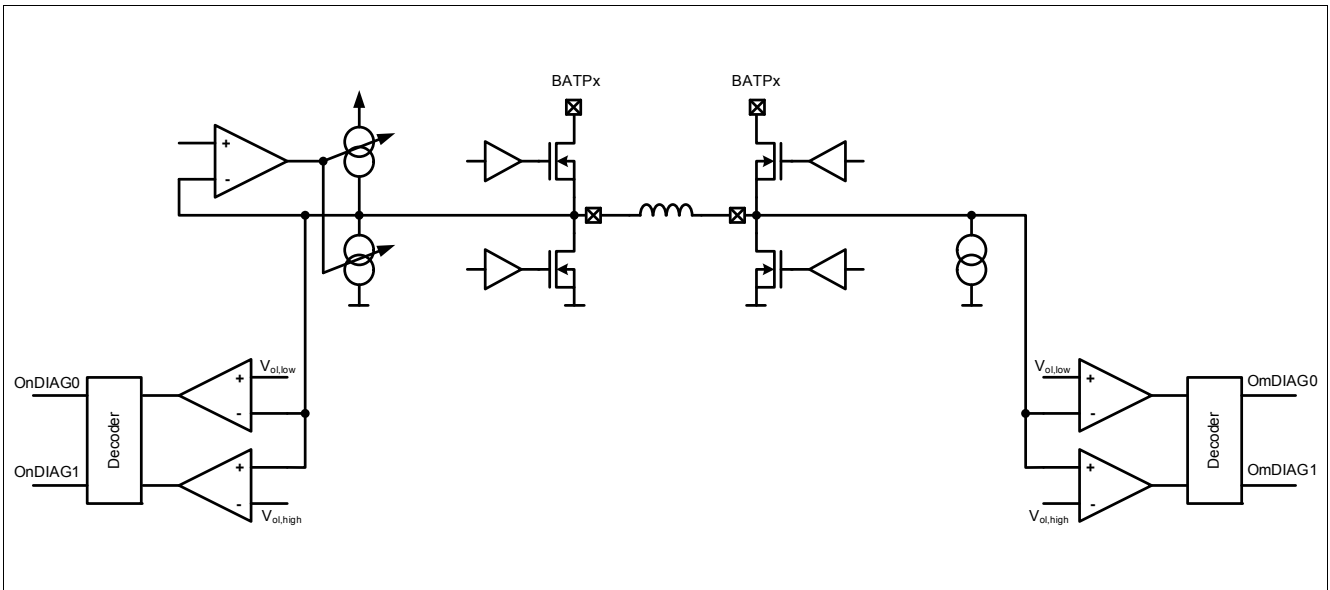
For the procedure to switch on an affected channel after failure condition see [Chapter 9.2](#).

### 9.7.2 Diagnosis of Half Bridges *OUT21* to *OUT24*

For the half bridge outputs various diagnosis function are implemented. For short to battery and short to GND in on diagnosis the protection function overcurrent is used (diagnosis bits **O210C** to **O240C** in diagnosis register **BriDiag1**). Overtemperature is signaled with the diagnosis bits **B10T** and **B20T** in diagnosis register **BriDiag1**. For open load and short to GND (SCG) in off a special circuit is implemented. The diagnosis bits **O21DIA** to **O24DIA** in diagnosis register **BriDiag0** are set according the setup of the channels and according the priority shown in [Table 30](#).



**Figure 34** Open Load and Short to GND/Battery Detection Circuit for Half Bridge Configuration (Low- or High-Side Load)

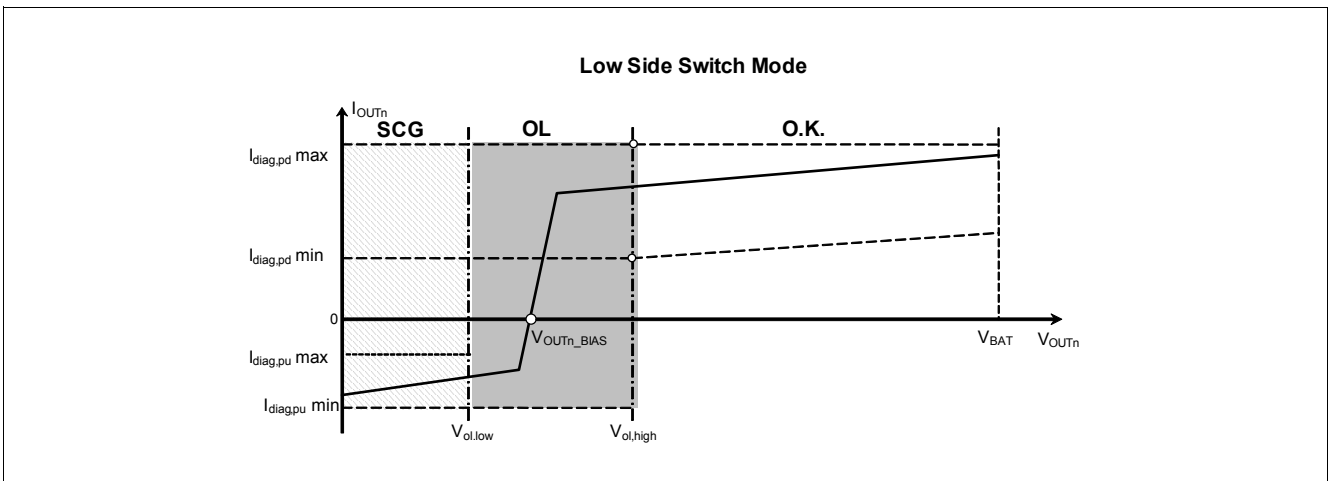


**Figure 35** Open Load and Short to GND/Battery Detection Circuit for Full Bridge Configuration

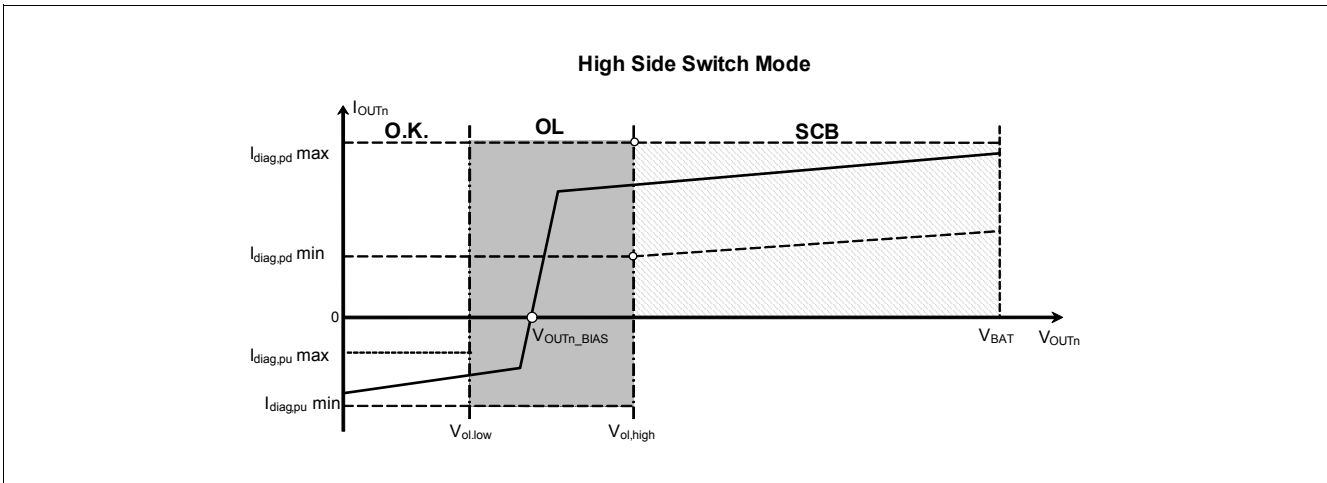
In **Figure 36** and **Figure 37** the behavior of the output current as a function of the output voltage in the different configurations are shown.

The detection in off for open load is the same for both settings but for the short detection there is a difference for low-side and high-side switch mode.

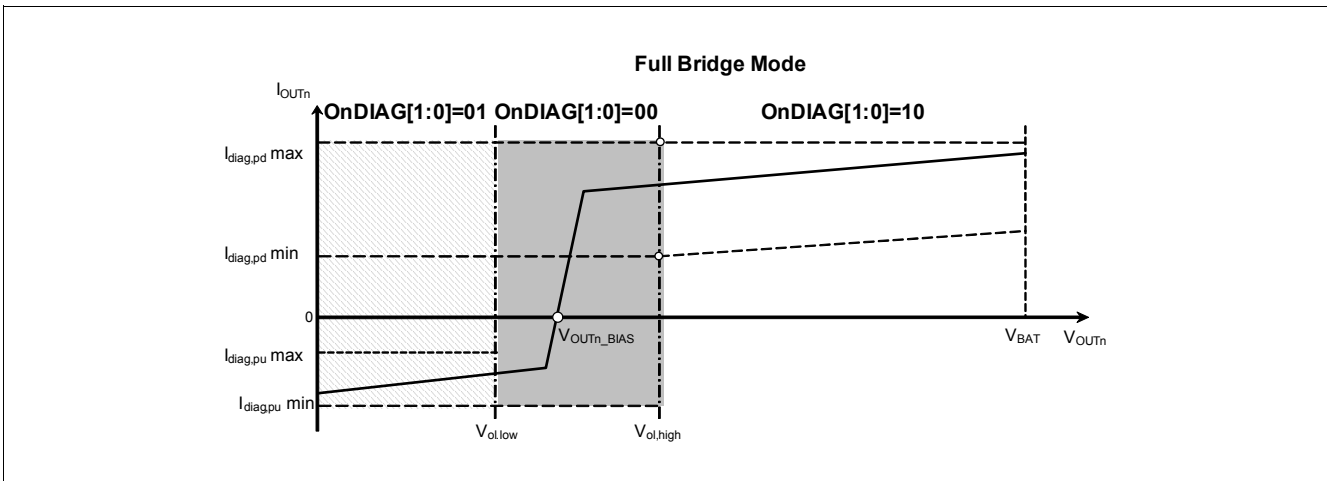
- High-side switch mode: short to battery detection in off
- Low-side switch mode: short to GND detection in off



**Figure 36** Output Behavior in Off for Low-Side Switch Configuration with Open Load and Short to GND Detection



**Figure 37 Output Behavior in Off for High-Side Switch Configuration with Open Load and Short to Battery Detection**



**Figure 38 Output Behavior in Off for Full Bridge Mode Configuration**

The detection is active if the high-side and the low-side switch are off and the diagnosis activation timer  $t_{br,diag,act}$  starts counting. For activation of the open load in off detection in active freewheeling configuration the half bridge must be disabled by setting the bits **021E** to **024E** of configuration register **OEConfig2** to “low”, for passive freewheeling a normal off signal (*IN9* to *IN12* or **0210N** to **0240N** in control register **Cont2** is set to “low”) is sufficient. For full bridge mode both half bridges must be off or disabled regarding the setting of the half bridge. After the **Bridge Diagnosis Activation Time**  $t_{br,diag,act}$  the output of the detection circuit is stored in the diagnosis register **BriDiag0** according the priority shown in **Table 30**. After activation of the open load in off detection a filter time  $t_{br,diag,f}$  to suppress disturbances is implemented. The diagnosis register bits are set after the specified filter times. With the readout of the diagnosis register the content is updated to the actual diagnosis.

In **Table 30** the definition of the diagnosis bits for single switch usage is defined, in **Table 31** the definition for full bridge mode.

*Note: especially for full bridge mode it is recommended to read out the diagnosis register twice due to transition states and possible misleading diagnosis register entries*



**Table 30 Description of Diagnosis Information Single Switch Usage**

OnDIAG[1:0] <sup>1)</sup>	Priority (1 = highest priority)	High-Side Switch Mode	Low-Side Switch Mode
00	3	no failure	no failure
01	2	open load in off	n.a.
10	2	n.a.	open load in off
11	1	short circuit to battery in off	short circuit to ground in off

1) n from 21 to 24

*Note: For high-side switch mode (low-side load) after start up there will be a short to ground detection before the output is configured to high-side load and the diagnosis bits are set to “11”. This detection is not right and it is recommended to read out the diagnosis registers twice after start up to avoid wrong diagnosis information.*

**Table 31 Description of Diagnosis Information in Full Bridge Mode**

OnDIAG[1:0] <sup>1)</sup>	OmDIAG[1:0] <sup>1)</sup>	Full Bridge Mode
00	00	no failure

**Single Failure**

00	01	open load in off (or double fault open load and short to GND at <i>OUT22 /OUT24</i> )
10	10	short circuit to battery in off
01	01	short circuit to ground in off (or double fault open load and short to GND at <i>OUT21 /OUT23</i> )

**Double Failure**

00	10	open load and short circuit to bat at <i>OUT22 /OUT24</i> in off
01	10	short circuit to ground at <i>OUT21 /OUT23</i> and short circuit to battery at <i>OUT22 /OUT24</i> in off
10	01	short circuit to battery at <i>OUT21 /OUT23</i> and short circuit to ground or open load at <i>OUT22 /OUT24</i> in off

**Remaining Combinations**

10	00	not existing or transition states after switch off
xx	11	
11	xx	
01	00	

1) n = 21 and m=22 or n=23 and m=24

### 9.7.3 Electrical Characteristics Half Bridges

**Table 32 Electrical Characteristics Half Bridges**

$V_S = 13.5\text{ V}$ ,  $V_{SV} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to GND, positive current flowing into pin, (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
<b>OUT21...24, n = 21 to 24</b>							
Operation Current	$I_{OUTn}$	–	–	0.6	A		P_9.1
Overcurrent Switch Off Threshold	$I_{OUTn,oc}$	0.6	–	1.5	A		P_9.2
Overcurrent Switch Off Filter Time	$t_{oc,f}$	0.5	–	2	$\mu\text{s}$		P_9.3
On Resistance	$R_{OUTn,on}$		–	2.4	$\Omega$	$I_{OUTn} = 0.3\text{ A}$	P_9.4
OUT21 On Resistance at Low Battery Voltage, low temperature	$R_{OUT21,on,l,LT}$		–	2.4	$\Omega$	$I_{OUTn} = 0.1\text{ A}$ , $V_{BAT} = 4.5\text{ V}$ $T_j < 100^\circ\text{C}$	P_9.5
OUT21 On Resistance at Low Battery Voltage, high temperature	$R_{OUT21,on,l,HT}$		–	2.6	$\Omega$	$I_{OUTn} = 0.1\text{ A}$ , $V_{BAT} = 4.5\text{ V}$ $T_j > 100^\circ\text{C}$	P_9.6
Leakage Current, low-side	$I_{OUTn,l,low}$	–	–	20 <sup>1)</sup>	$\mu\text{A}$	$V_{OUTn} = 13.5\text{ V}$	P_9.7
Leakage Current, high-side	$I_{OUTn,l,high}$	-20 <sup>1)</sup>	–	–	$\mu\text{A}$	$V_{OUTn} = 0\text{ V}$	P_9.8
Turn On Delay Time <sup>2)</sup>	$t_{d,on}$	–	–	10	$\mu\text{s}$	$I_{OUTn} = 0.3\text{ A}$ , resistive load	P_9.9
Turn Off Delay Time <sup>2)</sup>	$t_{d,off}$	0.1	–	10	$\mu\text{s}$	$I_{OUTn} = 0.3\text{ A}$ , resistive load	P_9.10
Switch On Time <sup>2)</sup>	$t_{s,on}$	0.9	–	2.5	$\mu\text{s}$	$I_{OUTn} = 0.3\text{ A}$ , resistive load	P_9.11
Switch Off Time <sup>2)</sup>	$t_{s,off}$	0.9	–	2.5	$\mu\text{s}$	$I_{OUTn} = 0.3\text{ A}$ , resistive load	P_9.12

**Diagnosis OUT21 to 24**

Overtemperature Switch Off Threshold	$T_{OUTn,ot}$	150	–	200	$^\circ\text{C}$	<sup>3)</sup>	P_9.13
Overtemperature Hysteresis	$T_{OUTn,ot,hy s}$	–	10	–	$^\circ\text{C}$	<sup>3)</sup>	P_9.14
Open Load in Off Detection Threshold High Limit	$V_{ol,high}$	0.9*V5V -0.2	0.9* V5V	0.9*V5V +0.2	V		P_9.15
Open Load in Off Detection Threshold Low Limit	$V_{ol,low}$	0.5*V5V -0.2	0.5* V5V	0.5*V5V +0.2	V		P_9.16
Diagnosis Pull Up Current	$I_{diag,pu}$	-980	–	-220	$\mu\text{A}$		P_9.17
Diagnosis Pull Down Current	$I_{diag,pd}$	150	–	300	$\mu\text{A}$		P_9.18
Bridge Diagnosis Activation Time	$t_{br,diag,act}$	60	–	135	$\mu\text{s}$		P_9.19
Bridge Diagnosis Filter Time	$t_{br,diag,f}$	0.5	–	2	$\mu\text{s}$		P_9.20

1) In operation leakage current covered by open load current

- 2) see [Figure 31](#) for timing definition
- 3) not subject to production test, specified by design

## 9.8 Push Pull Stages *OUT8* to *OUT13* and *DFB8* to *DFB13*

These 5 V push pull stages are designed for driving on-board MOSFETs. The outputs are fully protected and various diagnosis functions are implemented.

They are controlled and enabled like all power stages according the description in [Chapter 9.1](#) and [Chapter 9.2](#). In off (“0” in control register or “low” at the configured direct drive input pin) the low-side transistor of the push/pull stage is on and forces a “low voltage level at the pin.

### 9.8.1 Protection of *OUT8* to *OUT13*

There are functions implemented to detect short to battery at the external MOSFET and to protect the driver outputs.

For the short to battery detection feedback pins *DFB8* to *DFB13* are implemented to sense the voltage at the drain of the external MOSFET. The short to battery detection in on is done by comparing the voltage level of the drain feedback pins with the short to bat detection threshold.

A short is detected after the “[Short to Battery Detection Filter Time](#)”. In case of short to battery the output is switched off and the corresponding diagnosis bits in the diagnosis register [OutDiag1](#) to [OutDiag3](#) are set according the priority shown in [Table 33](#). There are four different thresholds, “[Short to Battery Detection Threshold in On 1](#)” to “[Short to Battery Detection Threshold in On 4](#)”, implemented so that the detection threshold can be adapted to the used MOSFET. The diagnosis of the push pull stages can be set in three groups. The configuration is done with the bits [PP0D](#) to [PP2D](#) in the configuration register [OutConfig2](#) and [OutConfig3](#).

The protection of the driver output pins is done by comparing the output voltage on the pins *OUT8* to *OUT13* with the “[Overvoltage Detection Threshold](#)”. An overvoltage (e.g. short to battery) is detected after the “[Overvoltage Diagnosis Filter Time](#)” and the corresponding diagnosis bits in the diagnosis register [PPOVDiag](#) is set. In case of overvoltage high and low-side transistors of the push pull driver are switched off (high ohmic state).

### 9.8.2 Diagnosis of *OUT8* to *OUT13*

For the push pull stages *OUT8* to *OUT13* various diagnosis functions for the external MOSFETs are implemented. The open load, short to ground in off and short to battery in on detection is done via the drain feedback *DFB8* to *DFB13*. The diagnosis pull down current of the open load/short to ground in off detection can be switched off (see configuration register [OutConfig2](#)). With deactivated pull down current open load in off detection is not active and the diagnosis information of OnDIAG[1:0] = 10B will never occur. With deactivated pull down current the short to ground detection is active.

In [Figure 39](#) the behavior of the output current as a function of the output voltage is shown.

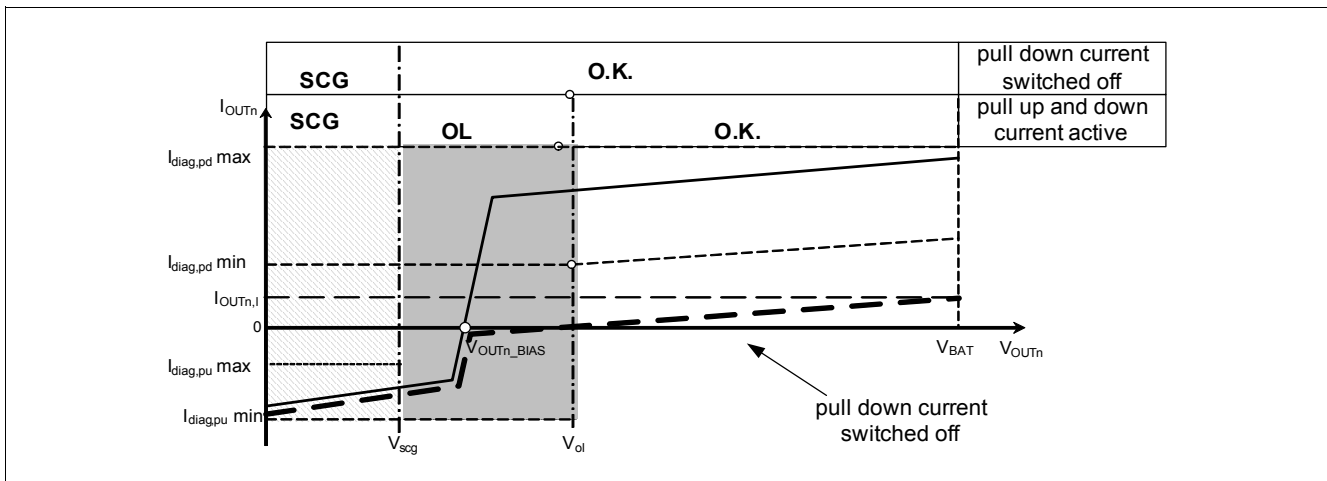


Figure 39 Output behavior in off with open load and short to GND detection of DFB8 to DFB13

Whenever the push pull stages are off the open load/short to GND detection circuit is enabled. To suppress disturbances the output of the detection circuit is stored in the diagnosis register **OutDiag1** to **OutDiag3** after the **Diagnosis Filter Time for Open Load and Short to GND in Off Detection**  $t_{diag,f}$  and according to the priority shown in **Table 33**. With the readout of the diagnosis register the content is updated to the actual diagnosis.

Table 33 Description of Diagnosis Information (DFB8 to DFB13)

OnDIAG[1:0]	Priority (1 = highest priority)	Description
00	4	no failure
01	1	short circuit to battery
10	2	open load in off <sup>1)</sup>
11	3	short circuit to ground in off

1) no open load in off detection with deactivated pull down current

## 9.9 Electrical Characteristics Push Pull Stages OUT8 to OUT13

Table 34 Electrical Characteristics Push Pull Stages OUT8 to OUT13

Stages on or off,  $V_S = 13.5\text{ V}$ ,  $V_{VSV} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to GND, positive current flowing into pin, (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
<b>OUT8...13, n = 8 to 13</b>							
High Level Output Voltage	$V_{OUTn,h}$	4	-	5.5	V	$I_{OUTn} = -5\text{ mA}$	P_9.8.1
Low Level Output Voltage	$V_{OUTn,l}$	-	-	0.6	V	$I_{OUTn} = 5\text{ mA}$	P_9.8.2
Pull up current	$I_{OUTn,pu}$	-	-	-20	mA	$V_{OUTn} = 0\text{ V}$ , OUTn on	P_9.8.3
Pull down current	$I_{OUTn,pd}$	20	-	-	mA	$V_{OUTn} = 5\text{ V}$ , OUTn off	P_9.8.4

**Table 34 Electrical Characteristics Push Pull Stages *OUT8* to *OUT13* (cont'd)**

Stages on or off,  $V_S = 13.5\text{ V}$ ,  $V_{VSV} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to GND, positive current flowing into pin, (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
Overvoltage Detection Threshold	$V_{OUTn,ov,th}$	5.5	–	7.7	V		P_9.8.5
Overvoltage Diagnosis Filter Time	$t_{OUTn,ov,f}$	5	–	10	$\mu\text{s}$		P_9.8.6

**Diagnosis *DFB8* to *DFB13***

Short to Battery Detection Threshold in On 1	$V_{DFBn,sb,1}$	90	125	150	mV	referred to <i>PGND</i>	P_9.8.7
Short to Battery Detection Threshold in On 2	$V_{DFBn,sb,2}$	180	225	250	mV	referred to <i>PGND</i>	P_9.8.8
Short to Battery Detection Threshold in On 3	$V_{DFBn,sb,3}$	350	400	450	mV	referred to <i>PGND</i>	P_9.8.9
Short to Battery Detection Threshold in On 4	$V_{DFBn,sb,4}$	0.7	0.8	0.9	V	referred to <i>PGND</i>	P_9.8.10
Short to Battery Detection Filter Time	$V_{DFBn,sb,fl}$	10	–	15	$\mu\text{s}$		P_9.8.11
Open Load in Off Detection Threshold	$V_{ol}$	$5V-0.2$	$5V$	$5V+0.2$	V		P_9.8.12
Short to GND in Off Detection Threshold	$V_{scg}$	$0.5^*V$ $5V-0.2$	$0.5^*$ $5V$	$0.5^*V$ $5V+0.2$	V		P_9.8.13
Diagnosis Pull Down Current in Off	$I_{diag,pd}$	220	–	600	$\mu\text{A}$	$V_{DFBn} = 13.5\text{ V}$	P_9.8.14
Diagnosis Pull Up Current in Off	$I_{diag,pu}$	-300	–	-100	$\mu\text{A}$	$V_{DFBn} = 0\text{ V}$	P_9.8.15
Diagnosis Filter Time for Open Load and Short to GND in Off Detection	$t_{diag,f,off}$	60	–	135	$\mu\text{s}$		P_9.8.16
Pull Down Current in On	$I_{diag,pd,on}$	–	–	1.8	$\mu\text{A}$	$V_{DFBn} = 5\text{ V}$	P_9.8.17

**9.10 Push Pull Stages *IGN1* to *IGN4***

The *IGN1* to *IGN4* are 5 V push pull stages for on- and off-board ignition power stages (e.g. with IGBTs, darlington transistors). For off board ignition power stages the outputs *IGN1* to *IGN4* are equipped with a back supply suppression (in case of a short circuit from *IGN1* to *IGN4* to battery there is no parasitic current flow back to 5 V).

They are controlled and enabled like all power stages according the description in [Chapter 9.1](#) and [Chapter 9.2](#). Additionally a “high” at the pin *IGNEN* is needed to enable the outputs. In off (“0” in control register or “low” at the configured direct drive input pin or *IGNEN* is “low”) the low-side transistor of the push/pull stage is on and forces a “low voltage level at the pin.

The outputs are fully protected and various diagnosis functions are implemented.

**9.10.1 Protection of *IGN1* to *IGN4***

The protection of the outputs is done by detecting short to battery and short to ground. This is done by comparing the output voltage level with the “[Short to Battery Detection Threshold](#) and [Short to Ground](#)

**Detection Threshold**". To suppress disturbances the output signal of the short to GND and short to battery detection circuit is stored in the diagnosis register **IgnDiag** after the "**Diagnosis Filter Time for Short to GND and Battery Detection**"  $t_{diag,f,sc}$  and according the priority shown in **Table 35**.

During detected short to GND the output is switched off (low-side transistor of push/pull stage is on), during detected short to battery the output is high ohmic (tristate).

The short to battery detection is always active. The short to ground detection is enabled with the on signal of the output stage.

Additionally an overtemperature protection is implemented. There is one common sensor for *IGN1* and *IGN2* and one for *IGN3* and *IGN4*.

### 9.10.2 Diagnosis of *IGN1* to *IGN4*

An open load detection during the switch on phase is implemented and can be enabled with the bit **IOLA** in the configuration register **IGNConfig**. In **Figure 40** the detection principle is shown. When the open load detection in on is enabled, first the output is pulled up by a defined current, which is set by the bits **IOLI** in the configuration register **IGNConfig**.

The output voltage, which is passed to the detection circuit, is filtered ("**Diagnosis Filter Time for Open Load Detection**") to suppress disturbances. After the open load time ("**Open Load Time 1**" to "**Open Load Time 4**" selected in configuration register **IGNConfig** bits **IOLT**) the filtered output is compared with the **Open Load Detection Threshold Vol**. The diagnosis register **IgnDiag** is set if the filtered output is higher than the **Open Load Detection Threshold** and the output is fully switched on.

The failures are stored in the diagnosis register according the priority shown in **Table 35** with "1" is the highest priority. With the readout of the diagnosis register **IgnDiag** the content is updated to the actual diagnosis.

**Table 35 Description of Diagnosis Information (*IGN1* to *IGN4*)**

<b>IGNnDIAG[1:0]</b>	<b>Priority (1 = highest priority)</b>	<b>Description</b>
00	4	no failure
01	1	short circuit to battery or overtemperature
10	2	open load
11	3	short circuit to ground in on

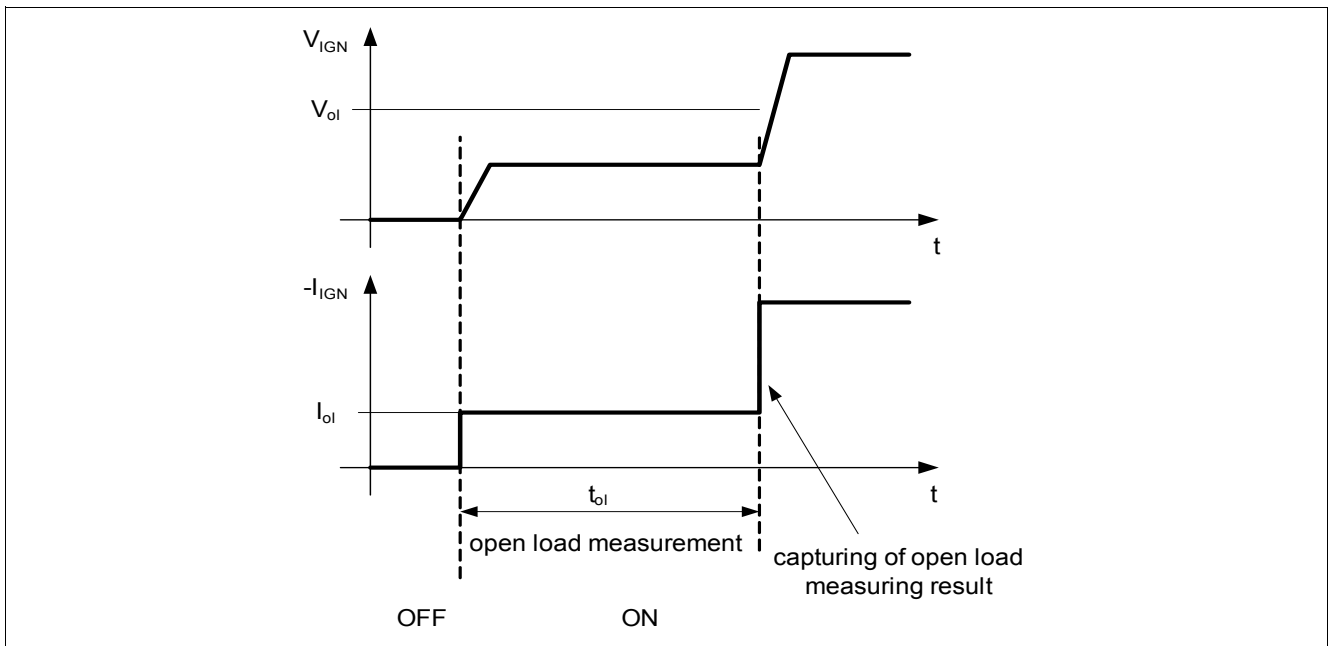


Figure 40 Ignition Output Open Load Detection

### 9.11 Electrical Characteristics Push Pull Stages *IGN1* to *IGN4*

Table 36 Electrical Characteristics Push Pull Stages

Stages on or off,  $V_S = 13.5\text{ V}$ ,  $V_{V5V} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to GND, positive current flowing into pin, (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
<b>IGN1...4, n = 1 to 4</b>							
High Level Output Voltage	$V_{IGNn,h}$	4.35	–	–	V	$I_{IGNn} = -15\text{ mA}$ ,	P_9.9.1
Low Level Output Voltage	$V_{IGNn,l}$	–	–	0.6	V	$I_{IGNn} = 5\text{ mA}$	P_9.9.2
Pull up current	$I_{IGNn,pu}$	–	–	-20	mA	$V_{IGNn} = 0\text{ V}$ , IGNn on	P_9.9.3
Pull down current	$I_{IGNn,pd}$	20	–	–	mA	$V_{IGNn} = 5\text{ V}$ , IGNn off	P_9.9.4
Leakage current	$I_{L\_IGNn}$	–	–	120	$\mu\text{A}$	$V_{IGNn} = 13.5\text{ V}$	P_9.9.5
Leakage current to V5V	$I_{L\_IGNn,V5V}$	–	–	1	$\mu\text{A}$	$V_{IGNn} = 13.5\text{ V}$	P_9.9.26
Overtemperature Switch Off Threshold	$T_{IGNx,ot}$	150	–	200	$^\circ\text{C}$	<sup>1)</sup>	P_9.9.6
Overtemperature Hysteresis	$T_{IGNx,ot,hys}$		10		$^\circ\text{C}$	<sup>1)</sup>	P_9.9.7
<b>Diagnosis <i>IGN1</i> to <i>IGN4</i></b>							
Short to Battery Detection Threshold	$V_{IGNn,scb}$	6.4	–	7.5	V		P_9.9.8
Short to Ground Detection Threshold	$V_{scg}$	1.6	–	2.3	V		P_9.9.9
Diagnosis Filter Time for Short to GND and Battery Detection	$t_{diag,f,sc}$	5	–	10	$\mu\text{s}$		P_9.9.10



**Table 36 Electrical Characteristics Push Pull Stages (cont'd)**

Stages on or off,  $V_S = 13.5\text{ V}$ ,  $V_{VSV} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to GND, positive current flowing into pin, (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
Open Load Detection Threshold	$V_{ol}$	4	–	4.5	V		P_9.9.11
Open Load Switch On Current 1	$I_{olf,1}$	-120	-100	-40	$\mu\text{A}$		P_9.9.12
Open Load Switch On Current 2	$I_{olf,2}$	-500	-400	-300	$\mu\text{A}$		P_9.9.13
Open Load Switch On Current 3	$I_{olf,3}$	-1.2	-1	-0.4	mA		P_9.9.14
Open Load Switch On Current 4	$I_{olf,4}$	-5	-4	-2.5	mA		P_9.9.15
Open Load Time 1	$t_{ol,1}$	50	60	70	$\mu\text{s}$		P_9.9.16
Open Load Time 2	$t_{ol,2}$	210	250	290	$\mu\text{s}$		P_9.9.17
Open Load Time 3	$t_{ol,3}$	450	510	570	$\mu\text{s}$		P_9.9.18
Open Load Time 4	$t_{ol,4}$	690	775	860	$\mu\text{s}$		P_9.9.19
Diagnosis Filter Time for Open Load Detection	$t_{diag,f,olf}$	6	10	14	$\mu\text{s}$		P_9.9.20

**Direct Drive Inputs *IGNEN***

Low Level Input Voltage	$V_{IN,l}$	-0.3	–	0.9	V		P_9.9.21
High Level Input Voltage	$V_{IN,h}$	2	–	$V_{VDDIO}$	V		P_9.9.22
Input Voltage Hysteresis	$V_{IN,hys}$	50	200	–	mV		P_9.9.23
Pull Down Current	$I_{IN,pd}$	25	–	100	$\mu\text{A}$	$V_{IN} = V_{VDDIO}$	P_9.9.24
Pull Down Current	$I_{IN,pd}$	2.4	–	–	$\mu\text{A}$	$V_{IN} = 0.6\text{ V}$	P_9.9.25

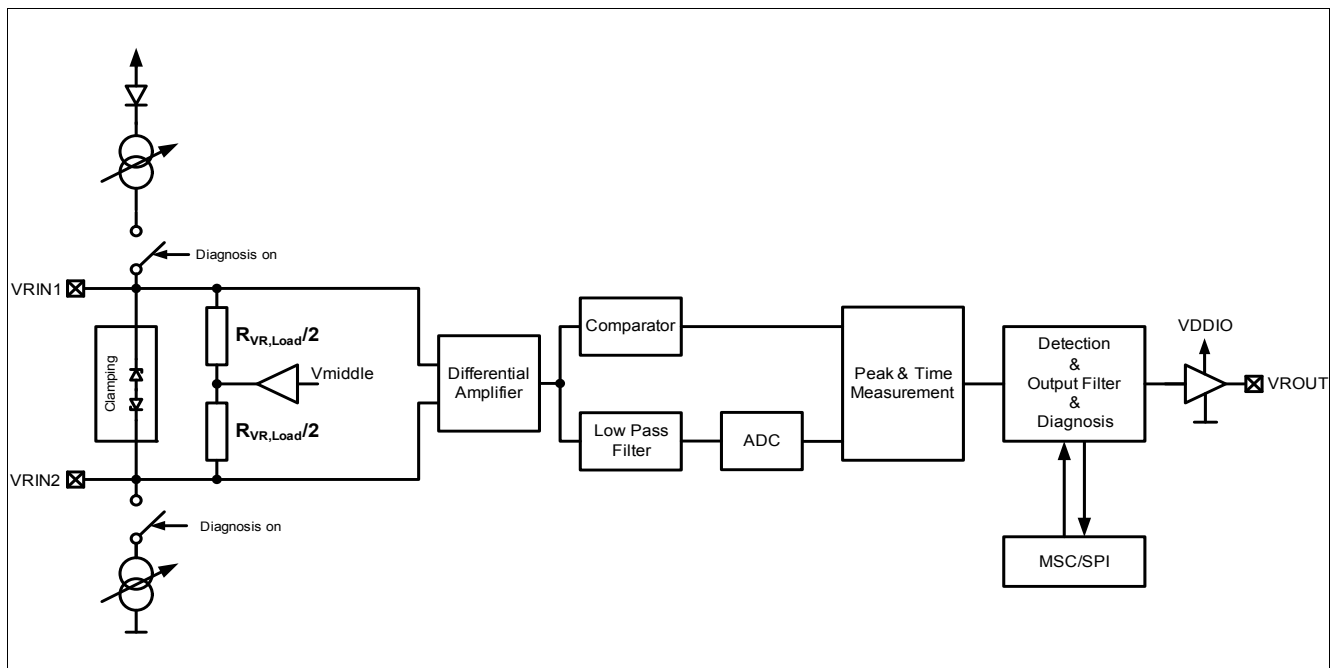
1) Parameter is not subject of production test, specified by design

## 10 VR and Hall Sensor Interface

The variable reluctance (VR) sensor interface converts an output signal of a VR sensor into a push-pull logic level signal suited for microcontroller input ports. To achieve the best accuracy for the positive and the negative edge of the *VR<sub>OUT</sub>* signal the switching point is the zero crossing. For robustness against disturbances the next zero crossing is enabled only if a signal peak (minimum or maximum of the signal) is detected. The amplitude of the VR sensor signal is limited by an internal clamping circuit to avoid damage of the device due to overvoltage caused by the VR sensor signal.

There are three operation modes for VR sensor applications and one Hall sensor mode implemented. The manual VR sensor mode with static setup of the detection parameter under control of the microcontroller via MSC/SPI and an auto mode with an adaptive algorithm to ensure best detection performance. The semi auto mode is less accurate than the auto mode.

The diagnosis VR sensor interface setup could be done by measuring the voltage between the two input pins during diagnosis mode. Additionally three diagnosis bits for short to battery, short to GND and open load (directly at the pins) are available.



**Figure 41 VR Sensor Interface Block diagram**

### 10.1 Signal Detection

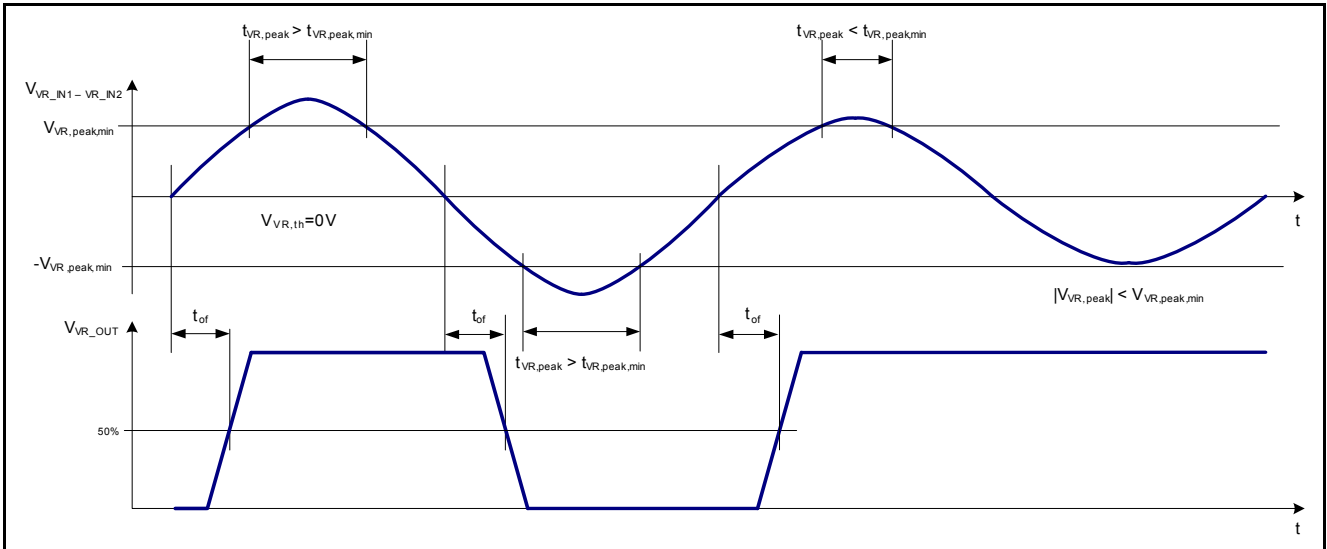
The signal detection for Hall sensor mode is a comparator with the switching threshold **VVRIN1,th, hall** and the hysteresis **VVRIN1,hys, hall**. The detection of the VR signal consist of the zero crossing detection, peak detection and the output filter. At the input there is a clamping circuit between the pins *VRIN1* and *VRIN2* suited to clamp the maximum current of VR sensors.

The zero crossing detection ensures that the influence of the input signal slope is eliminated for both edges. To avoid disturbances due to the floating input signal a middle voltage is applied with the integrated load resistance. The clamping circuit between the pins *VRIN1* and *VRIN2* clamps the input voltage in both direction to protect the input structures. The clamping is suited for VR sensors with a maximum output current of **ΔIVR,clamp** (see **Table 37**).

The peak detection is done by measuring the voltage difference by the analog to digital converter and the detection of the slope of the input signal. If the gradient of the slope changes the sign the next zero crossing detection is enabled. The detection of the sign is done by comparing the absolute value of the signal with the

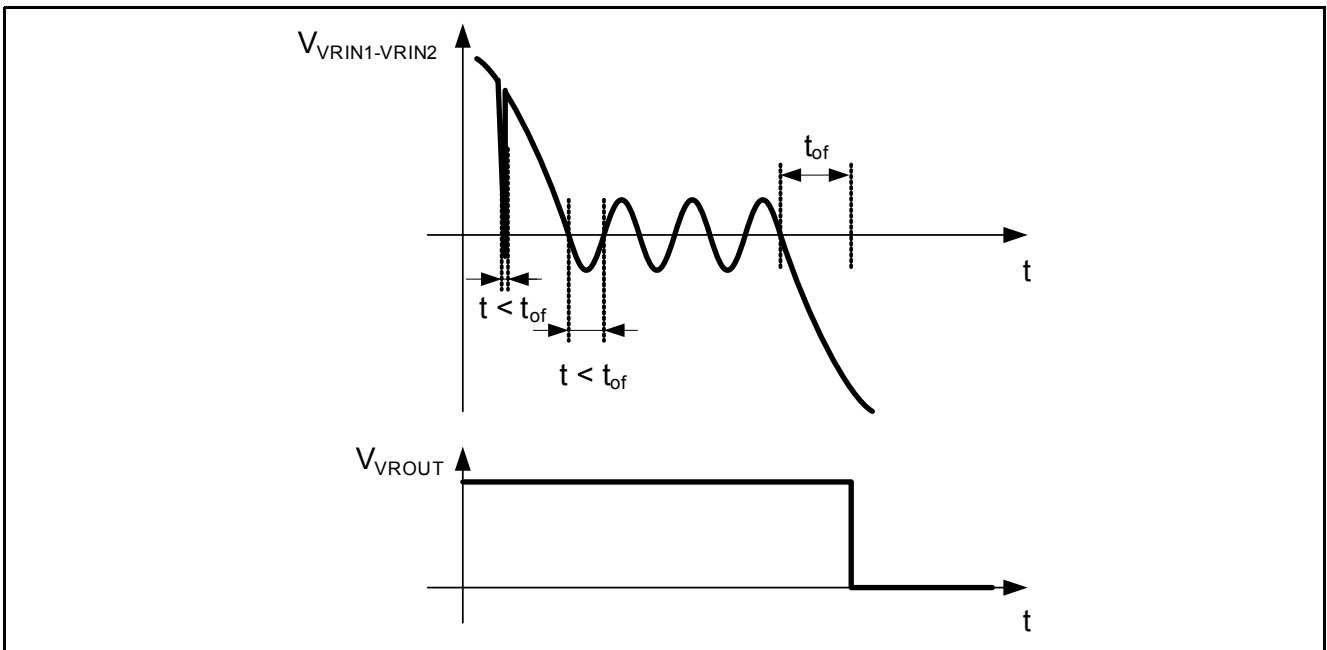
**VR and Hall Sensor Interface**

peak detection threshold (**VVR,peak,min,1** to **VVR,peak,min,4** according setup). A sign change is only valid if the absolute value of the signal is larger than peak detection threshold (**VVR,peak,min,1** to **VVR,peak,min,4** according setup) for a time longer than the peak detection time **tVR,peak,min,1** to **tVR,peak,min,2** according setup (see **Figure 42**).



**Figure 42** Timing Characteristics of the VR Sensor Interface

The output filter is implemented for all operation modes to suppress disturbances with high frequencies. The function is shown in **Figure 43**. The output signal **VROUT** is filtered with the time **tof,1**. The output signal of the internal zero crossing detection must be stable for a time longer than **tof,1**.



**Figure 43** Output Filter Behavior

Following parameters could be set by MSC/SPI communication:

- peak detection threshold **VVR,peak,min,1** to **VVR,peak,min,4** with the bits **VRSPV** in the configuration register **VRSCConfig**

## VR and Hall Sensor Interface

- peak detection time **tVR,peak,min,1** to **tVR,peak,min,2** with the bit **VRSPT** in the configuration register **VRSConfig0**
- output filter time **tof,1** to **tof,4** with the bits **VRSF** in the configuration register **VRSConfig0**

### 10.2 Detection Modes

The TLE8888-1QK integrates four detection modes:

- auto detection mode for VR sensor signals
- manual detection mode for VR sensor signals
- semi auto detection mode for VR sensor signals
- detection mode for Hall sensor signals

To select the various detection modes the bits **VRSM** in the configuration register **VRSConfig1** must be set.

Auto detection mode for VR sensor signals: In the auto detection mode an algorithm is setting all parameters to the optimal values to achieve the best detection behavior. The peak detection time is set due to the actual speed value, the peak detection threshold is set due to the level of the previous peaks. The output filter time (**tof,1** to **tof,4**) is set by the microcontroller independently to increase the robustness against short disturbances at the inputs. Write access to the registers bits of **VRSPT** and **VRSPV** are ignored in auto detection mode.

Semi auto detection mode for VR sensor signals: The algorithm of the semi auto mode is based on less number of measurement information as the auto detection mode. This leads to a simpler implementation of the detection algorithm. The output filter time (**tof,1** to **tof,4**) is set by the microcontroller independently to increase the robustness against short disturbances at the inputs. Write access to the registers bits of **VRSPT** and **VRSPV** are ignored in semi auto detection mode.

Manual detection mode for VR sensor signals: In the manual detection mode the microcontroller has the full control of all parameters of the detection and the algorithm of the auto detection modes are disabled. The settings are done via the MSC/SPI interface.

Detection mode for Hall sensor signals: For the Hall sensor mode the pin **VRIN2** is forced internally to the switching threshold **VVRIN1,th, hall**. The detection principle is a comparator with hysteresis. Write access to the registers bits of **VRSPT** and **VRSPV** are ignored in the detection mode for Hall sensor signals. The diagnosis is disabled. With this set up the number of external devices is reduced (see **Chapter 17.2**).

*Note: Switching between the different configurations must be avoided with active signals at the inputs VRIN1 and VRIN2.*

### 10.3 Diagnosis for VR Sensor Signal Detection Modes

The TLE8888-1QK integrates three different diagnosis modes for the VR sensor interface:

- short to GND/short to battery diagnosis mode: detection of short to GND or short to battery directly at pins **VRIN1** and **VRIN2**
- open load diagnosis mode: detection of open load directly at pins **VRIN1** and **VRIN2**
- ADC measurement mode: measurement of the voltage between the pins **VRIN1** and **VRIN2**

The modes are defined in the configuration register **VRSConfig1** with the bits **VRSDIAGM**.

The diagnosis of the VR sensor is done by activating the diagnosis mode with the bits **VRSDIAGM** in the configuration register **VRSConfig1** and starting diagnosis measurement with the bit **VDIAGS** in the command register **Cmd0**. With the activation of the VRS diagnosis mode at **VRIN1** a pull up current source to the internal supply and at **VRIN2** a pull down current source is applied (current configuration with bits **VRSI\_SC** for short to GND/short to battery diagnosis mode, **VRSI\_OL** for open load diagnosis mode and **VRSI\_ADC** for ADC

## **VR and Hall Sensor Interface**

measurement mode in the configuration registers **VRSConfig1** and **VRSConfig2**). To avoid bad influence of the time constants of the external circuitry the timing of the measurement is controlled by the microcontroller. The sequence is shown in **Figure 44**.

The end of the diagnosis procedure triggered by the start command is signaled by the correspondent data valid bits **VRSDV\_SC** (short to GND and short to battery diagnosis mode), **VRSDV\_OL** (open load diagnosis mode) in diagnosis register **VRSDiag0** and **VRSDV\_ADC** (ADC measurement mode) in the diagnosis register **VRSDiag1**.

For the detection thresholds see parameter **Short to GND detection threshold**, **Short to battery detection threshold** and **Open load detection threshold**. The output of the ADC measurement is defined by the parameter **ADC measurement gain** and **ADC measurement offset**.

The result of the diagnosis is available in the diagnosis register **VRSDiag0** with the bits **VRSG** (short to GND detection), **VRSB** (short to battery detection) and **VR SOL** (open load detection directly at the pins). The digital value of the ADC measurement is available in the register **VRSDiag1** with the bits **VRSD**. This ADC value can be used by the microcontroller to define additional error detection conditions different to the defined short to GND, short to battery and open load thresholds.

The data valid bits are reset with start of the corresponding diagnosis or with the readout of the register.

*Note:* In detection mode for Hall sensor signals the diagnosis is deactivated and the values of **VRSDIAGM** and **VR SI\_SC** in the register **VRSConfig1**, **VR SI\_ADC** and **VR SI\_OL** in register **VRSConfig2** and the start command **VDIAGS** in the register **Cmd0** are ignored.

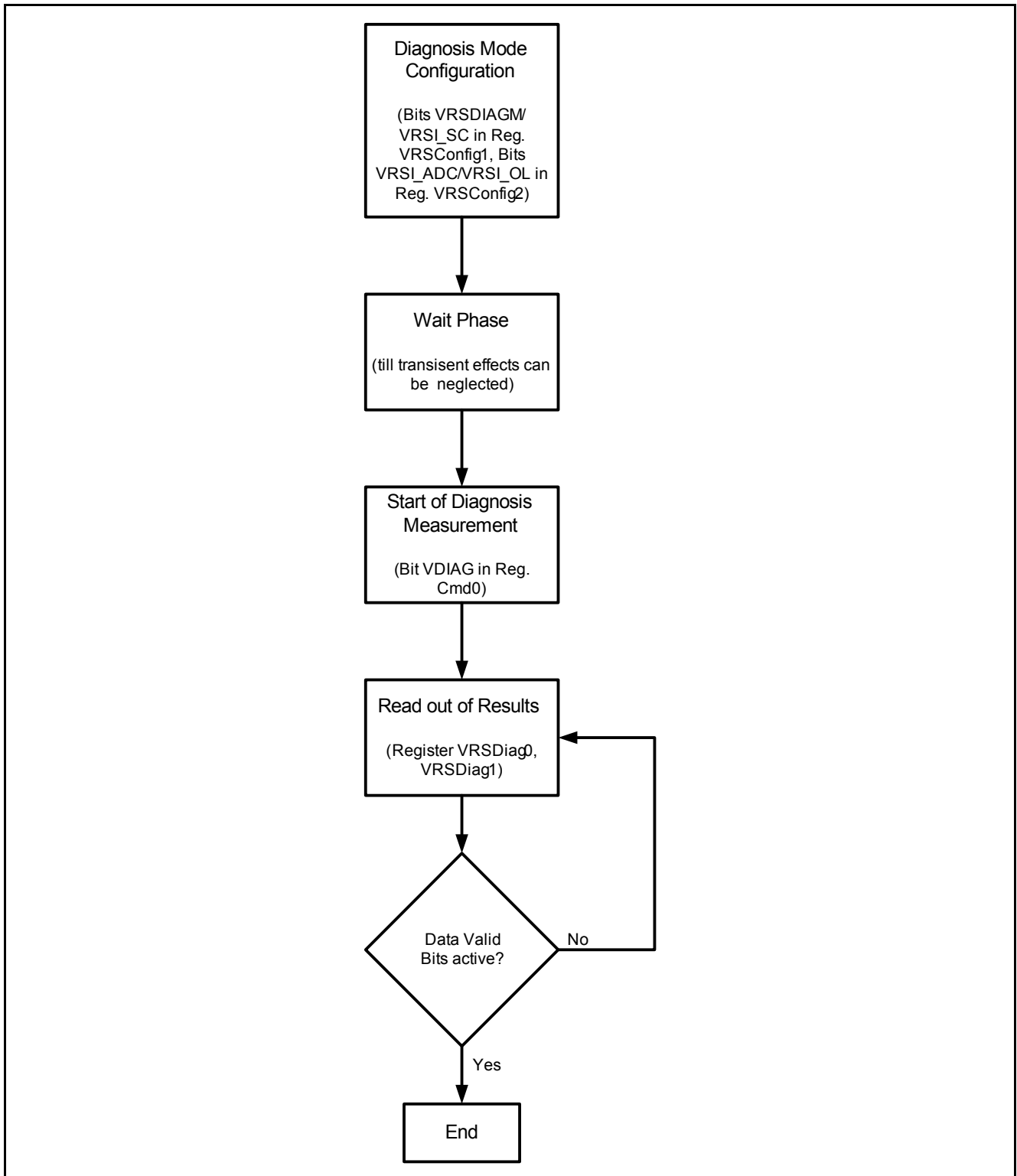


Figure 44 VRS Flow Chart

For the measurement the internal circuits are changed. In [Figure 45](#), [Figure 46](#) and [Figure 47](#) the block diagram of the different setups are shown.

VR and Hall Sensor Interface

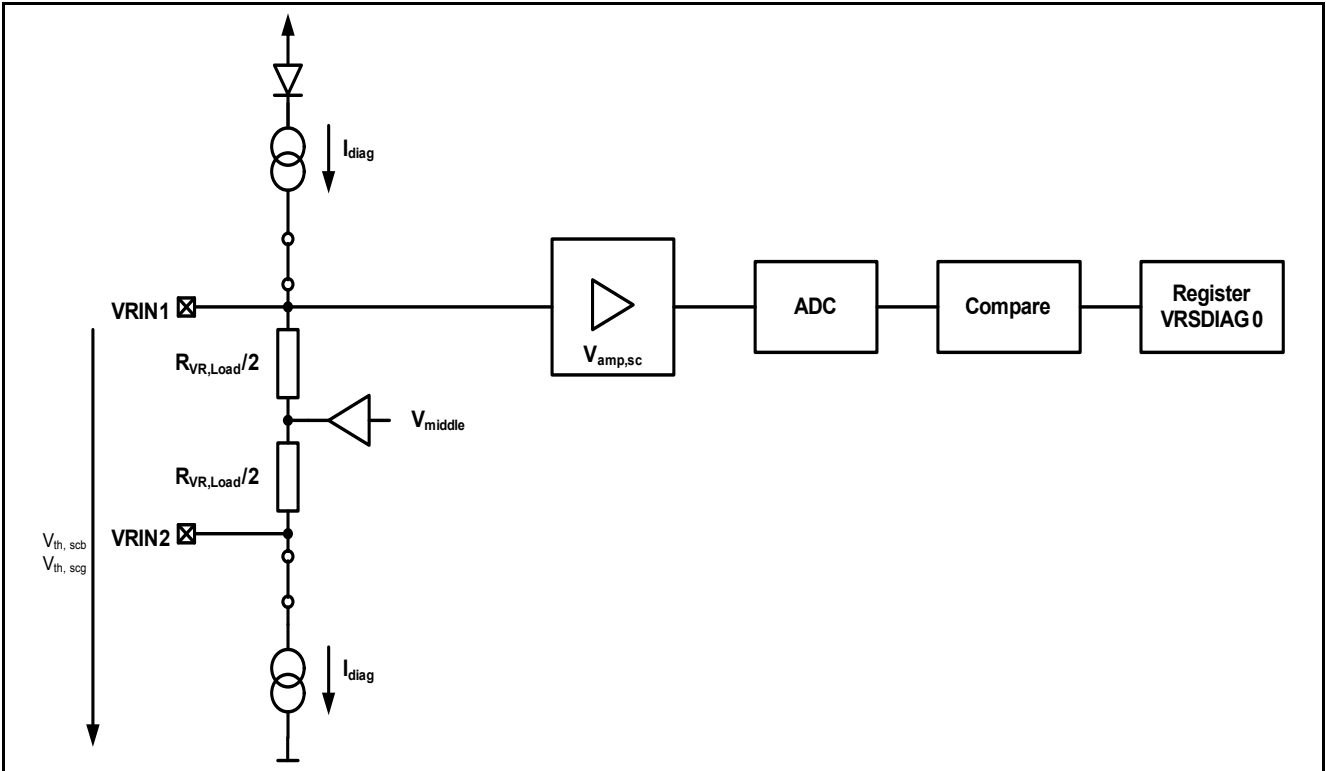


Figure 45 VRS Diagnosis Block Diagram for Short to GND and Short to Battery Measurement

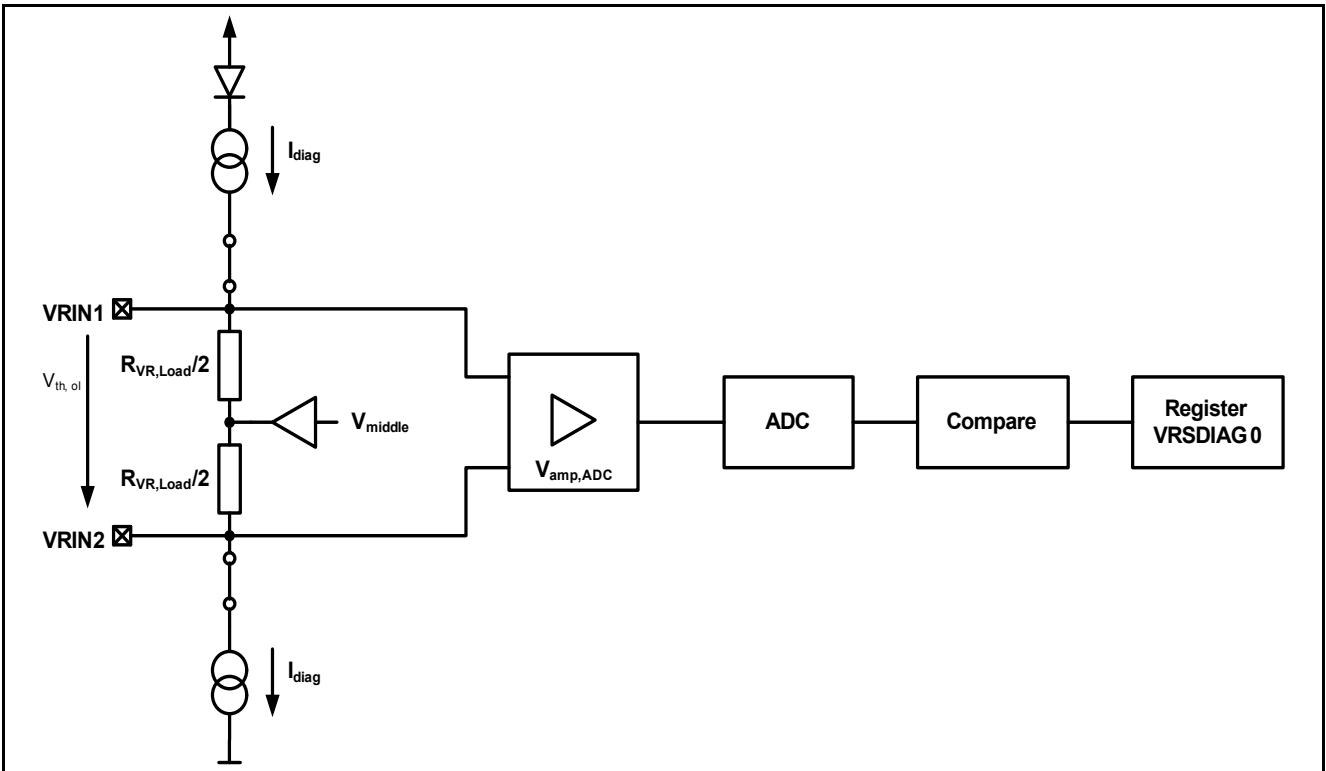


Figure 46 VRS Diagnosis Block Diagram for Open Load Measurement

VR and Hall Sensor Interface

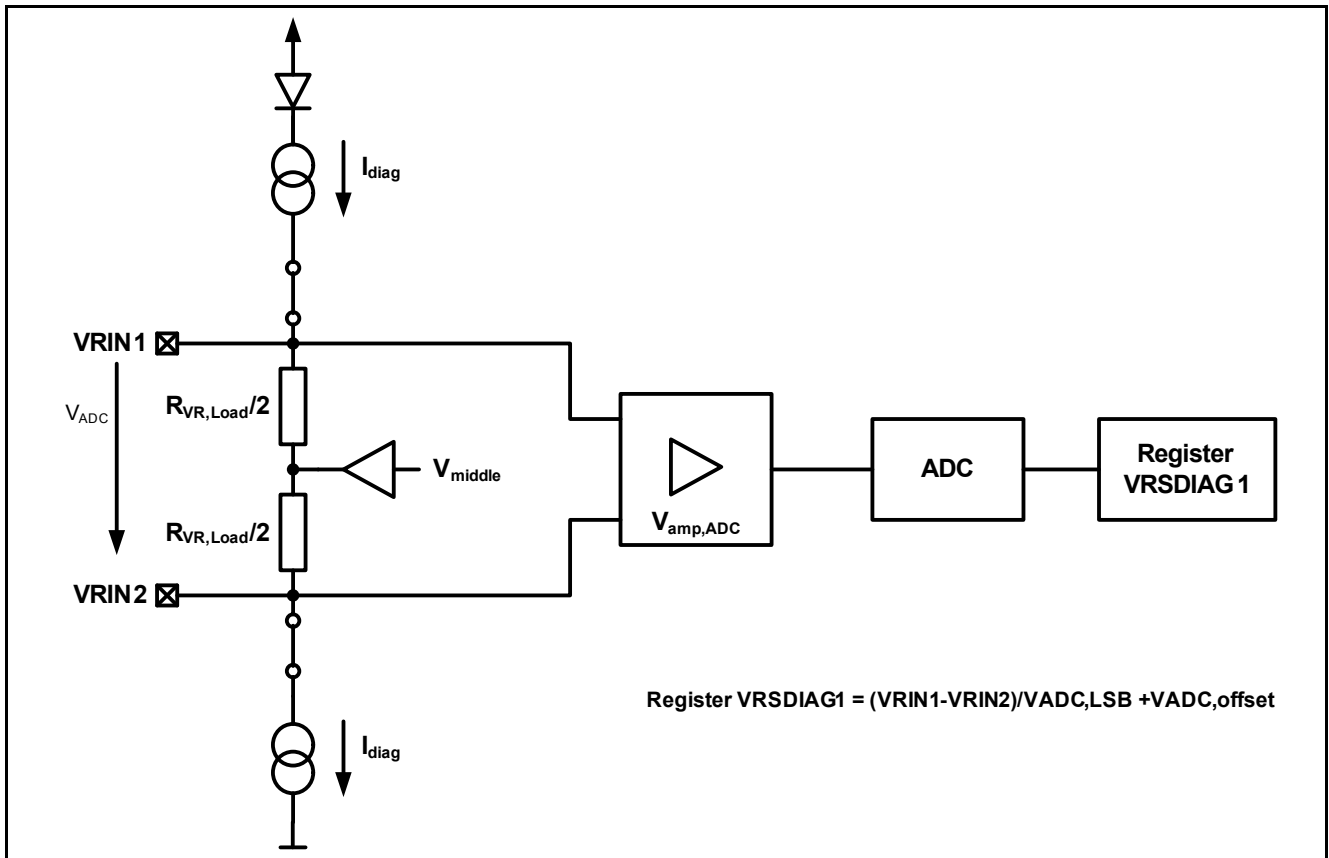


Figure 47 VRS Diagnosis Block Diagram for ADC Measurement



**VR and Hall Sensor Interface**

**10.4 Electrical Characteristics VR Sensor Interface**

**Table 37 Electrical Characteristics: VR Sensor Interface**

$V_S = 13.5\text{ V}$ ,  $V_{VSV} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to ground, positive current flowing into pin (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
<b>Input Characteristics:</b>							
VR Sensor Interface Detection Threshold	$V_{VR,th}$	-30	0	30	mV		P_10.4.1
minimum amplitude for peak detection 1	$V_{VR,peak,min,1}$	-	50	-	mV	reset value	P_10.4.2
minimum amplitude for peak detection 2	$V_{VR,peak,min,2}$	-	150	-	mV		P_10.4.3
minimum amplitude for peak detection 3	$V_{VR,peak,min,3}$	-	350	-	mV		P_10.4.4
minimum amplitude for peak detection 4	$V_{VR,peak,min,4}$	-	550	-	mV		P_10.4.5
minimum time for peak detection 1	$t_{VR,peak,min,1}$	-	10	-	$\mu\text{s}$	reset value 1 kHz sinusoidal signal	P_10.4.6
minimum time for peak detection 2	$t_{VR,peak,min,2}$	-	250	-	$\mu\text{s}$	1 kHz sinusoidal signal	P_10.4.7
VR Sensor Interface Load Resistance	$R_{VR,Load}$	50	75	110	$\text{k}\Omega$		P_10.4.9
VR Sensor Interface Input Clamping Current	$\Delta I_{VR,clamp}$	-	-	50	mA	$\Delta I_{VR,clamp} = (I_{VRIN1} - I_{VRIN2})/2$	P_10.4.18
VR Sensor Interface Input Clamping Voltage	$\Delta V_{VR,clamp}$	2	-	3	V	$\Delta V_{VR,clamp} =  V_{VRIN1} - V_{VRIN2} $ , $I_{VR,clamp} = 50\text{ mA}$	P_10.4.19
Switching threshold voltage at pin <i>VRIN1</i> for Hall Sensor Mode	$V_{VRIN1,th, hall}$	0.9	-	2	V	no load at pin <i>VRIN2</i> <sup>1)</sup>	P_10.4.20
Switching hysteresis pin <i>VRIN1</i> for Hall Sensor Mode	$V_{VRIN1,hys, hall}$	0.35	0.5	-	V	no load at pin <i>VRIN2</i>	P_10.4.10
Middle voltage level normal mode	$V_{middle}$	1.9	2.25	2.5	V		P_10.4.11
<b>VRS Diagnosis:</b>							
Middle voltage level diagnosis mode	$V_{middle}$	0.9	1.3	1.65	V		P_10.4.12
Diagnosis measurement time	$t_{conv}$	-	7	8	$\mu\text{s}$		P_10.4.13

**VR and Hall Sensor Interface**

**Table 37 Electrical Characteristics: VR Sensor Interface (cont'd)**

$V_S = 13.5\text{ V}$ ,  $V_{VSV} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to ground, positive current flowing into pin (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
Diagnosis current accuracy	$I_{\text{diag, acc}}$	-30%	-	+30%		$VRIN1 = VRIN2 = V_{\text{middle}}$ ; typ. values see register <b>VRConfig1</b> and <b>VRConfig2</b>	P_10.4.14
Short to GND detection threshold	$V_{\text{th, scg}}$	0.8	-	1.1	V		P_10.4.15
Short to battery detection threshold	$V_{\text{th, scb}}$	2.8	-	3.3	V		P_10.4.16
Open load detection threshold	$V_{\text{th, ol}}$	0.9	-	1.2	V		P_10.4.17
ADC measurement input range	$V_{\text{ADC, r}}$	-1.5	-	1.5	V		P_10.4.8
ADC measurement gain	$V_{\text{ADC, LSB}}$	-	49	-	mV	valid from $6_d$ to $70_d$	P_10.4.31
ADC measurement offset	$V_{\text{ADC, offset}}$	-	$37_d$	-			P_10.4.32

**Output Characteristics:**

Low Level Output Voltage - Low Output Current	$V_{\text{VR_OUT, L, l}}$	-	-	0.4	V	$I_{\text{VR_OUT}} = 100\ \mu\text{A}$	P_10.4.21
Low Level Output Voltage - High Output Current	$V_{\text{VR_OUT, L, h}}$	-	-	1.5	V	$I_{\text{VR_OUT}} = 1\ \text{mA}$	P_10.4.22
High Level Output Voltage - Low Output Current	$V_{\text{VR_OUT, H, l}}$	VDDIO-0.4	-	-	V	$I_{\text{VR_OUT}} = -100\ \mu\text{A}$	P_10.4.23
High Level Output Voltage - High Output Current	$V_{\text{VR_OUT, H, h}}$	VDDIO-1.5	-	-	V	$I_{\text{VR_OUT}} = -1\ \text{mA}$	P_10.4.24

**Transfer Characteristics:**

Output Filter Time 1	$t_{\text{of, 1}}$	1	2	3	$\mu\text{s}$	reset value	P_10.4.25
Output Filter Time 2	$t_{\text{of, 2}}$	5	6	7.5	$\mu\text{s}$		P_10.4.26
Output Filter Time 3	$t_{\text{of, 3}}$	9.5	11	13	$\mu\text{s}$		P_10.4.27
Output Filter Time 4	$t_{\text{of, 4}}$	19	21	23	$\mu\text{s}$		P_10.4.28

1) external circuitry for hall mode see [Chapter 17.2](#)

**Local Interconnect Network (LIN)**

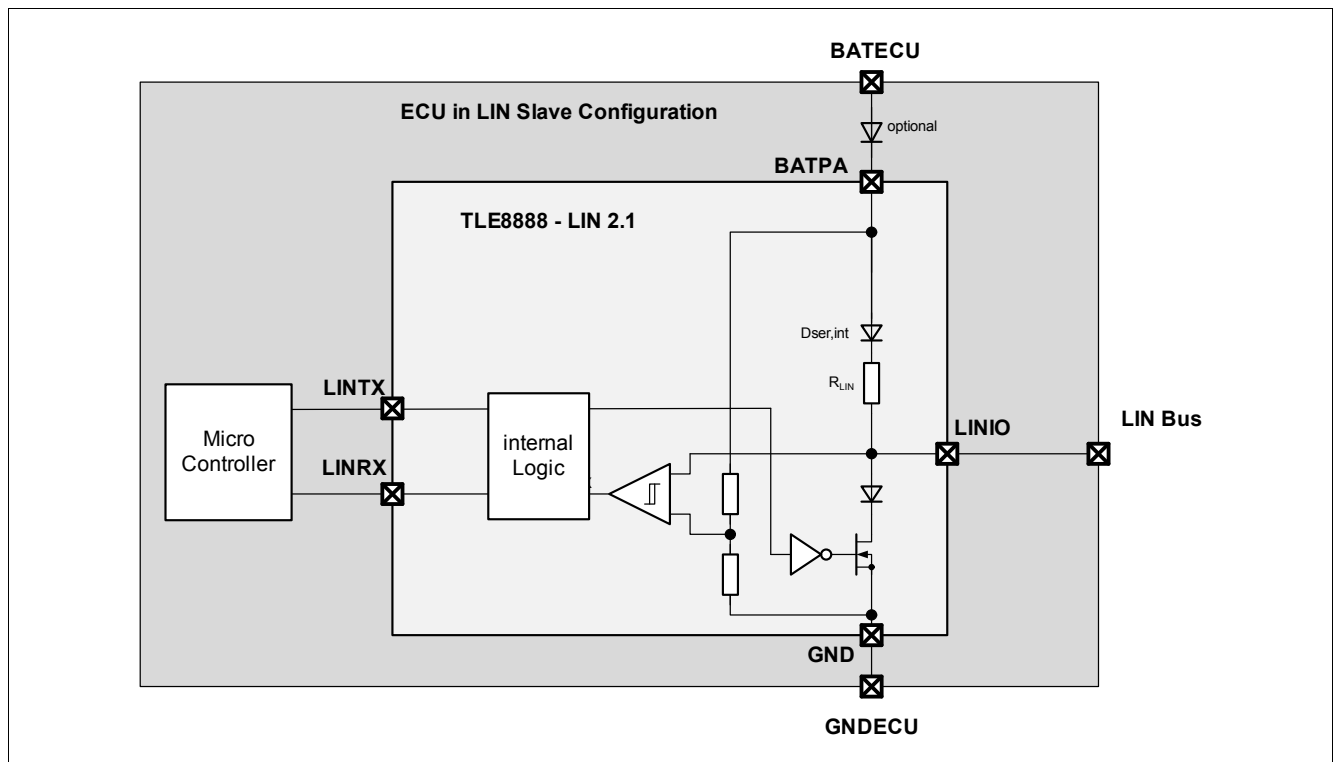
**11 Local Interconnect Network (LIN)**

The LIN interface is designed for in-vehicle networks using data transmission up to 20 kbit/s. The implementation of the physical layer is according to LIN specification revision 2.1 for slave nodes and is compatible with lower versions like revision 2.0 and 1.3<sup>1)</sup>. *LINTX* is the transmit-data input from the microcontroller, *LINIO* is the bidirectional LIN bus signal and *LINRX* is the receive-data output to the microcontroller. The transmitted data stream at *LINTX* is converted to the LIN bus signal at *LINIO*. *LINRX* reflects the received data at *LINIO* with a logic signal suited for 3.3 V and 5 V microcontroller interfaces.

The detection thresholds at *LINIO* are related to the power supply *BATPA*<sup>2)</sup>.

The LIN interface of the TLE8888-1QK is compatible to the physical layer definition of the K-Line (ISO 9141) standard. For K-Line operation no additional settings are necessary.

A flash mode for high speed operation can be selected with the communication interface (MSC or SPI). There is no bus wake-up function implemented.



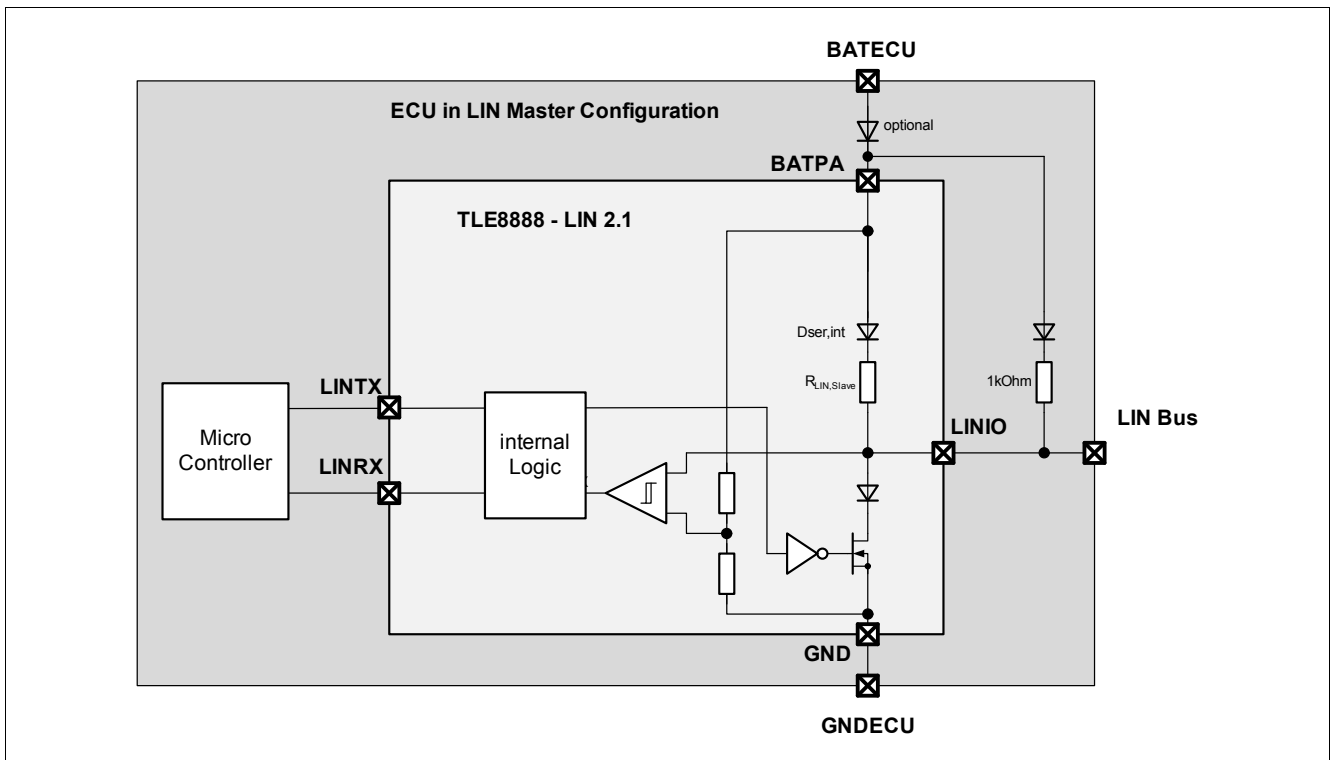
**Figure 48 Local Interconnect Network (LIN) Slave Node**

The LIN interface in the TLE8888-1QK is implemented according the requirements of the standard for slave nodes. For master setup an external pull up resistor (typ. 1 k $\Omega$ , see definition in LIN specification) and a diode must be connected to *LINIO* and *BATPA* on the ECU (see [Figure 49](#)).

1) see LIN specification revision 2.1 chapter 6.2

2) *BATPA* is identical to the internal supply voltage *VSUP* defined in LIN specification revision 2.1

**Local Interconnect Network (LIN)**



**Figure 49 Local Interconnect Network (LIN) Master Node**

## 11.1 Operation Modes

The interface can be configured for three operation modes:

- LIN/K-Line Mode: operation according LIN specification revision 2.1 with a maximum speed of 20 kbit/s and K-Line standard ISO 9141
- Receive Only Mode: transmission of data is disabled
- Flash Mode: operation up to 115 kbit/s is possible, slope control and current limitation are deactivated

The selection of the modes is done with setting the bits **LIN** in the register **ComConfig1** via communication interface (MSC or SPI). The operation mode after power on reset is defined by reset value of the register.

## 11.2 Failure Modes in LIN/K-Line Operation

In the LIN specification a special behavior of the interface is required for some failure conditions. This behavior is also active if a K-Line node is used.

### 11.2.1 Performance in Non Operation Supply Voltage Range

For supply voltages out of operation range the interface may still operate, but communication is not guaranteed. For  $LINTX = \text{'high'}$  (recessive) the interface shall not drive  $LINIO$  to dominant state and if  $LINIO$  is in recessive state the  $LINRX$  output shall provide a 'high' (recessive).

### 11.2.2 Loss of Supply Voltage and GND Connection

During loss of supply voltage or GND connection the interface shall not interfere with the communication of other LIN nodes. Upon return of connection, normal operation shall resume without any intervention on the LIN bus line (pin  $LINIO$ ).

### **11.2.3 Bus Wiring Short to Battery or GND**

The LIN interface is protected against short to battery or short to GND. Upon remove of the fault, normal operation shall resume without any intervention on the LIN bus line (pin *LINIO*).

### **11.2.4 TX Time Out**

The TX time out function is implemented to prevent the bus line from being blocked by a permanent 'low' at the pin *LINTX* caused by an error at the ECU or the microcontroller. If the *LINTX* signal is 'low' (dominant) for  $t > t_{\text{timeout}}$  the transmission of the *LINTX* signal to the bus is deactivated and the LIN output stage is disabled.

The transmission is reactivated, after a rising edge at *LINTX* was detected. The implemented time out feature requires a minimum data rate of 1600 bit/s.

The time out function can be disabled with the configuration bit **LINTOE** in the configuration register **ComConfig1**.

### **11.2.5 Overtemperature Protection**

The LIN bus output *LINIO* is protected against overload with an overtemperature protection. In case of overtemperature the output transistor is switched off and the diagnosis bit **LINOT** in the diagnosis register **ComDiag** is set. The configuration register is not changed.

**Local Interconnect Network (LIN)**

**11.3 Electrical Characteristics LIN**

**Table 38 Electrical Characteristics: LIN**

$V_S = 13.5\text{ V}$ ,  $V_{VSV} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to ground, positive current flowing into pin (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
Supply voltage range for normal operation	$V_{BATPA,LIN}$	7	–	18	V	acc. Param 10 LIN Spec. Rev. 2.1	P_11.3.1
Limitation Current at LINIO for driver dominant state	$I_{LINIO,lim}$	40	–	200	mA	acc. Param 12 LIN Spec. Rev. 2.1	P_11.3.2
Leakage Current at LINIO for bus dominant state and driver off	$I_{LINIO,leak,dom}$	-1	–	–	mA	acc. Param 13 LIN Spec. Rev. 2.1 $V_{LINIO} = 0\text{ V}$ $V_{BAT} = 12\text{ V}$	P_11.3.3
Leakage Current at LINIO for bus recessive state	$I_{LINIO,leak,rec}$	–	–	20	$\mu\text{A}$	acc. Param 14 LIN Spec. Rev. 2.1 $V_{LINIO} > V_{BAT}$	P_11.3.4
Current at LINIO during GND loss	$I_{LINIO,no\_GND}$	-1	–	1	mA	acc. Param 15 LIN Spec. Rev. 2.1 $GND = V_S$ $0\text{ V} < V_{LINIO} < 18\text{ V}$ $V_{BAT} = 12\text{ V}$	P_11.3.5
Current at LINIO during power supply loss	$I_{LINIO,no\_Sup}$	–	–	20	$\mu\text{A}$	acc. Param 16 LIN Spec. Rev. 2.1 $GND = V_S = 0\text{ V}$ $0\text{ V} < V_{LINIO} < 18\text{ V}$	P_11.3.6
Receiver Dominant State	$V_{LINIO,dom}$	–	–	$0.4 \cdot V_{B\_ATPA}$	V	acc. Param 17 LIN Spec. Rev. 2.1	P_11.3.7
Receiver Recessive State	$V_{LINIO,rec}$	$0.6 \cdot V_{B\_ATPA}$	–	–	V	acc. Param 18 LIN Spec. Rev. 2.1	P_11.3.8
Receiver switching threshold center voltage	$V_{LINIO,cont}$	$0.475 \cdot V_{BATPA}$	–	$0.525 \cdot V_{BATPA}$	V	acc. Param 19 LIN Spec. Rev. 2.1 $V_{LINIO,cont} = (V_{th,dom} + V_{th,rec})/2$	P_11.3.9
Hysteresis of switching threshold	$V_{Hys}$	–	–	$0.175 \cdot V_{BATPA}$	V	acc. Param 20 LIN Spec. Rev. 2.1 $V_{Hys} = V_{th,rec} - V_{th,dom}$	P_11.3.10
Voltage drop at internal serial diode $D_{ser,int}$	$V_D$	0.4	–	1	V	acc. Param 21 LIN Spec. Rev. 2.1	P_11.3.11
Resistance of internal slave resistor $R_{slave}$	$R_{LIN,Slave}$	20	–	60	k $\Omega$	acc. Param 26 LIN Spec. Rev. 2.1	P_11.3.12

**Local Interconnect Network (LIN)**

**Table 38 Electrical Characteristics: LIN (cont'd)**

$V_S = 13.5\text{ V}$ ,  $V_{VSV} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to ground, positive current flowing into pin (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
Duty cycle 1	$D_1$	0.396	-	-	-	acc. Param 27 LIN Spec. Rev. 2.1	P_11.3.13
Duty cycle 2	$D_2$	-	-	0.581	-	acc. Param 28 LIN Spec. Rev. 2.1	P_11.3.14
Duty cycle 3	$D_3$	0.417	-	-	-	acc. Param 29 LIN Spec. Rev. 2.1	P_11.3.15
Duty cycle 4	$D_4$	-	-	0.59	-	acc. Param 30 LIN Spec. Rev. 2.1	P_11.3.16
Propagation delay of receiver rising edge	$t_{rx,pd,r}$	-	-	6	$\mu\text{s}$	acc. Param 31 LIN Spec. Rev. 2.1	P_11.3.17
Propagation delay of receiver falling edge	$t_{rx,pd,f}$	-	-	6	$\mu\text{s}$	acc. Param 31 LIN Spec. Rev. 2.1	P_11.3.18
Propagation delay symmetry of receiver	$t_{rx,pd, sym}$	-2	-	2	$\mu\text{s}$	acc. Param 32 LIN Spec. Rev. 2.1	P_11.3.19
TX Dominant Time Out Time	$t_{timeout}$	6	12	20	ms	min. data rate of 1600bit/s required	P_11.3.20
Bus Recessive Output Voltage	$V_{BUS,rec}$	$0.8 \cdot V_B$ ATPA	-	-	V		P_11.3.21
Bus Dominant Output Voltage	$V_{BUS,do}$	-	-	1.4	V	$V_{BATPA} = 7\text{ V}$ $R_{pu} = 500\ \Omega$	P_11.3.22
Bus Dominant Output Voltage	$V_{BUS,do}$	-	-	2.2	V	$V_{BATPA} = 18\text{ V}$ $R_{pu} = 500\ \Omega$	P_11.3.23
LIN/IO Input Capacitance	$C_{LINIO}$	-	15	25	pF	1)	P_11.3.24
Overtemperature Switch Off Threshold	$T_{LIN,ot}$	150	-	200		1)	P_11.3.25
Overtemperature Hysteresis	$T_{LIN,ot,hys}$	-	10	-		1)	P_11.3.26

**LINRX Output Characteristics**

Low Level Output Voltage - Low Output Current	$V_{LINRX,L,l}$	-	-	0.4	V	$I_{LINRX} = 100\ \mu\text{A}$	P_11.3.27
Low Level Output Voltage - High Output Current	$V_{LINRX,L,h}$	-	-	1.5	V	$I_{VR\_OUT} = 1\text{ mA}$	P_11.3.28
High Level Output Voltage - Low Output Current	$V_{LINRX,H,l}$	VDDIO-0.4	-	-	V	$I_{LINRX} = -100\ \mu\text{A}$	P_11.3.29
High Level Output Voltage - High Output Current	$V_{LINRX,H,h}$	VDDIO-1.5	-	-	V	$I_{LINRX} = -1\text{ mA}$	P_11.3.30

**LINTX Input Characteristics**

Low Level Input Voltage	$V_{LINTX,l}$	-0.3	-	0.9	V		P_11.3.31
-------------------------	---------------	------	---	-----	---	--	-----------

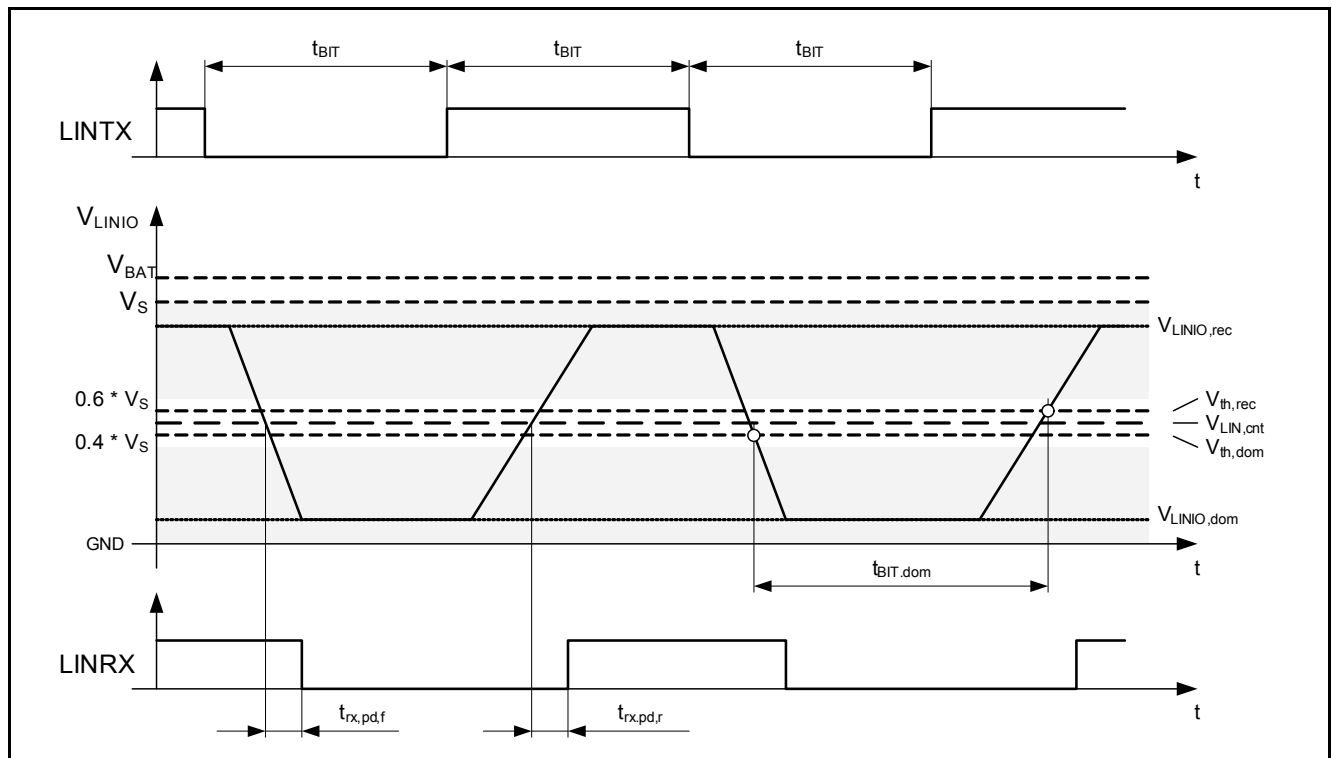
**Local Interconnect Network (LIN)**

**Table 38 Electrical Characteristics: LIN (cont'd)**

$V_S = 13.5\text{ V}$ ,  $V_{VSV} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to ground, positive current flowing into pin (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
High Level Input Voltage	$V_{LINTX,h}$	2	–	$V_{VDDIO}$	V		P_11.3.32
Input Voltage Hysteresis	$V_{IN,hys}$	50	200	–	mV		P_11.3.33
Pull Up Current	$I_{LINTX,pu}$	-100	–	-25	$\mu\text{A}$	$V_{LINTX} = 0\text{ V}$	P_11.3.34
Pull Up Current	$I_{LINTX,pu}$	–	–	-2.4	$\mu\text{A}$	$V_{LINTX} = V_{VDDIO} - 0.6\text{ V}$	P_11.3.35

1) Not subject to production test, specified by design



**Figure 50 Timing Diagram of the LIN Interface**



## 12 High Speed Controller Area Network (CAN) Transceiver

The Controller Area Network (CAN) is a serial bus system that connects microcontroller, sensors and actuators for real-time control applications.

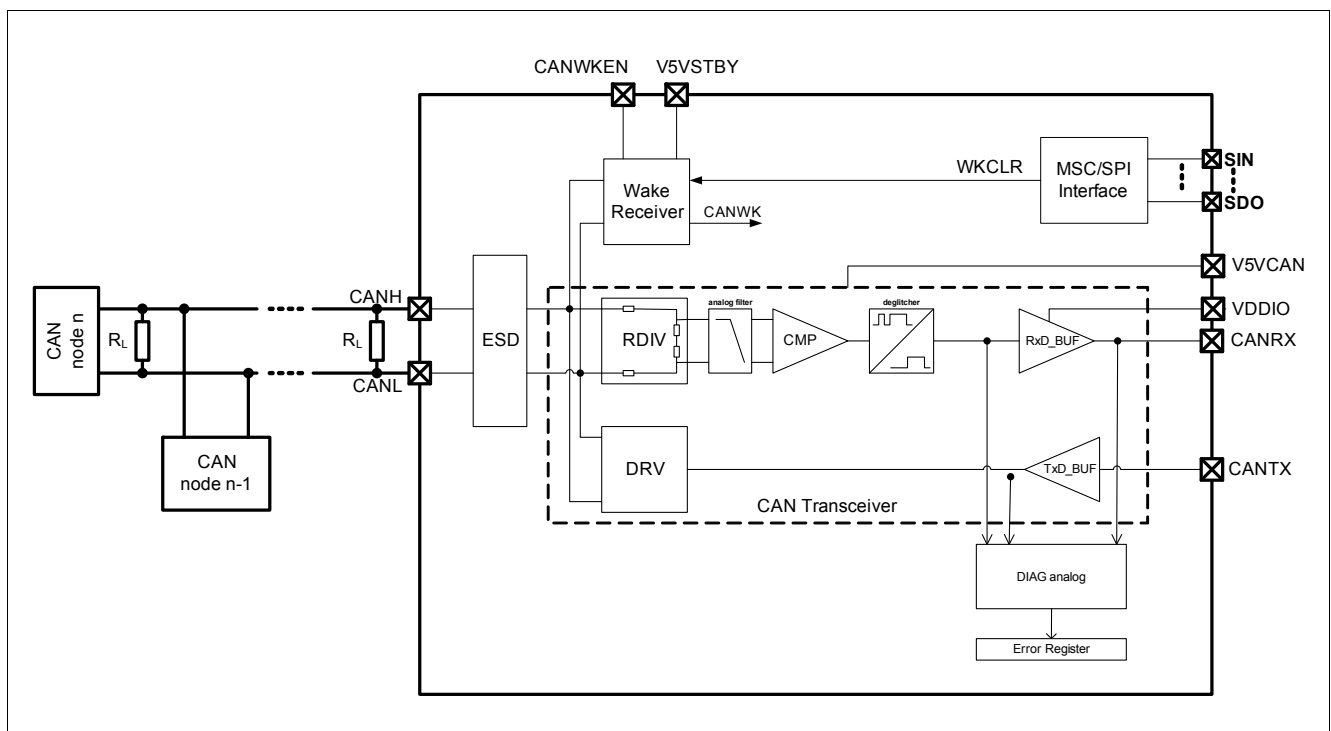
The integrated CAN interface provides the physical layer of the CAN according to ISO 11898. It is suitable for high speed differential data transmission and reception. It works as an interface between the CAN protocol controller and the physical bus lines.

Remote wake-up function with a dominant signal at the bus lines is implemented.

### 12.1 Functional Description

The high speed CAN is a two wire differential network which allows data transmission rates up to 1Mbit/s. The input *CANTX* and the output *CANRX* are connected to the microcontroller of the ECU. As shown in **Figure 51**, the CAN has a receive unit and a output driver stage, allowing the transceiver to send data to the bus line and monitor data from the bus lines at the same time. It converts the serial data stream available at the transmit data input *CANTX* into a differential output signal at *CANH* and *CANL*. The receiver stage monitors *CANH* and *CANL* and converts the differential voltage to a serial data stream at *CANRX*.

The supply of the CAN transceiver is done out of *V5VCAN*, the wake receiver is supplied out of *V5VSTBY*. The pin *V5VCAN* must be connected directly to the 5 V supply pin *V5V*. In order to optimize EMC performance a ceramic capacitor **CV5VCAN** should be connected to the pins *V5VCAN* and *PGND* (pin 50).



**Figure 51 High speed CAN topology**

### 12.2 Operation Modes

Four different operation modes are available. Regardless of the supply status the CAN interface does not disturb the communication on the bus line.

### **12.2.1 Normal Operation Mode**

In normal operation mode the CAN transceiver sends the serial data stream available at the pin *CANTX* to the CAN bus while at the same time the data available at the CAN bus is monitored at the *CANRX* pin. In normal operation mode all functions are active:

- The driver output is active and drives data from the *CANTX* pin to the CAN bus.
- The receiver unit is active and provides the data from the CAN bus to the *CANRX* pin.
- The failure detection is active.

### **12.2.2 Receive Only Mode**

In the receive only mode the CAN transceiver can still receive data from the bus, but the driver output stage is disabled and therefore no data can be sent to the CAN bus. All other functions are active:

- The driver output is disabled and data which is available at the *CANTX* pin will be blocked and not communicated to the CAN bus.
- The receiver unit is active and provides the data from the CAN bus to the *CANRX* pin.
- The failure detection is active.

### **12.2.3 Power-Down Mode**

If the TLE8888-1QK is not supplied the bus communication is not allowed to be disturbed. Therefore the resistors of the receiver unit are switched off and the bus input pins *CANH* and *CANL* are high resistive.

### **12.2.4 Remote Wake-Up**

The wake receiver is internally supplied from the standby supply pin *V5VSTBY*. The wake-up function is enabled by an external connection of the pin *CANWKEN* to the standby supply pin *V5VSTBY*. The wake function is disabled by an external connection to *AGND* and the current consumption of the wake-up circuit is reduced to leakage currents only.

In “ECU Sleep” state a dominant signal at *CANH* and *CANL* for longer than the **CAN Wake-up filter time** preceded by a recessive signal causes an internal wake-up and the internal wake signal **CANWK** is set. With a wake clear command (set bit **WKCLR** to “1” in command register **Cmd0**) **CANWK** is reset (status see bit **CANWK** in the status register **OpStat0**). The next wake-up is only detected with a transition from recessive to dominant. With this implementation of the wake-up procedure, bus line dominant clamping does not lead to permanent wake-up.

In **Figure 52**, **Figure 53** and **Figure 54** the behavior is shown.

High Speed Controller Area Network (CAN) Transceiver

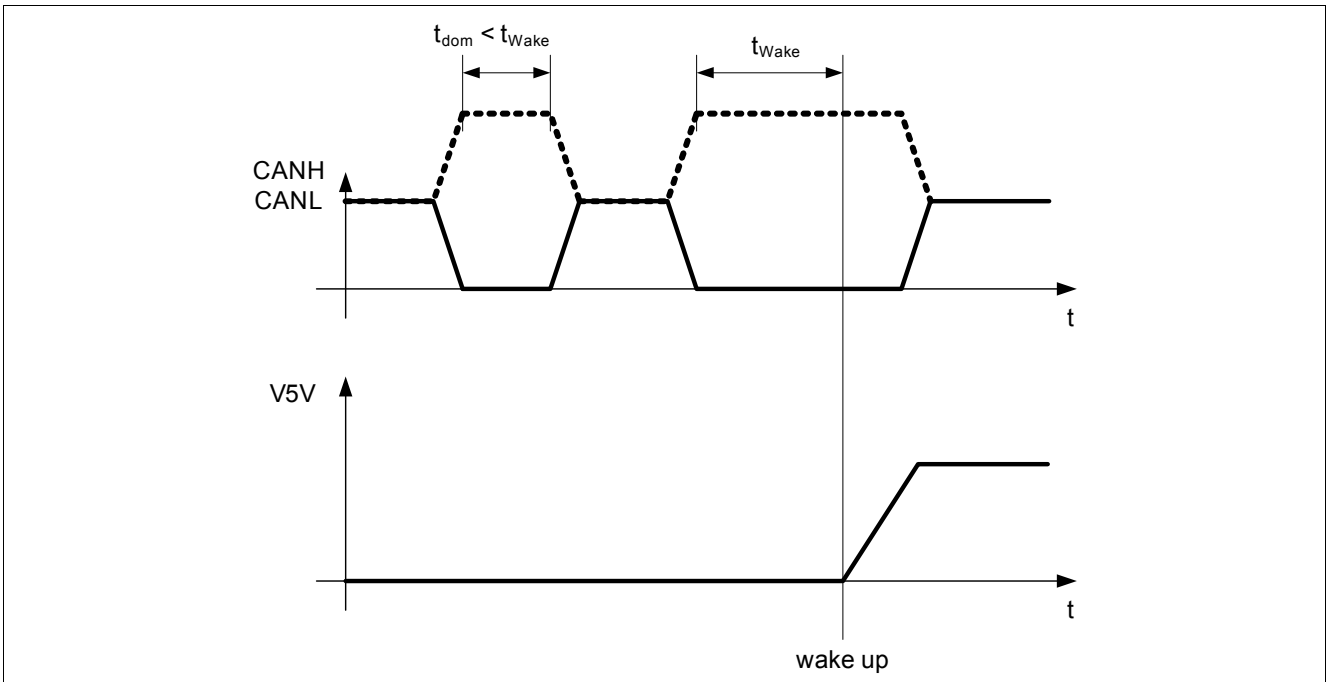


Figure 52 CAN Remote Wake-up

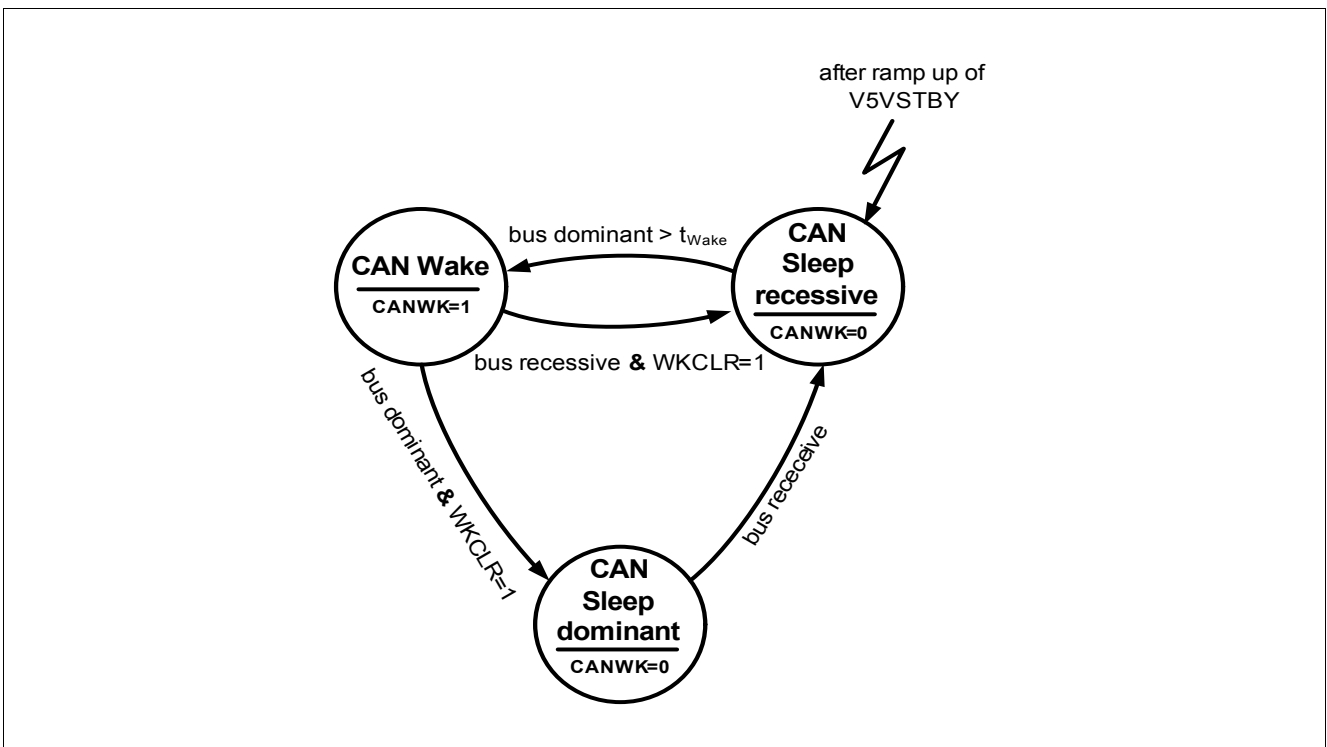
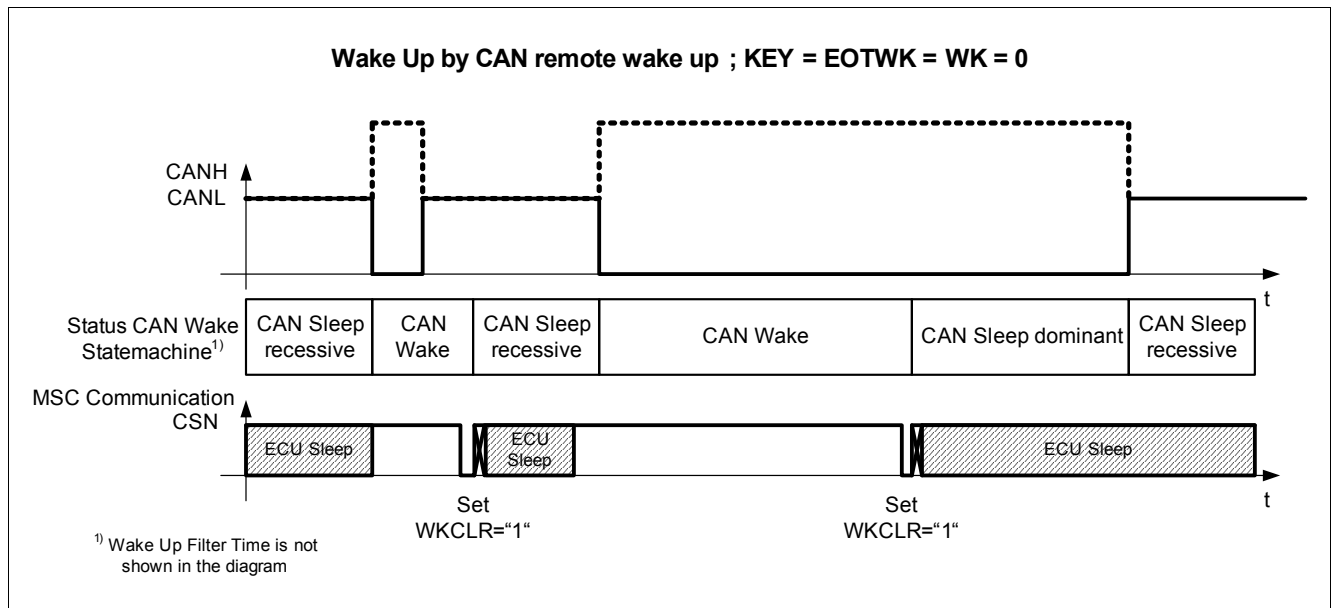


Figure 53 CAN Wake-up State machine

High Speed Controller Area Network (CAN) Transceiver



**Figure 54 State Transitions at CAN Remote Wake-up**

## 12.3 Diagnostic Functions

The CAN transceiver has an implemented diagnostic unit. Bus failures and local failures can be detected.

### 12.3.1 CAN Bus Failure Detection

In normal operation the CAN transceiver can detect following bus failure:

- Bus line dominant clamping (bit **CANBDC** in diagnosis register **ComDiag**)

Following bus failures can't be detected (outputs are protected):

- CANH shorted to GND
- CANL shorted to GND
- CANH shorted to low voltage supply
- CANL shorted to low voltage supply
- CANH shorted to  $V_{Bat}$
- CANL shorted to  $V_{Bat}$
- CANH open
- CANL open
- CANH shorted to CANL

### 12.3.2 Local Failure Detection

In normal operation the CAN transceiver can detect following local failures:

- CAN TX dominant time-out (bit **CANTXTO** in diagnosis register **ComDiag**)
- Overtemperature (bit **CANOT** in diagnosis register **ComDiag**)

In case of failure detection only the corresponding diagnosis register bits are changed. No change in the configuration occurs.

**High Speed Controller Area Network (CAN) Transceiver**

**12.4 Electrical Characteristics CAN Transceiver**

**Table 39 Electrical Characteristics: CAN Transceiver**

$V_S = 13.5\text{ V}$ ,  $V_{VSV} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to ground, positive current flowing into pin (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
CANH voltage, recessive state	$V_{CANH,rec}$	2	2.5	3	V	no load	P_12.4.1
CANL voltage, recessive state	$V_{CANL,rec}$	2	2.5	3	V	no load	P_12.4.2
CANH voltage, dominant state	$V_{CANH,dom}$	2.75	3.5	4.5	V		P_12.4.3
CANL voltage, dominant state	$V_{CANL,dom}$	0.5	1.5	2.25	V		P_12.4.4
Differential output bus voltage, dominant state	$V_{diff,out,dom}$	1.5	2	3	V	$4.75\text{ V} < V_{VSVCAN} < 5.25\text{ V}$	P_12.4.5
Common mode bus voltage, dominant and recessive state	$V_{CM}$	-12	-	12	V	$4.75\text{ V} < V_{VSVCAN} < 5.25\text{ V}$	P_12.4.6
External Termination resistor	$R_L$	100	120	130	$\Omega$		P_12.4.7
Differential input voltage, recessive state	$V_{diff,in,rec}$	-1	-	0.5	V		P_12.4.8
Differential input voltage, dominant state	$V_{diff,in,dom}$	0.9	-	5	V		P_12.4.9
Differential receiver hysteresis	$V_{diff,hys}$	20	100	-	mV		P_12.4.10
Common mode input resistance	$R_{in}$	5	-	50	k $\Omega$		P_12.4.11
Bit time	$t_B$	1	-	-	$\mu\text{s}$		P_12.4.12
Propagation delay time CANTX to CANRX recessive to dominant	$t_{pd,rec,dom}$	-	-	255	ns		P_12.4.13
Propagation delay time CANTX to CANRX dominant to recessive	$t_{pd,dom,rec}$	-	-	255	ns		P_12.4.14
Propagation delay time CANTX to CANH/CANL recessive to dominant	$t_{pd,out,dom}$	-	-	140	ns	$T_j = 25^\circ\text{C}^{1)}$ $C_{CANH/CANL} < 10\text{ pF}$	P_12.4.15
Propagation delay time CANTX to CANH/CANL dominant to recessive	$t_{pd,out,rec}$	-	-	140	ns	$T_j = 25^\circ\text{C}^{1)}$ $C_{CANH/CANL} < 10\text{ pF}$	P_12.4.16

**High Speed Controller Area Network (CAN) Transceiver**

**Table 39 Electrical Characteristics: CAN Transceiver (cont'd)**

$V_S = 13.5\text{ V}$ ,  $V_{VSV} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to ground, positive current flowing into pin (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
Bus line dominant clamping detection time	$t_{\text{bus,cl,dom}}$	4	–	7	ms		P_12.4.17
CANTX dominant detection time	$t_{\text{CANTX,cl,dom}}$	4	–	7	ms		P_12.4.18
V5VCAN buffer capacitance <sup>1)</sup>	$C_{\text{V5VCAN}}$		2	–	$\mu\text{F}$	recommended for optimized EMC performance	P_12.4.19
Overtemperature Switch Off Threshold	$T_{\text{CAN,ot}}$	150	–	200	$^\circ\text{C}$	<sup>1)</sup>	P_12.4.20
Overtemperature Hysteresis	$T_{\text{CAN,ot,hys}}$	–	10	–	$^\circ\text{C}$	<sup>1)</sup>	P_12.4.21

**CANRX Output Characteristics**

Low Level Output Voltage - Low Output Current	$V_{\text{CANRX,L,l}}$	–	–	0.4	V	$I_{\text{CANRX}} = 100\ \mu\text{A}$	P_12.4.22
Low Level Output Voltage - High Output Current	$V_{\text{CANRX,L,h}}$	–	–	1.5	V	$I_{\text{CANRX}} = 1\ \text{mA}$	P_12.4.23
High Level Output Voltage - Low Output Current	$V_{\text{CANRX,H,l}}$	VDDIO-0.4	–	–	V	$I_{\text{CANRX}} = -100\ \mu\text{A}$	P_12.4.24
High Level Output Voltage - High Output Current	$V_{\text{CANRX,H,h}}$	VDDIO-1.5	–	–	V	$I_{\text{CANRX}} = -1\ \text{mA}$	P_12.4.25

**CANTX Input Characteristics**

Low level input voltage	$V_{\text{CANTX,l}}$	-0.3	–	1	V		P_12.4.26
High level input voltage	$V_{\text{CANTX,h}}$	2	–	$V_{\text{V5VCAN}}$	V		P_12.4.27
Input voltage hysteresis	$V_{\text{CANTX,hys}}$	50	200	–	mV		P_12.4.28
Pull up current	$I_{\text{CANTX,pu}}$	-100	–	-25	$\mu\text{A}$	$V_{\text{CANTX}} = 0\ \text{V}$	P_12.4.29

**Wake Receiver**

Differential input voltage, recessive state, low power mode	$V_{\text{diff,rec,lp}}$	-1	–	0.4	V	$4.75\text{ V} < V_{\text{V5VSTBY}} < 5.25\ \text{V}$	P_12.4.30
Differential input voltage, dominant state, low power mode	$V_{\text{diff,dom,lp}}$	1.15	–	5	V	$4.75\ \text{V} < V_{\text{V5VSTBY}} < 5.25\ \text{V}$	P_12.4.31
Common mode bus voltage, low power mode	$V_{\text{CM,lp}}$	-12	–	12	V	$4.75\ \text{V} < V_{\text{V5VSTBY}} < 5.25\ \text{V}$	P_12.4.32
CAN Wake-up filter time	$t_{\text{wake,CAN}}$	0.75	–	5	$\mu\text{s}$	$4.75\ \text{V} < V_{\text{V5VSTBY}} < 5.25\ \text{V}$	P_12.4.33
Additional current consumption in low power mode at pin <i>BATSTBY</i>	$I_{\text{CANWK}}$	–	–	35	$\mu\text{A}$	$0\ \text{V} \leq V_{\text{CANH}} \leq 5\ \text{V}$ , $0\ \text{V} \leq V_{\text{CANL}} \leq 5\ \text{V}$	P_12.4.34

1) Not subject to production test, specified by design

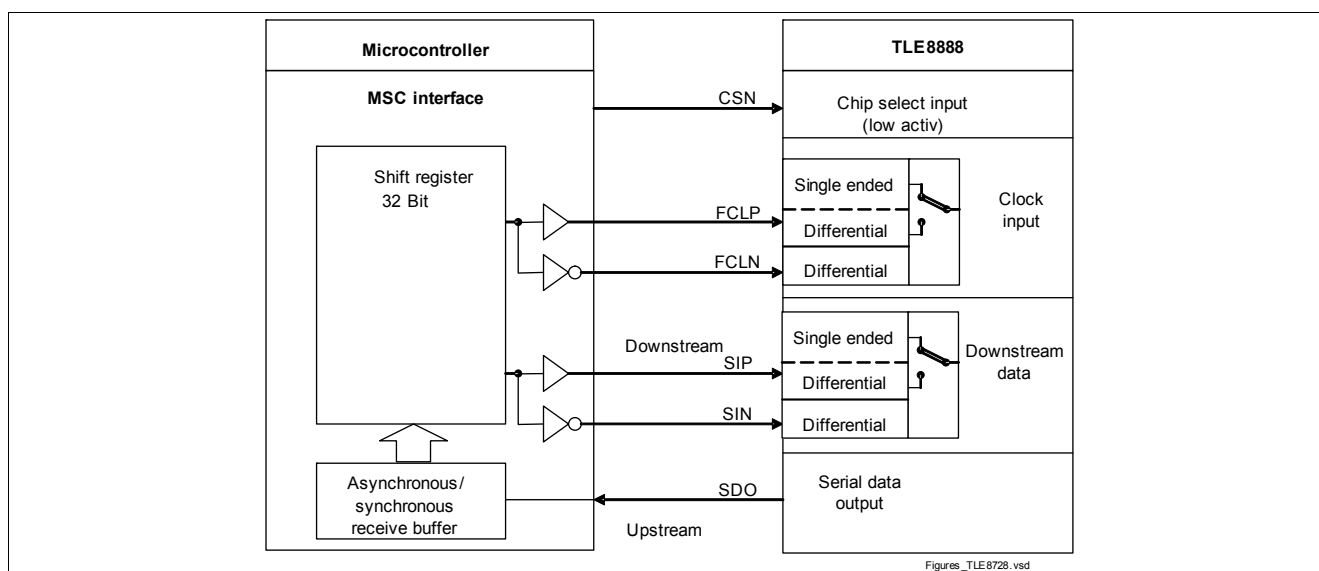
## 13 Microsecond Channel MSC

The bidirectional microsecond channel (MSC) is a serial interface which is especially optimized to connect peripheral devices via serial link to microcontroller. The serial communication link is built up by a fast synchronous downstream channel from microcontroller to the device and an asynchronous upstream channel (referenced to downstream clock). The downstream interface can be “low voltage differential” (*FCLN*, *FCLP*, *SIN*, *SIP*, *CSN*) or “single ended” (*FCLP*, *SIP*, *CSN*).

Via MSC, the microcontroller controls the outputs and logic of the device including the diagnosis and monitoring module. Read data is requested by microcontroller via downstream communication and returned by the device via MSC upstream channel.

Multiple “power devices” with MSC for downstream operation are possible. The device is selected by *CSN*. The MSC logic is internally supplied and referenced to *AGND*.

The behavior of the MSC interface during reset is described in [Table 5](#) and [Table 6](#) in [Chapter 5.2](#).



**Figure 55 MSC Interface (not tested, overview only)**

### 13.1 Downstream Communication

Downstream frames are synchronous serial frames with clock and data line.

The physical interface for downstream communication can be “low voltage differential” or “single ended” type. Both interface types are using individual pins (*FCLN*, *FCLP*, *SIN* and *SIP*) and common pins (*CSN* and *SDO*). For single ended interface *FCLN* and *SIN* have to be connected to *VDDIO*. For low voltage differential interface both input voltage levels must be within the defined input voltage range.

The frames and the behavior of the communication are the same in differential and single ended mode. Differential inputs for downstream data are *SIP* and *SIN*; the differential input signal *SIP* – *SIN* is the same logical signal as *SIP* alone in single ended mode and *SI* will be used in the description for both types of communication. The clock pins are *FCLP* and *FCLN*, the differential clock *FCLP* – *FCLN* is the same logical signal as *FCLP* in single ended mode and *CLK* will be used in the description for both types of communication. There is one input *CSN* for chip select, and one output *SDO* for upstream data. The device is always the slave in this communication link.

The *CSN* signal enables receiver circuits automatically during a downstream frame transmission.

Two types of downstream frames are defined:



**Microsecond Channel MSC**

- Command frames (selection bit = “1”)
- Data frames (selection bit = “0”)

The device MSC uses non inverting polarity for SI and CLK: SI changes its state with the rising edge of CLK and is sampled with the falling edge; a logic ‘1’ is a ‘high level’ on SI, and a logic ‘0’ is a ‘low level’ on SI. Data at SI is latched by the device on the falling edge of CLK.

The *CSN* input is active low during the active phases of command or data frames. An active enable signal validates the SI input signal. Outside the active phase (*CSN* line is at high level) data at SI is ignored.

It is possible to drive multiple “power devices” with shared CLK and SI lines and individual *CSN* signal.

Command frames and data frames may be sent in any sequence (with a passive phase of at least 2 CLK-cycles after each frame).

**Table 40 Execution of commands**

<b>Event on MSC downstream</b>	<b>upstream busy</b>	<b>upstream idle</b>
valid read command frame	ignored	executed
valid write command frame	executed <sup>1)</sup>	executed
valid data frame	accepted	accepted
invalid command	ignored	ignored
invalid data frame	ignored	ignored

1) only after **tprep,sr** or **tprep,mr**, see also **Chapter 13.2**

The serial clock CLK must be active (toggling) during upstream communication even when no command frame or data frame is transmitted.

The clock period of CLK is defined as  $t_{FCL}$ , maximum downstream clock rate is  $f_{FCLmax}$ .

The active phase of a downstream frame starts with the falling edge of the signal on *CSN* and ends with the rising edge. *CSN* changes its state with the rising edge of clock CLK.

Microsecond Channel MSC

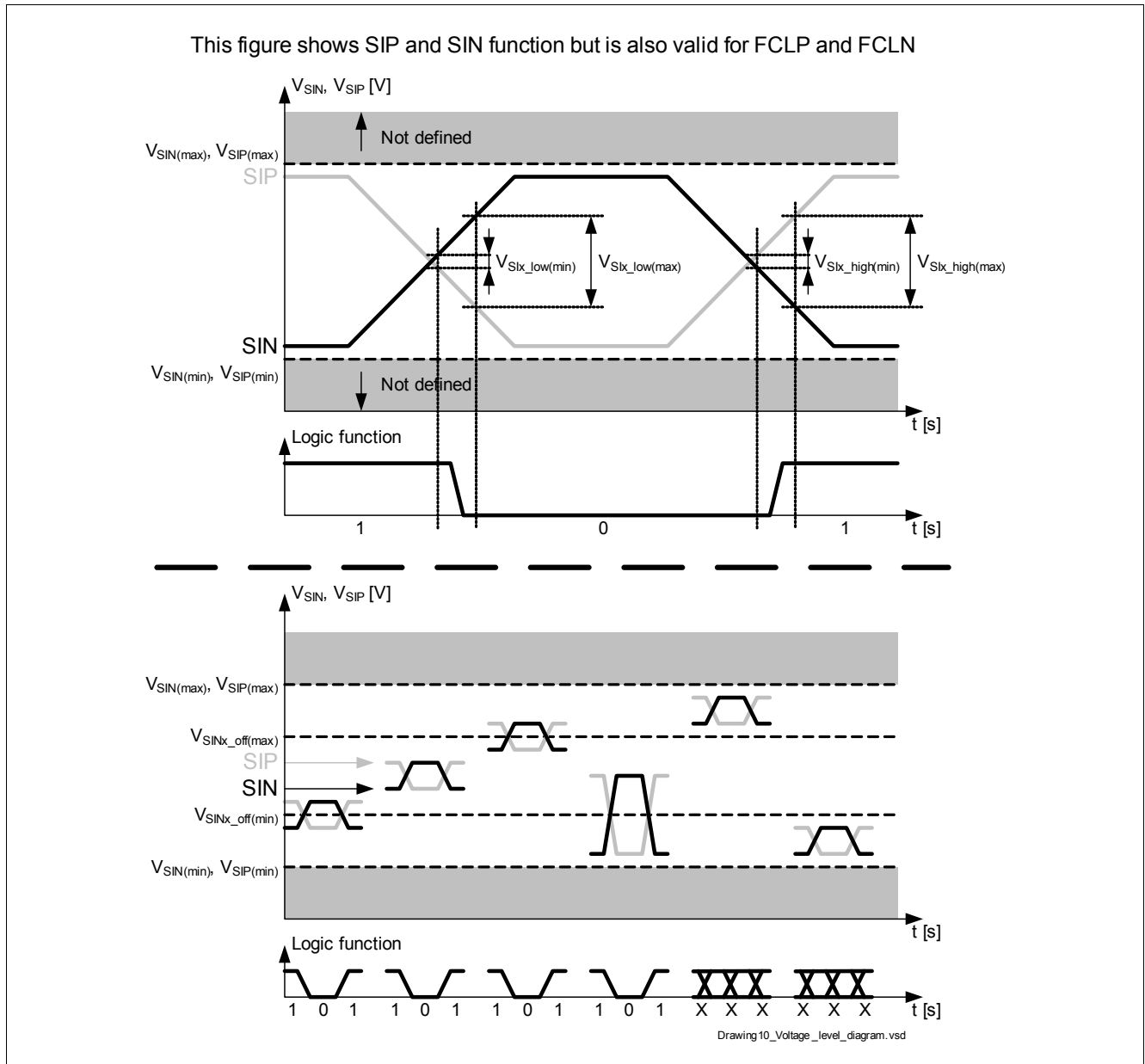


Figure 56 Voltage level diagram

### 13.1.1 Downstream Supervisory Functions

A command- or data frame is interpreted as valid, if it has the correct number of CLK pulses (a frame has a length of 17 clock pulses). Clock pulses are counted at the falling edge of the signal.

There is no parity check.

If TLE8888-1QK receives no valid data frame for  $t > t_{MSC\_mon}$ , the device switches off the output stages (all output stage control bits are set to “0”), the bits **01E** to **024E** in the configuration registers **OEConfig0** to **OEConfig3** are set to “0” and the MSC time out failure bit in the register **ComDiag** is set to “1”. The MSC time out failure bit is reset by a readout of the register **ComDiag** and all output stages remain off. For switching on the stages the bits **01E** to **024E** in the configuration registers **OEConfig0** to **OEConfig3** must be set to “1” and the control bits must be set. Outputs which are configured to be driven directly with the direct drive inputs are switched according the input level of the pins *IN1* to *IN12* after set of the bits **01E** to **024E**.

Microsecond Channel MSC

### 13.1.2 Command Frame

A command frame always starts with a high level bit (command selection bit). The number of command bits of the active phase of a command frame is fixed to 16. A command is executed only if the number of transmitted bits of an active command frame is equal to 17.

The length of the command frame's passive phase  $t_{CPP}$  must be a minimum of  $2 * t_{FCL}$  (2 clock pulses).

Alternatively the passive phase can consist in  $t_{CPP} = t_{FCL}$  (1 clock pulse) followed by a frame of wrong length (4...8 bits, with or without CSN active low) and a second  $t_{CPP} = t_{FCL}$  (1 clock pulse).

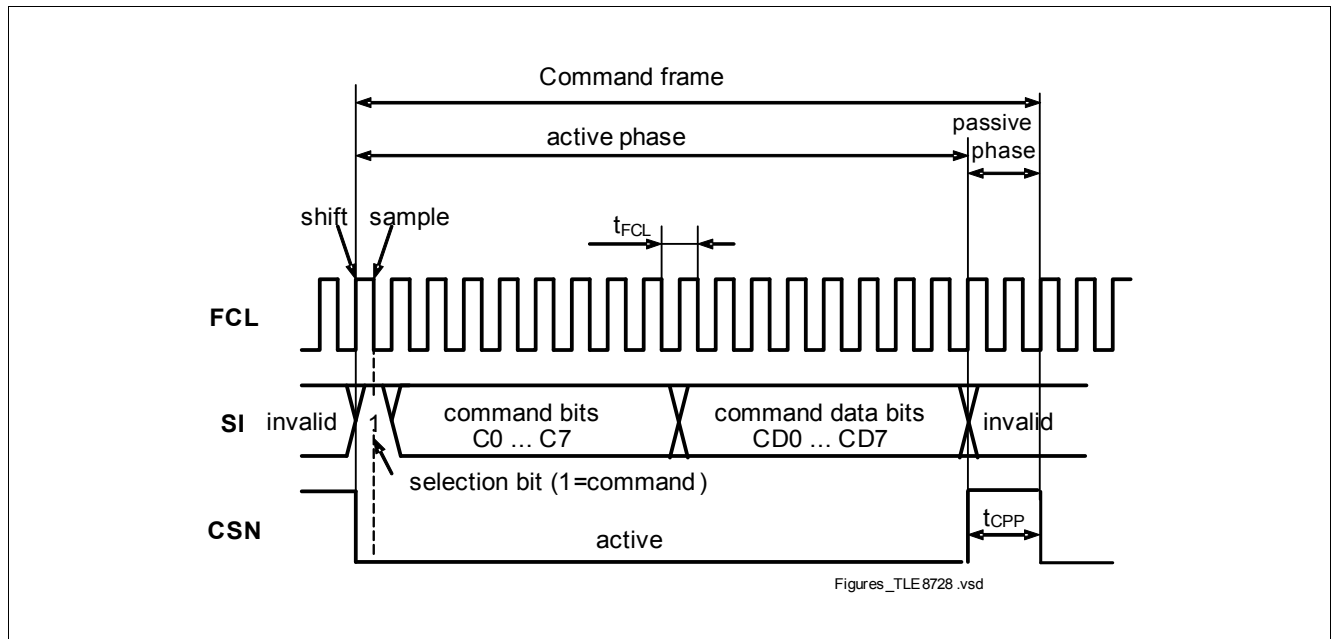


Figure 57 MSC command frame

Content of a command frame (LSB transmitted first)

Table 41 Command frame

Bit #	Description
0 (first bit)	= '1': command selection bit
1...8	Command [C0...C7]
9...16	Data for the command [CD0...CD7]

The least significant (LSB) bit of a command is transmitted first

### 13.1.3 Data Frame

A data frame always starts with a low level bit (data selection bit). The number of the data bits of the active phase of a data frame is fixed to 28 bit.

A data frame is accepted if the actual length is the expected length 29.

MSC Monitoring  $t_{MSC\_mon}$  is re triggered by any data frame with correct length (no other error detection mechanism is implemented).

The length of the data frame's passive phase  $t_{DPP}$  must be a minimum of  $2 * t_{FCL}$  (2 clock pulses).

Microsecond Channel MSC

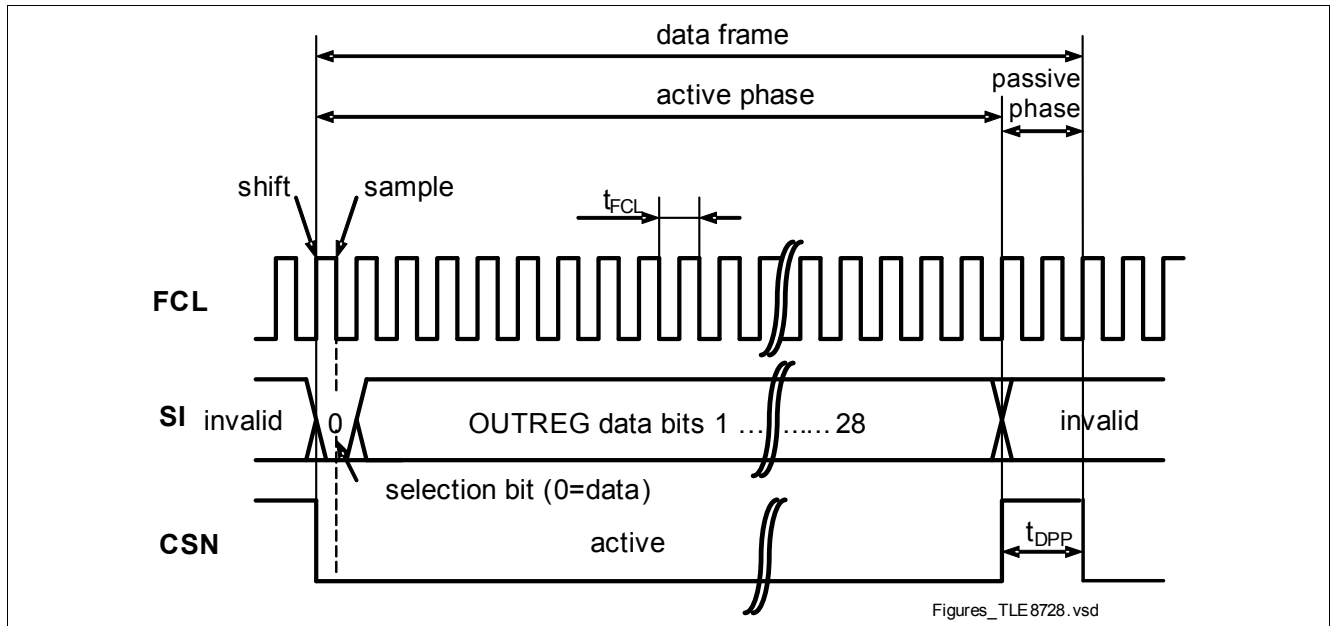


Figure 58 MSC data frame

Table 42 Data frame

OUTREG Bit	Description
0 (first bit)	= '0': data selection bit
1	<b>O140N</b> <sup>1)</sup>
2	<b>O110N</b> <sup>1)</sup>
3	<b>O240N</b> <sup>1)</sup>
4	<b>O130N</b> <sup>1)</sup>
5	<b>IGN10N</b> <sup>1)</sup>
6	<b>IGN20N</b> <sup>1)</sup>
7	<b>O50N</b> <sup>1)</sup>
8	<b>O10N</b> <sup>1)</sup>
9	<b>O150N</b> <sup>1)</sup>
10	<b>IGN30N</b> <sup>1)</sup>
11	<b>O20N</b> <sup>1)</sup>
12	<b>O220N</b> <sup>1)</sup>
13	<b>O90N</b> <sup>1)</sup>
14	<b>O230N</b> <sup>1)</sup>
15	<b>O190N</b> <sup>1)</sup>
16	<b>O160N</b> <sup>1)</sup>
17	<b>O180N</b> <sup>1)</sup>
18	<b>O200N</b> <sup>1)</sup>
19	<b>O80N</b> <sup>1)</sup>
20	<b>O40N</b> <sup>1)</sup>
21	<b>O170N</b> <sup>1)</sup>

Microsecond Channel MSC

Table 42 Data frame (cont'd)

OUTREG Bit	Description
22	O100N <sup>1)</sup>
23	O210N <sup>1)</sup>
24	O70N <sup>1)</sup>
25	O60N <sup>1)</sup>
26	O30N <sup>1)</sup>
27	IGN40N <sup>1)</sup>
28	O120N <sup>1)</sup>

1) Definition see Chapter 14.1.5.

There is no parity bit in the data frame.

The data is stored in the control register **Cont0** to **Cont3**.

### 13.2 Upstream Communication

The serial data output *SDO* is the synchronous serial data signal of the upstream channel and is always single ended. The polarity is ‘non inverting polarity’ – i.e. a low level bit at *SDO* is stored in the microcontroller as a logic ‘0’, and a high level bit at *SDO* is stored in the microcontroller as a logic ‘1’. The frequency for *SDO* is derived from CLK by an internal divider and can be configured via MSC.

The output of *SDO* can be configured as an open drain or an push pull output. The set is done with the bit **MSCO** in the configuration register **ComConfig0**. The full range of up stream frequency divider settings in the configuration register **ComConfig0** bits **MSCF** is valid for the push pull output configuration.

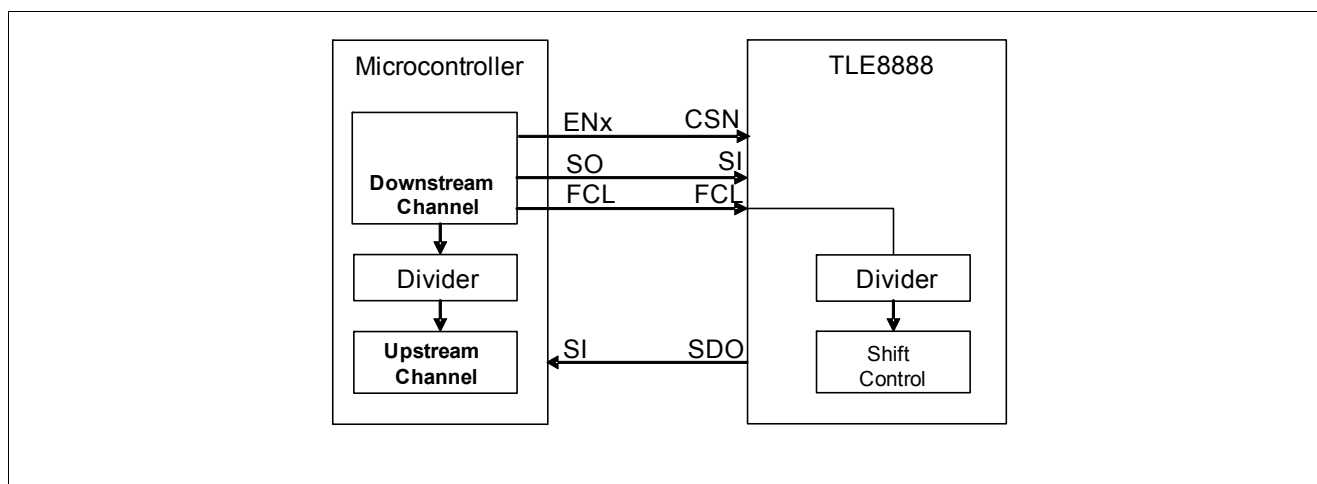


Figure 59 MSC upstream communication (not tested, overview only, Single Ended)

The data frame could be defined with 12 and 16 bit according the setting of **MSCUF** in the configuration register **ComConfig0**. In **Figure 60** the formats are shown. The address bits A2 and A3 are used for the selection of the upstream data register in the microcontroller.

Definition of Address Bits A0 to A3 in 16 Bit Upstream Mode:

- Fixed A0 to A3 Value:  
The value of the address bits A0 to A3 is fixed according the definition of **MSCA** in the configuration register **ComConfig1** at the rising edge of *CSN* of the read command. For read out with multiple read out commands the value of A0 to A3 does not change.

**Microsecond Channel MSC**

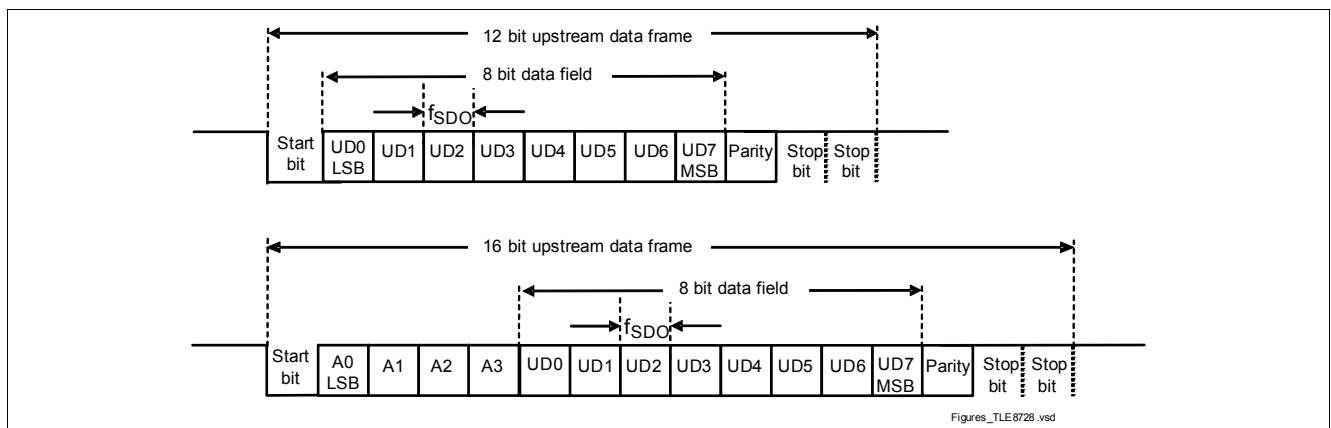
- **Multiple Read Command Mode:**  
 This mode is especially for the multiple read commands and the configuration of the microcontroller in UD3 interrupt mode. A2 and A3 are used in this mode to define the upstream data register (UD0 -UD3) and a number of n times 4 of upstream frames. A0 is defined as read overflow and A1 is defined as read busy.

**Table 43 Definition of A0 in Multiple Read Command Mode for 16 Bit Upstream Format**

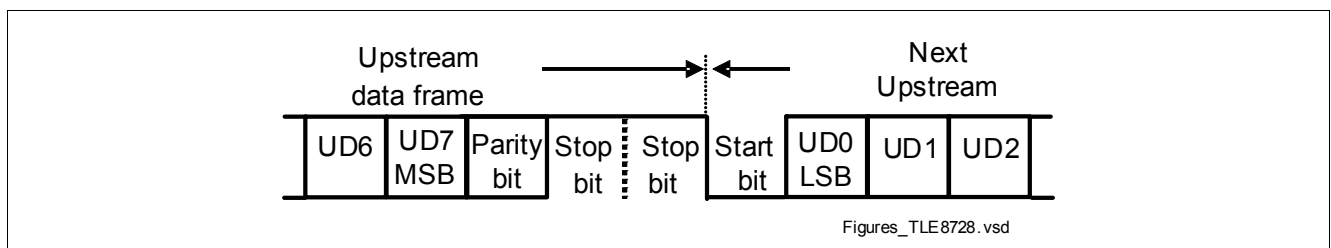
A0	Description
0	No read command is ignored
1	A read command was sent during upstream communication. This read command was ignored and this is signaled with A0 = 1

**Table 44 Definition of A1 in Multiple Read Command Mode for 16 Bit Upstream Format**

A1	Description
0	last upstream frame; after finish of this frame next transmitted read command will be executed
1	Upstream activities required by an multiple read commands are ongoing



**Figure 60 MSC upstream frame**



**Figure 61 MSC upstream communication flow**

**Table 45 12 Bit Upstream Frame**

Bit	description
0	start bit, always '0'
1-8	upstream data bits UD0...7

**Microsecond Channel MSC**

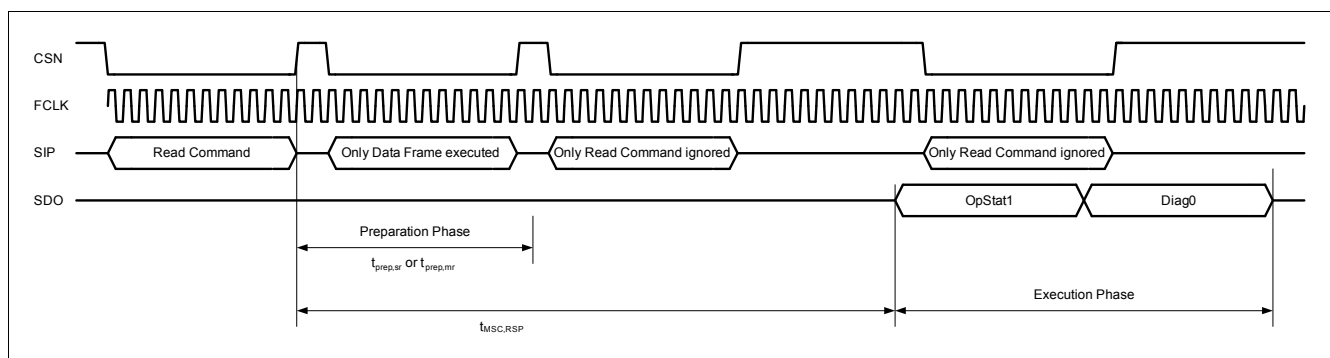
**Table 45 12 Bit Upstream Frame (cont'd)**

Bit	description
9	parity bit (The parity bit is set in order to achieve an even number of '1' in Bits UD0...7+Parity)
10, 11	stop bits, always '1'

**Table 46 16 Bit Upstream Frame**

Bit	description
0	start bit, always '0'
1-4	address bits A0...3
5-12	upstream data bits UD0...7
9	parity bit (The parity bit is set in order to achieve an even number of '1' in Bits UD0...7+Parity)
10, 11	stop bits, always '1'

Transmission of the registers via upstream starts within  $t_{MSC\_RSP}$  after read command has been received. During an ongoing upstream communication the device will ignore further read commands until the upstream data transfer is finished. A new read command is accepted if the rising edge CSN arrives after the last stop bit has been sent. Data frames are executed independently of ongoing read requests. Write commands are ignored during **MSC upstream preparation time for single read command  $t_{prep,sr}$**  or **MSC upstream preparation time for multi read command  $t_{prep,mr}$**  (see Figure 62). After that time the write commands are executed also during ongoing upstream communication. If the write command is changing the register which is in transmission, the old register content will be sent. With setting the command bit **MSCUPS** in the command register **Cmd0** the running upstream transmission is stopped and all remaining read request of a multiple read command are cleared.



**Figure 62 Example MSC upstream and active downstream communication**

### 13.3 Timing Characteristics

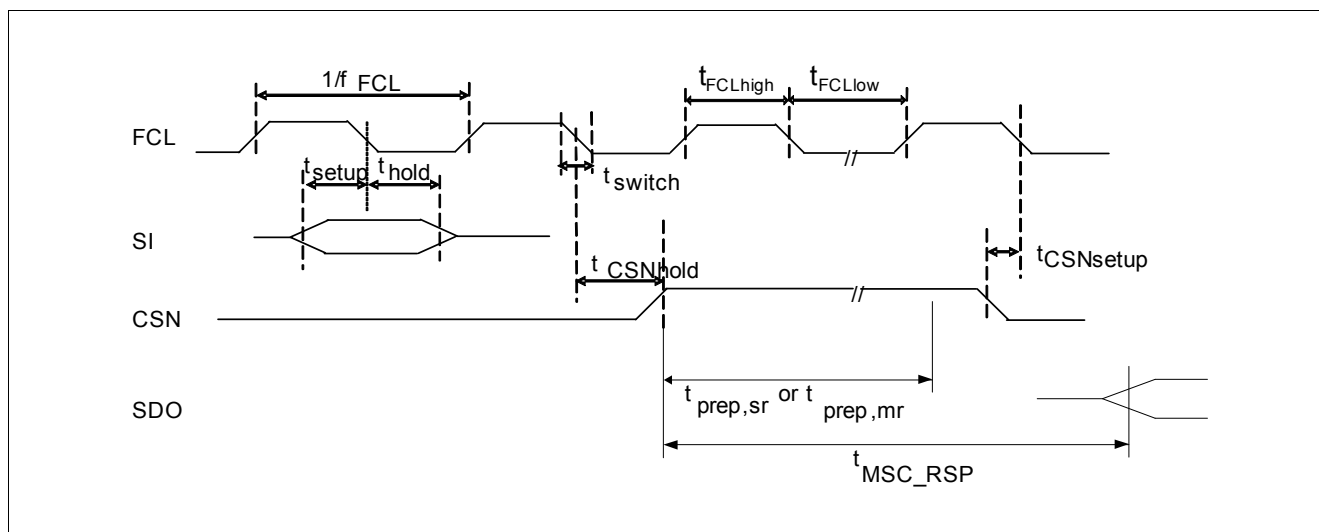


Figure 63 MSC timing

The downstream clock within the device must be active during an upstream data frame transmission (i.e. each answer to a READ command).

The upstream response time  $t_{MSC\_RSP}$  describes the time between end of read command (rising edge of CSN) to beginning of up-stream communication (falling edge of start bit).

### 13.4 Electrical Characteristics

Table 47 Electrical Characteristics: Microsecond Channel

$V_S = 13.5\text{ V}$ ,  $V_{VSV} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to ground, positive current flowing into pin (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
<b>Pin CSN</b>							
Input comparator low level	$V_{CSN\_low}$	-0.3	-	0.8			P_13.4.1
Input comparator high level	$V_{CSN\_high}$	1.6	-	5.5	V	-	P_13.4.2
Input comparator hysteresis	$V_{CSN\_hys}$	0.1	-	0.5	V	-	P_13.4.3
Input capacitance <sup>1)</sup>	$C_{CSN}$			12	pF	-	P_13.4.4
Input current Internal pull up current source to $V_{DDIO}$	$I_{CSN}$	-25	-	-3	$\mu\text{A}$	$0\text{ V} < V_{CSN} < 2\text{ V}$	P_13.4.5
<b>Pins FCLP, FCLN MSC Differential Mode</b>							
Input voltage range	$V_{FCLP}$ , $V_{FCLN}$	0.8	-	1.6	V	-	P_13.4.6



**Microsecond Channel MSC**

**Table 47 Electrical Characteristics: Microsecond Channel (cont'd)**

$V_S = 13.5\text{ V}$ ,  $V_{VSV} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to ground, positive current flowing into pin (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
Differential input high detection level, $V_{FCLx\_high} = V_{FCLP} - V_{FCLN}$	$V_{FCLx\_high}$	-	-	125	mV	-	P_13.4.7
Differential input low detection level, $V_{FCLx\_low} = V_{FCLP} - V_{FCLN}$	$V_{FCLx\_low}$	-125	-	-	mV	-	P_13.4.8
Differential input hysteresis	$V_{FCLx,hys}$	50		200	mV		P_13.4.53
Input voltage offset, $V_{FCLx\_off} = 0.5 * (V_{FCLP} + V_{FCLN})$	$V_{FCLx\_off}$	1.05	-	1.4	V	-	P_13.4.9
Differential capacitance between; FCLP and FCLN	$C_{FCLx}$	-	-	8	pF	<sup>1)</sup>	P_13.4.10
Input pull down current	$I_{FCLN}$	3	-	25	$\mu\text{A}$	$1\text{ V} < V_{FCLx} < V_{VDDIO}$	P_13.4.12

**Pins FCLP Single Ended Mode**

Input comparator low level	$V_{FLCP\_low}$	-0.3	-	0.8			P_13.4.13
Input comparator high level	$V_{FLCP\_high}$	1.6	-	5.5	V	-	P_13.4.14
Input comparator hysteresis	$V_{FLCP\_hys}$	0.1	-	0.5	V	-	P_13.4.15
Input capacitance	$C_{FLCP}$			12	pF	<sup>1)</sup>	P_13.4.16
Input pull down current	$I_{FLCP}$	3	-	25	$\mu\text{A}$	$1\text{ V} < V_{FLCP} < V_{VDDIO}$	P_13.4.17

**Clock Frequency**

FCLP, FCLN frequency	$f_{FCLx}$	-	-	23	MHz		P_13.4.18
FCL frequency single ended mode	$f_{FCL}$	-	-	12.5	MHz		P_13.4.19

**Pins SIP, SIN MSC Differential Mode**

Input voltage range	$V_{SIP}, V_{SIN}$	0.8	-	1.6	V	-	P_13.4.20
Differential input high detection level, $V_{SIX\_high} = V_{SIP} - V_{SIN}$	$V_{SIX\_high}$	-	-	125	mV	-	P_13.4.21
Differential input low detection level, $V_{SIX\_low} = V_{SIP} - V_{SIN}$	$V_{SIX\_low}$	-125	-	-	mV	-	P_13.4.22
Differential input hysteresis	$V_{SIX,hys}$	50		200	mV		P_13.4.54
Input voltage offset, $V_{SIX\_Off} = 0.5 * (V_{SIP} + V_{SIN})$	$V_{SIX\_Off}$	1.05	-	1.4	V	-	P_13.4.23
Differential capacitance between SIP and SIN	$C_{SIX}$	-	-	8	pF	<sup>1)</sup>	P_13.4.24

**Microsecond Channel MSC**

**Table 47 Electrical Characteristics: Microsecond Channel (cont'd)**

$V_S = 13.5\text{ V}$ ,  $V_{VSV} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to ground, positive current flowing into pin (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
Input pull down current	$I_{SIN}$	3	–	25	$\mu\text{A}$	$1\text{ V} < V_{SIX} < V_{VDDIO}$	P_13.4.26

**Pin SIP Single Ended Mode**

Input comparator low level	$V_{SIP\_low}$	-0.3	–	0.8			P_13.4.27
Input comparator high level	$V_{SIP\_high}$	1.6	–	5.5	V	–	P_13.4.28
Input comparator hysteresis	$V_{SIP\_hys}$	0.1	–	0.5	V	–	P_13.4.29
Input capacitance	$C_{SIP}$			12	pF	<sup>1)</sup>	P_13.4.30
Input pull down current	$I_{SIP}$	3	–	25	$\mu\text{A}$	$1\text{ V} < V_{SIP} < V_{VDDIO}$	P_13.4.31

**Pin SDO open drain set up**

SDO output low level	$V_{SDO\_low}; V_{SDO\_low}$	–	–	0.8	V	$I_{SDO} < 4\text{ mA};$	P_13.4.32
		–	–	0.4	V	$I_{SDO} < 1\text{ mA}$	P_13.4.33
SDO passive output high voltage	$V_{SDO\_high,p}$	$V_{DDIO} - 1.5$	$V_{DDIO}$	–	V	no load	P_13.4.34
Output current capability	$I_{SDO\_max}$	15 <sup>2)</sup>	–	–	mA	$V_{SDO} = 5\text{ V}$ and $V_{VDDIO} = 5\text{ V}$	P_13.4.35
SDO pull-up current source	$I_{SDO\_high}$	-50	–	-10	$\mu\text{A}$	$0\text{ V} < V_{SDO} < 2\text{ V}$ , SDO in tristate, pull up to $V_{DDIO}$	P_13.4.36
SDO (high level = inactive) pin capacity	$C_{SDO}$	–	–	10	pF	measured with bias voltage of $1\text{ V}^1)$	P_13.4.37
SDO frequency; maximum upstream frequency with external pull-up	$f_{SDO}$	500	–	–	kHz	2.2 k $\Omega$ and $C_L = 15\text{ pF}^1)$	P_13.4.38

**Pin SDO push pull set up**

SDO output low level	$V_{SDO\_low}; V_{SDO\_low}$	–	–	0.8	V	$I_{SDO} < 4\text{ mA};$	P_13.4.39
		–	–	0.4	V	$I_{SDO} < 1\text{ mA}$	P_13.4.40
SDO active output high voltage	$V_{SDO\_high,a}$	$V_{DDIO} - 0.4$	–	–	V	$I_{SDO} = 100\ \mu\text{A}$	P_13.4.41

**Timing Characteristics<sup>3)</sup>**

Data hold time	$t_{hold}$	10	–	–	ns	–	P_13.4.42
Data Setup time	$t_{setup}$	10	–	–	ns	–	P_13.4.43
Switching time	$t_{switch}$	–	–	3	ns	<sup>1)</sup>	P_13.4.44
FCL low time	$t_{FCLlow}$	13	–	–	ns	–	P_13.4.45
FCL high time	$t_{FCLhigh}$	13	–	–	ns	–	P_13.4.46

**Microsecond Channel MSC**

**Table 47 Electrical Characteristics: Microsecond Channel (cont'd)**

$V_S = 13.5\text{ V}$ ,  $V_{VSV} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to ground, positive current flowing into pin (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
CSN setup time	$t_{\text{CSNsetup}}$	10	–	–	ns	–	P_13.4.47
CSN hold time	$t_{\text{CSNhold}}$	10	–	–	ns	–	P_13.4.48
MSC data time-out monitoring	$t_{\text{MSC_mon}}$	60	–	135	$\mu\text{s}$	–	P_13.4.49
MSC upstream preparation time for single read command	$t_{\text{prep,sr}}$	–	–	$0.9 + 4 \cdot t_{\text{FCL}}$	$\mu\text{s}$		P_13.4.11
MSC upstream preparation time for multi read command	$t_{\text{prep,mr}}$	–	–	$1.8 + 4 \cdot t_{\text{FCL}}$	$\mu\text{s}$		P_13.4.25
MSC upstream response time; up-stream divider independent	$t_{\text{MSC_RSP}}$	–	–	100	$\mu\text{s}$		P_13.4.50
Required idle time after command	$t_{\text{CPP}}$	$2/f_{\text{FCL}}$ (2 clock pulses)	–	–	s	–	P_13.4.51
Required idle time after data frame	$t_{\text{DPP}}$	$2/f_{\text{FCL}}$ (2 clock pulses)	–	–	s	–	P_13.4.52

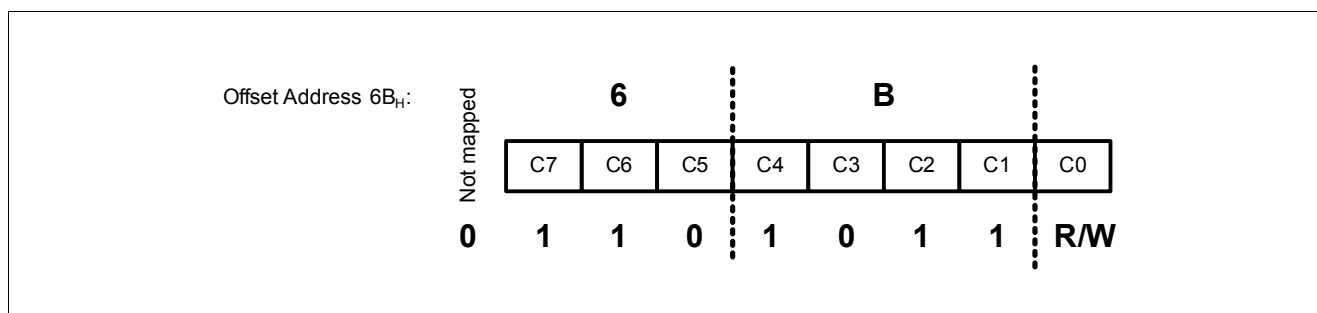
- 1) not subject to production test, specified by design
- 2) Application must ensure that current into this pin does not exceed this value.
- 3) See [Figure 57](#), [Figure 58](#) and [Figure 63](#)

## 14 Register and Commands

In [Chapter 14.1](#) to [Chapter 14.1.5](#) detailed descriptions and definitions of the registers and commands are shown. General definition for all registers and commands are described below.

### Offset Address

The offset address used for the register address is mapped to the command bits from C1 to C7. In [Figure 64](#) an example is shown. Maximum allowed address is 7F<sub>H</sub>.



**Figure 64 Mapping Offset Address to the Command Bits**

### Read Access

A read access to a register is done by sending a “0” for the bit C0 of the command frame of the MSC or the SPI frame. All register bits are updated constantly. With the positive edge of *CSN* of a valid read command the internal register information is loaded into the output shift register. The communication via *SDO* to the microcontroller is according the serial interface mode MSC or SPI. Therefore the read information is related to the time of the positive edge of *CSN*.

### Write Access

A write access to a register is done by sending a “1” for the bit C0 of the command frame of the MSC or the SPI frame or with the data frame of the MSC communication. With the positive edge of *CSN* of a valid write access for read/write register the bits are set and for command registers the defined function is executed (e.g. multiple read command).

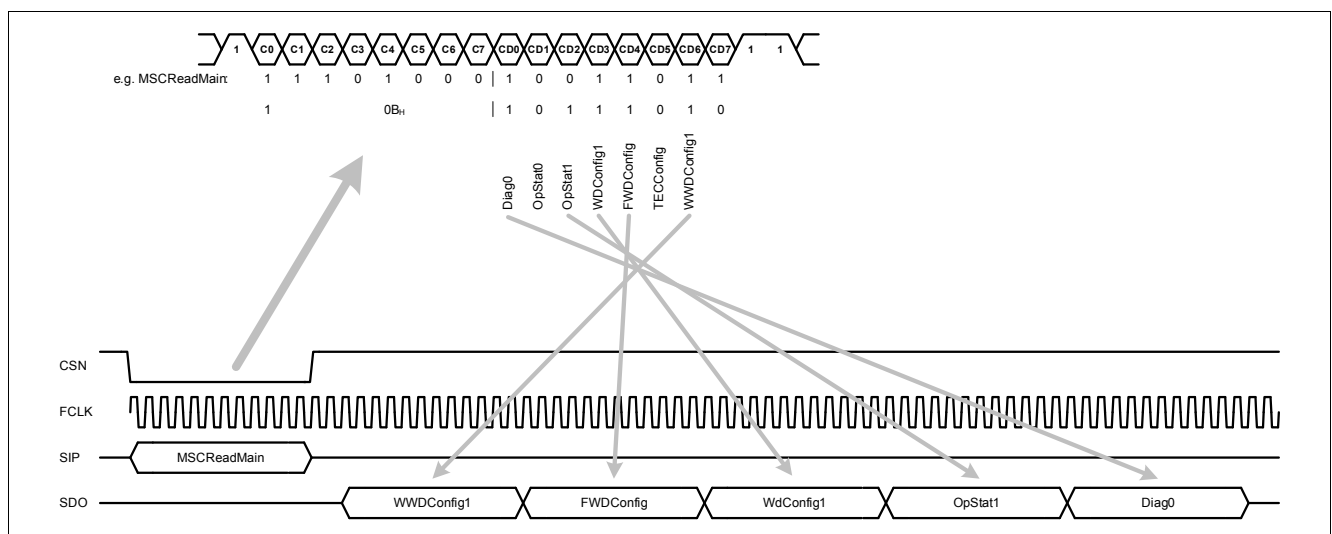
### Command Register

These registers are write only registers. Following functions are executed:

- Main relay switching with bits **MRON** and **MRSE** in command register **Cmd0**: In all states where a serial communication with the TLE8888-1QK is allowed the main relay can be switched. This is done by enabling the command with a “1” for **MRSE** and a “0” for switch off or a “1” for switch on for **MRON**. Switch off of the main relay leads for an application with supply of the ECU over the main relay path to a power-down.
- VRS diagnosis start with bit **VDIAGS** in command register **Cmd0**: With a “1” the VRS diagnosis is started. A “0” leads to no action.
- Stop of a MSC upstream communication with bit **MSCUPS** in command register **Cmd0**: With a “1” the upstream communication is stopped immediately. This leads during an upstream to invalid communication. This command is implemented to stop especially multiple read communication. A “0” leads to no action. For SPI mode this command has no effect.
- Start of the engine off timer with bit **EOTS** in command register **Cmd0**: With a “1” the engine off timer is started if the configuration is set accordingly. A “0” leads to no action.

**Register and Commands**

- Restart of the delayed off timer with bit **RDOT** in command register **Cmd0**: With a “1” the delayed off timer is reset and started again. A “0” leads to no action.
- Wake-up signal clear with bit **WKCLR** in command register **Cmd0**: With a “1” all internal wake-up signals (WKINT, CANWK, EOTWK) are reset. A “0” leads to no action.
- Response write command **FWDRespCmd** and **FWDRespSyncCmd**: With the write access to these registers the 8 bit response byte is sent to the TLE8888-1QK. The interpretation of the sent response byte is done according the description in **Chapter 6**.
- Multiple read command **MSCReadWd0** to **MSCReadWd1**: Multiple read commands are only allowed for MSC setup of the serial interface. The number of read register is defined by a “1” in the data bits of the command. The chosen register is sent in the order MSB down to LSB (see **Figure 65**). In SPI setup a multiple read command is an invalid communication. During a multi read upstream read commands are ignored, write commands are allowed. To stop an upstream operation use the command **MSCUPS**.
- Software reset command **CmdSR**: With the execution of this command the software reset of the TLE8888-1QK is performed according **Table 6** in **Chapter 5**.
- Central output enable command **CmdOE**: With the execution of this command the central output enable bit is set or reset. For the description of the functionality see **Chapter 9.2**. The status of the central enable bit is available in register **OpStat1**.
- Lock command **CmdLOCK**: With the execution of this command the lock bit is set or reset. This bit is used to lock some configuration registers (see **Table 49**) to avoid a change of these register e.g. during operation. The status of the lock bit is available in register **OpStat1**.



**Figure 65 Example of a Multi read Command**

**Diagnosis Register**

The diagnosis register bits are set according the asynchronous detection circuits. The reset of the diagnosis bits is done with the read out of the registers if the failure condition is not detected anymore.

**Central Overtemperature Bit COT in Diagnosis Register Diag0**

The central overtemperature bit is an OR combination of all overtemperature detection signals which leads to active diagnosis bits. With at least one active overtemperature diagnosis the central overtemperature bit is “1”, with no active overtemperature diagnosis this bit is “0”. All other diagnosis signals doesn’t change the status of the central overtemperature bit.

**Register and Commands**

**Central Failure Bit CF in Diagnosis Register Diag0**

The central failure bit is an OR combination of diagnosis bits (see [Table 48](#)). If one or more of these diagnosis bits are active then the central failure bit is “1”. If all are inactive the central failure bit is “0”. The overtemperature diagnosis doesn’t change the status of the central failure bit.

**Table 48 Overview of Diagnosis Registers an Bits affecting the Central Failure Bit**

Register	Offset	Bit(s)	Note
<b>ComDiag</b>	<b>024<sub>H</sub></b>	<b>MSCTO, COMFE, CANBDC, CANTXTO</b>	
<b>OutDiag0 to OutDiag4</b>	<b>026<sub>H</sub> to 029<sub>H</sub></b>	all bits	central failure bit not set if only overtemperature is detected
<b>PPOVDiag</b>	<b>02A<sub>H</sub></b>	all bits	
<b>BriDiag0</b>	<b>02B<sub>H</sub></b>	all bits	
<b>BriDiag1</b>	<b>02C<sub>H</sub></b>	only overcurrent bits	
<b>IgnDiag</b>	<b>02D<sub>H</sub></b>	all bits	
<b>WdDiag</b>	<b>02E<sub>H</sub></b>	<b>WWDTO, WWDSCE, FWDREL, FWDREA</b>	

**Engine Off Timer Register EOTStat0 to EOTStat2, EOTConfig0 and EOTConfig1**

These register are located in the standby block and are supplied by the standby supply. They are not reset with the power on reset of the digital block.

**Registers affected by the Lock Bit**

**Table 49 Overview of Register affected by the Lock Bit**

Register	Offset
<b>OutConfig0</b>	<b>040<sub>H</sub></b>
<b>OutConfig1</b>	<b>041<sub>H</sub></b>
<b>OutConfig2</b>	<b>042<sub>H</sub></b>
<b>OutConfig3</b>	<b>043<sub>H</sub></b>
<b>OutConfig4</b>	<b>044<sub>H</sub></b>
<b>OutConfig5</b>	<b>045<sub>H</sub></b>
<b>BriConfig0</b>	<b>046<sub>H</sub></b>
<b>BriConfig1</b>	<b>047<sub>H</sub></b>
<b>IGNConfig</b>	<b>048<sub>H</sub></b>
<b>VRSCConfig1</b>	<b>04A<sub>H</sub></b>
<b>VRSCConfig2</b>	<b>04B<sub>H</sub></b>
<b>OpConfig0</b>	<b>04E<sub>H</sub></b>
<b>ComConfig0</b>	<b>04F<sub>H</sub></b>
<b>ComConfig1</b>	<b>050<sub>H</sub></b>

**Register and Commands**

**Table 49 Overview of Register affected by the Lock Bit (cont'd)**

<b>Register</b>	<b>Offset</b>
<b>EOTConfig0</b>	<b>051<sub>H</sub></b>
<b>EOTConfig1</b>	<b>052<sub>H</sub></b>
<b>InConfig0</b>	<b>053<sub>H</sub></b>
<b>InConfig1</b>	<b>054<sub>H</sub></b>
<b>InConfig2</b>	<b>055<sub>H</sub></b>
<b>InConfig3</b>	<b>056<sub>H</sub></b>
<b>DDConfig0</b>	<b>057<sub>H</sub></b>
<b>DDConfig1</b>	<b>058<sub>H</sub></b>
<b>DDConfig2</b>	<b>059<sub>H</sub></b>
<b>DDConfig3</b>	<b>05A<sub>H</sub></b>
<b>WDConfig1</b>	<b>064<sub>H</sub></b>

## 14.1 Register Table

**Table 50 Register Overview**

Register Short Name	Register Long Name	Offset Address	Reset Value
Cmd0		001 <sub>H</sub>	00 <sub>H</sub>
MSCReadWd0		003 <sub>H</sub>	00 <sub>H</sub>
MSCReadDiag0EOT		004 <sub>H</sub>	00 <sub>H</sub>
MSCReadDiag1		005 <sub>H</sub>	00 <sub>H</sub>
MSCReadCont		006 <sub>H</sub>	00 <sub>H</sub>
MSCReadConfig0		007 <sub>H</sub>	00 <sub>H</sub>
MSCReadConfig1		008 <sub>H</sub>	00 <sub>H</sub>
MSCReadConfig2		009 <sub>H</sub>	00 <sub>H</sub>
MSCReadOEConfig		00A <sub>H</sub>	00 <sub>H</sub>
MSCReadMain		00B <sub>H</sub>	00 <sub>H</sub>
MSCReadWd1		00C <sub>H</sub>	00 <sub>H</sub>
WWDSERVICECmd		015 <sub>H</sub>	00 <sub>H</sub>
FWDRespCmd		016 <sub>H</sub>	00 <sub>H</sub>
FWDRespSyncCmd		017 <sub>H</sub>	00 <sub>H</sub>
WDHBTPSyncCmd		018 <sub>H</sub>	00 <sub>H</sub>
CmdSR		01A <sub>H</sub>	00 <sub>H</sub>
CmdOE		01C <sub>H</sub>	00 <sub>H</sub>
CmdLOCK		01E <sub>H</sub>	00 <sub>H</sub>
Diag0		020 <sub>H</sub>	00 <sub>H</sub>
Diag1		021 <sub>H</sub>	00 <sub>H</sub>
VRSDiag0		022 <sub>H</sub>	00 <sub>H</sub>
VRSDiag1		023 <sub>H</sub>	00 <sub>H</sub>
ComDiag		024 <sub>H</sub>	00 <sub>H</sub>
OutDiag0		025 <sub>H</sub>	00 <sub>H</sub>
OutDiag1		026 <sub>H</sub>	00 <sub>H</sub>
OutDiag2		027 <sub>H</sub>	00 <sub>H</sub>
OutDiag3		028 <sub>H</sub>	00 <sub>H</sub>
OutDiag4		029 <sub>H</sub>	00 <sub>H</sub>
PPOVDiag		02A <sub>H</sub>	00 <sub>H</sub>
BriDiag0		02B <sub>H</sub>	00 <sub>H</sub>
BriDiag1		02C <sub>H</sub>	00 <sub>H</sub>
IgnDiag		02D <sub>H</sub>	00 <sub>H</sub>
WdDiag		02E <sub>H</sub>	00 <sub>H</sub>
EOTStat0		031 <sub>H</sub>	00 <sub>H</sub>



**Table 50 Register Overview (cont'd)**

<b>Register Short Name</b>	<b>Register Long Name</b>	<b>Offset Address</b>	<b>Reset Value</b>
<b>EOTStat1</b>		032 <sub>H</sub>	00 <sub>H</sub>
<b>EOTStat2</b>		033 <sub>H</sub>	00 <sub>H</sub>
<b>OpStat0</b>		034 <sub>H</sub>	00 <sub>H</sub>
<b>OpStat1</b>		035 <sub>H</sub>	00 <sub>H</sub>
<b>WWDStat</b>		036 <sub>H</sub>	30 <sub>H</sub>
<b>FWDStat0</b>		037 <sub>H</sub>	30 <sub>H</sub>
<b>FWDStat1</b>		038 <sub>H</sub>	30 <sub>H</sub>
<b>TECStat</b>		039 <sub>H</sub>	30 <sub>H</sub>
<b>WdStat0</b>		03A <sub>H</sub>	00 <sub>H</sub>
<b>WdStat1</b>		03B <sub>H</sub>	00 <sub>H</sub>
<b>WDHBT0</b>		03C <sub>H</sub>	00 <sub>H</sub>
<b>WDHBT1</b>		03D <sub>H</sub>	00 <sub>H</sub>
<b>OutConfig0</b>		040 <sub>H</sub>	FF <sub>H</sub>
<b>OutConfig1</b>		041 <sub>H</sub>	3F <sub>H</sub>
<b>OutConfig2</b>		042 <sub>H</sub>	3F <sub>H</sub>
<b>OutConfig3</b>		043 <sub>H</sub>	30 <sub>H</sub>
<b>OutConfig4</b>		044 <sub>H</sub>	3F <sub>H</sub>
<b>OutConfig5</b>		045 <sub>H</sub>	3F <sub>H</sub>
<b>BriConfig0</b>		046 <sub>H</sub>	00 <sub>H</sub>
<b>BriConfig1</b>		047 <sub>H</sub>	00 <sub>H</sub>
<b>IGNConfig</b>		048 <sub>H</sub>	00 <sub>H</sub>
<b>VRSConfig0</b>		049 <sub>H</sub>	00 <sub>H</sub>
<b>VRSConfig1</b>		04A <sub>H</sub>	00 <sub>H</sub>
<b>VRSConfig2</b>		04B <sub>H</sub>	00 <sub>H</sub>
<b>OpConfig0</b>		04E <sub>H</sub>	09 <sub>H</sub>
<b>ComConfig0</b>		04F <sub>H</sub>	A4 <sub>H</sub>
<b>ComConfig1</b>		050 <sub>H</sub>	0D <sub>H</sub>
<b>EOTConfig0</b>		051 <sub>H</sub>	00 <sub>H</sub>
<b>EOTConfig1</b>		052 <sub>H</sub>	00 <sub>H</sub>
<b>InConfig0</b>		053 <sub>H</sub>	00 <sub>H</sub>
<b>InConfig1</b>		054 <sub>H</sub>	00 <sub>H</sub>
<b>InConfig2</b>		055 <sub>H</sub>	00 <sub>H</sub>
<b>InConfig3</b>		056 <sub>H</sub>	00 <sub>H</sub>
<b>DDConfig0</b>		057 <sub>H</sub>	00 <sub>H</sub>
<b>DDConfig1</b>		058 <sub>H</sub>	00 <sub>H</sub>
<b>DDConfig2</b>		059 <sub>H</sub>	00 <sub>H</sub>
<b>DDConfig3</b>		05A <sub>H</sub>	00 <sub>H</sub>
<b>OEConfig0</b>		05B <sub>H</sub>	00 <sub>H</sub>

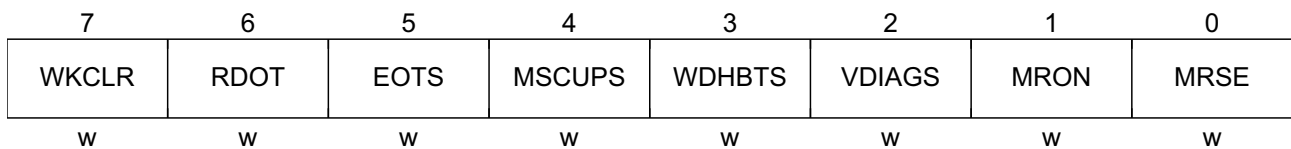
**Table 50 Register Overview (cont'd)**

Register Short Name	Register Long Name	Offset Address	Reset Value
OEConfig1		05C <sub>H</sub>	00 <sub>H</sub>
OEConfig2		05D <sub>H</sub>	00 <sub>H</sub>
OEConfig3		05E <sub>H</sub>	00 <sub>H</sub>
WWDConfig0		05F <sub>H</sub>	FF <sub>H</sub>
WWDConfig1		060 <sub>H</sub>	77 <sub>H</sub>
FWDConfig		061 <sub>H</sub>	F7 <sub>H</sub>
TECConfig		062 <sub>H</sub>	77 <sub>H</sub>
WDConfig0		063 <sub>H</sub>	47 <sub>H</sub>
WDConfig1		064 <sub>H</sub>	03 <sub>H</sub>
Cont0		07B <sub>H</sub>	00 <sub>H</sub>
Cont1		07C <sub>H</sub>	00 <sub>H</sub>
Cont2		07D <sub>H</sub>	00 <sub>H</sub>
Cont3		07E <sub>H</sub>	00 <sub>H</sub>

The registers are addressed wordwise.

### 14.1.1 Command Register

**Cmd0** **Offset** **Reset Value**  
001<sub>H</sub> 00<sub>H</sub>



Field	Bits	Type	Description
WKCLR	7	w	<b>Wake-up Signal Clear Command:</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , initiated clear of internal wake signals Reset: 0 <sub>B</sub>

Field	Bits	Type	Description
<b>RDOT</b>	6	w	<b>Restart Delayed off Timer Command:</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , delayed off timer is restarted Reset: 0 <sub>B</sub>
<b>EOTS</b>	5	w	<b>Engine Off Timer Start Command:</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , start counter Reset: 0 <sub>B</sub>
<b>MSCUPS</b>	4	w	<b>MSC Upstream Stop Bit Command:</b> 0 <sub>B</sub> , no influence to upstream transmission 1 <sub>B</sub> , upstream communication is stopped Reset: 0 <sub>B</sub>
<b>WDHBT5</b>	3	w	<b>Watchdog Heartbeat Timer Sample Command:</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , Watchdog Heartbeat Timer sampled (WDHBT0 and WDHBT1) Reset: 0 <sub>B</sub>
<b>VDIAGS</b>	2	w	<b>VRS Diagnosis Measurement Start Command:</b> 0 <sub>B</sub> , no measurement 1 <sub>B</sub> , start of VRS diagnosis measurement Reset: 0 <sub>B</sub>
<b>MRON</b>	1	w	<b>Main Relay On Command (active if MRSE = 1):</b> 0 <sub>B</sub> , initiated main relay is switched off 1 <sub>B</sub> , initiated main relay is switched on Reset: 0 <sub>B</sub>
<b>MRSE</b>	0	w	<b>Main Relay Switching Enable:</b> 0 <sub>B</sub> , main relay switching by bit MRON not enabled 1 <sub>B</sub> , main relay switching enabled: value of MRON executed Reset: 0 <sub>B</sub>

**MSCReadWd0**

**Offset**  
003<sub>H</sub>

**Reset Value**  
00<sub>H</sub>

7	6	5	4	3	2	1	0
WWDCONF IG0	WDCONFI G0	WWDSTAT	WDDIAG	FWDSTAT 1	FWDSTAT 0	TECSTAT	WDSTAT0
w	w	w	w	w	w	w	w

Field	Bits	Type	Description
<b>WWDCONFIG0</b>	7	w	<b>Read Status Register WWDConfig0</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , multi read operation executed (order MSB to LSB) Reset: 0 <sub>B</sub>
<b>WDCONFIG0</b>	6	w	<b>Read Status Register WDConfig0</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , multi read operation executed (order MSB to LSB) Reset: 0 <sub>B</sub>
<b>WWDSTAT</b>	5	w	<b>Read Status Register WWDStat</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , multi read operation executed (order MSB to LSB) Reset: 0 <sub>B</sub>
<b>WDDIAG</b>	4	w	<b>Read Configuration Register WdDiag</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , multi read operation executed (order MSB to LSB) Reset: 0 <sub>B</sub>
<b>FWDSTAT1</b>	3	w	<b>Read Configuration Register FWDStat1</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , multi read operation executed (order MSB to LSB) Reset: 0 <sub>B</sub>
<b>FWDSTAT0</b>	2	w	<b>Read Diagnosis Register FWDStat0</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , multi read operation executed (order MSB to LSB) Reset: 0 <sub>B</sub>
<b>TECSTAT</b>	1	w	<b>Read Diagnosis Register TECStat</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , multi read operation executed (order MSB to LSB) Reset: 0 <sub>B</sub>
<b>WDSTAT0</b>	0	w	<b>Read Status Register WdStat0</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , multi read operation executed (order MSB to LSB) Reset: 0 <sub>B</sub>

**MSCReadDiag0EOT**

**Offset**  
**004<sub>H</sub>**

**Reset Value**  
**00<sub>H</sub>**

7	6	5	4	3	2	1	0
PPOVDIAG	DIAG1	EOTSTAT 2	EOTSTAT 1	EOTSTAT 0	COMDIAG	VRSDIAG 1	VRSDIAG 0
w	w	w	w	w	w	w	w

Field	Bits	Type	Description
<b>PPOVDIAG</b>	7	w	<b>Read Diagnosis Register PPOVDiag</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , multi read operation executed (order MSB to LSB) Reset: 0 <sub>B</sub>
<b>DIAG1</b>	6	w	<b>Read Diagnosis Register Diag1</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , multi read operation executed (order MSB to LSB) Reset: 0 <sub>B</sub>
<b>EOTSTAT2</b>	5	w	<b>Read Status Register EOTStat2</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , multi read operation executed (order MSB to LSB) Reset: 0 <sub>B</sub>
<b>EOTSTAT1</b>	4	w	<b>Read Status Register EOTStat1</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , multi read operation executed (order MSB to LSB) Reset: 0 <sub>B</sub>
<b>EOTSTAT0</b>	3	w	<b>Read Status Register EOTStat0</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , multi read operation executed (order MSB to LSB) Reset: 0 <sub>B</sub>
<b>COMDIAG</b>	2	w	<b>Read Diagnosis Register ComDiag</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , multi read operation executed (order MSB to LSB) Reset: 0 <sub>B</sub>
<b>VRSDIAG1</b>	1	w	<b>Read Diagnosis Register VRSDiag1</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , multi read operation executed (order MSB to LSB) Reset: 0 <sub>B</sub>
<b>VRSDIAG0</b>	0	w	<b>Read Diagnosis Register VRSDiag0</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , multi read operation executed (order MSB to LSB) Reset: 0 <sub>B</sub>

**MSCReadDiag1**

**Offset**  
**005<sub>H</sub>**

**Reset Value**  
**00<sub>H</sub>**

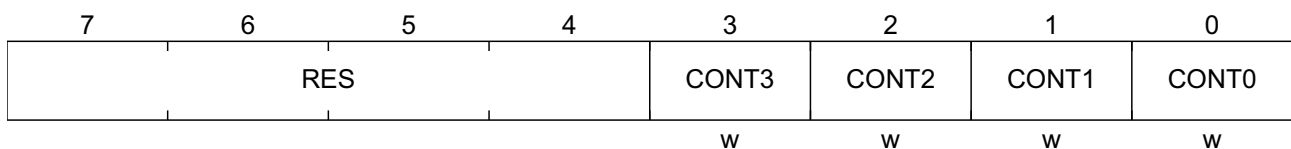
7	6	5	4	3	2	1	0
IGNDIAG	BRIDIAG 1	BRIDIAG 0	OUTDIAG 4	OUTDIAG 3	OUTDIAG 2	OUTDIAG 1	OUTDIAG 0
w	w	w	w	w	w	w	w

Field	Bits	Type	Description
<b>IGNDIAG</b>	7	w	<b>Read Diagnosis Register IgnDiag</b> $0_B$ , no action $1_B$ , multi read operation executed (order MSB to LSB) Reset: $0_B$
<b>BRIDIAG1</b>	6	w	<b>Read Diagnosis Register BriDiag1</b> $0_B$ , no action $1_B$ , multi read operation executed (order MSB to LSB) Reset: $0_B$
<b>BRIDIAG0</b>	5	w	<b>Read Diagnosis Register BriDiag0</b> $0_B$ , no action $1_B$ , multi read operation executed (order MSB to LSB) Reset: $0_B$
<b>OUTDIAG4</b>	4	w	<b>Read Diagnosis Register OutDiag4</b> $0_B$ , no action $1_B$ , multi read operation executed (order MSB to LSB) Reset: $0_B$
<b>OUTDIAG3</b>	3	w	<b>Read Diagnosis Register OutDiag3</b> $0_B$ , no action $1_B$ , multi read operation executed (order MSB to LSB) Reset: $0_B$
<b>OUTDIAG2</b>	2	w	<b>Read Diagnosis Register OutDiag2</b> $0_B$ , no action $1_B$ , multi read operation executed (order MSB to LSB) Reset: $0_B$
<b>OUTDIAG1</b>	1	w	<b>Read Diagnosis Register OutDiag1</b> $0_B$ , no action $1_B$ , multi read operation executed (order MSB to LSB) Reset: $0_B$
<b>OUTDIAG0</b>	0	w	<b>Read Diagnosis Register OutDiag0</b> $0_B$ , no action $1_B$ , multi read operation executed (order MSB to LSB) Reset: $0_B$

**MSCReadCont**

**Offset**  
**006<sub>H</sub>**

**Reset Value**  
**00<sub>H</sub>**



Field	Bits	Type	Description
<b>CONT3</b>	3	w	<b>Read Control Register Cont3</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , multi read operation executed (order MSB to LSB) Reset: 0 <sub>B</sub>
<b>CONT2</b>	2	w	<b>Read Control Register Cont2</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , multi read operation executed (order MSB to LSB) Reset: 0 <sub>B</sub>
<b>CONT1</b>	1	w	<b>Read Control Register Cont1</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , multi read operation executed (order MSB to LSB) Reset: 0 <sub>B</sub>
<b>CONT0</b>	0	w	<b>Read Control Register Cont0</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , multi read operation executed (order MSB to LSB) Reset: 0 <sub>B</sub>

**MSCReadConfig0**

**Offset**  
007<sub>H</sub>

**Reset Value**  
00<sub>H</sub>

7	6	5	4	3	2	1	0
BRICONF IG1	BRICONF IG0	OUTCONF IG5	OUTCONF IG4	OUTCONF IG3	OUTCONF IG2	OUTCONF IG1	OUTCONF IG0
w	w	w	w	w	w	w	w

Field	Bits	Type	Description
<b>BRICONFIG1</b>	7	w	<b>Read Configuration Register BriConfig1</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , multi read operation executed (order MSB to LSB) Reset: 0 <sub>B</sub>
<b>BRICONFIG0</b>	6	w	<b>Read Configuration Register BriConfig0</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , multi read operation executed (order MSB to LSB) Reset: 0 <sub>B</sub>
<b>OUTCONFIG5</b>	5	w	<b>Read Configuration Register OutConfig5</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , multi read operation executed (order MSB to LSB) Reset: 0 <sub>B</sub>

Field	Bits	Type	Description
<b>OUTCONFIG4</b>	4	w	<b>Read Configuration Register OutConfig4</b> $0_B$ , no action $1_B$ , multi read operation executed (order MSB to LSB) Reset: $0_B$
<b>OUTCONFIG3</b>	3	w	<b>Read Configuration Register OutConfig3</b> $0_B$ , no action $1_B$ , multi read operation executed (order MSB to LSB) Reset: $0_B$
<b>OUTCONFIG2</b>	2	w	<b>Read Configuration Register OutConfig2</b> $0_B$ , no action $1_B$ , multi read operation executed (order MSB to LSB) Reset: $0_B$
<b>OUTCONFIG1</b>	1	w	<b>Read Configuration Register OutConfig1</b> $0_B$ , no action $1_B$ , multi read operation executed (order MSB to LSB) Reset: $0_B$
<b>OUTCONFIG0</b>	0	w	<b>Read Configuration Register OutConfig0</b> $0_B$ , no action $1_B$ , multi read operation executed (order MSB to LSB) Reset: $0_B$

<b>MSCReadConfig1</b>								<b>Offset</b>	<b>Reset Value</b>
								<b>008<sub>H</sub></b>	<b>00<sub>H</sub></b>
7	6	5	4	3	2	1	0		
EOTCONF IG1	EOTCONF IG0	VRSCONF IG1	VRSCONF IG0	OPCONFI G0	COMCONF IG1	COMCONF IG0	IGNCONF IG		
w	w	w	w	w	w	w	w		

Field	Bits	Type	Description
<b>EOTCONFIG1</b>	7	w	<b>Read Configuration Register EOTConfig1</b> $0_B$ , no action $1_B$ , multi read operation executed (order MSB to LSB) Reset: $0_B$
<b>EOTCONFIG0</b>	6	w	<b>Read Configuration Register EOTConfig0</b> $0_B$ , no action $1_B$ , multi read operation executed (order MSB to LSB) Reset: $0_B$



Field	Bits	Type	Description
<b>VRSCONFIG1</b>	5	w	<b>Read Configuration Register VRSConfig1</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , multi read operation executed (order MSB to LSB) Reset: 0 <sub>B</sub>
<b>VRSCONFIG0</b>	4	w	<b>Read Configuration Register VRSConfig0</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , multi read operation executed (order MSB to LSB) Reset: 0 <sub>B</sub>
<b>OPCONFIG0</b>	3	w	<b>Read Configuration Register OpConfig0</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , multi read operation executed (order MSB to LSB) Reset: 0 <sub>B</sub>
<b>COMCONFIG1</b>	2	w	<b>Read Configuration Register ComConfig1</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , multi read operation executed (order MSB to LSB) Reset: 0 <sub>B</sub>
<b>COMCONFIG0</b>	1	w	<b>Read Configuration Register ComConfig0</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , multi read operation executed (order MSB to LSB) Reset: 0 <sub>B</sub>
<b>IGNCONFIG</b>	0	w	<b>Read Configuration Register IGNConfig</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , multi read operation executed (order MSB to LSB) Reset: 0 <sub>B</sub>

**MSCReadConfig2** **Offset** **Reset Value**  
**009<sub>H</sub>** **00<sub>H</sub>**

7	6	5	4	3	2	1	0
INCONFI G3	INCONFI G2	INCONFI G1	INCONFI G0	DDCONFI G3	DDCONFI G2	DDCONFI G1	DDCONFI G0
w	w	w	w	w	w	w	w

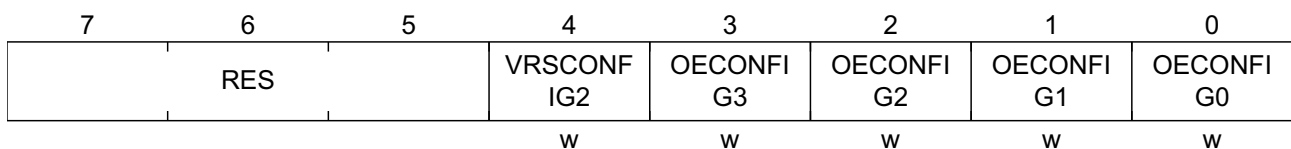
Field	Bits	Type	Description
<b>INCONFIG3</b>	7	w	<b>Read Configuration Register InConfig3</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , multi read operation executed (order MSB to LSB) Reset: 0 <sub>B</sub>

Field	Bits	Type	Description
<b>INCONFIG2</b>	6	w	<b>Read Configuration Register InConfig2</b> $0_B$ , no action $1_B$ , multi read operation executed (order MSB to LSB) Reset: $0_B$
<b>INCONFIG1</b>	5	w	<b>Read Configuration Register InConfig1</b> $0_B$ , no action $1_B$ , multi read operation executed (order MSB to LSB) Reset: $0_B$
<b>INCONFIG0</b>	4	w	<b>Read Configuration Register InConfig0</b> $0_B$ , no action $1_B$ , multi read operation executed (order MSB to LSB) Reset: $0_B$
<b>DDCONFIG3</b>	3	w	<b>Read Configuration Register DDConfig3</b> $0_B$ , no action $1_B$ , multi read operation executed (order MSB to LSB) Reset: $0_B$
<b>DDCONFIG2</b>	2	w	<b>Read Configuration Register DDConfig2</b> $0_B$ , no action $1_B$ , multi read operation executed (order MSB to LSB) Reset: $0_B$
<b>DDCONFIG1</b>	1	w	<b>Read Configuration Register DDConfig1</b> $0_B$ , no action $1_B$ , multi read operation executed (order MSB to LSB) Reset: $0_B$
<b>DDCONFIG0</b>	0	w	<b>Read Configuration Register DDConfig0</b> $0_B$ , no action $1_B$ , multi read operation executed (order MSB to LSB) Reset: $0_B$

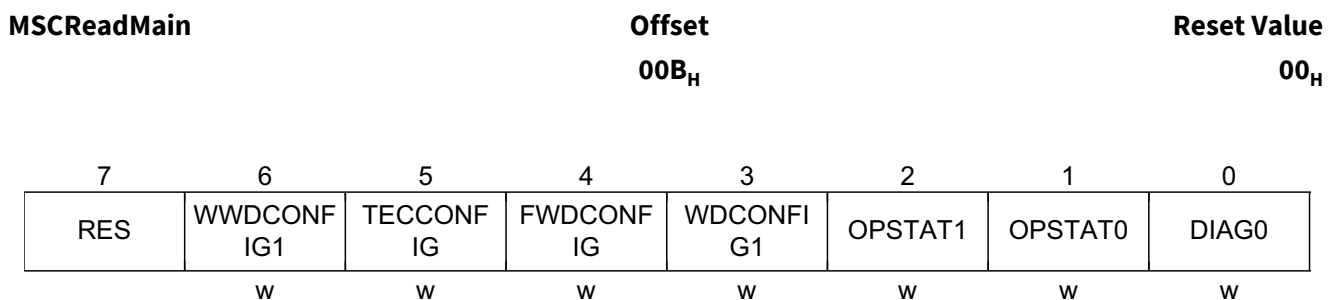
**MSCReadOEConfig**

**Offset**  
**00A<sub>H</sub>**

**Reset Value**  
**00<sub>H</sub>**



Field	Bits	Type	Description
<b>VRSCONFIG2</b>	4	w	<b>Read Configuration Register VRSConfig2</b> $0_B$ , no action $1_B$ , multi read operation executed (order MSB to LSB) Reset: $0_B$
<b>OECONFIG3</b>	3	w	<b>Read Configuration Register OEConfig3</b> $0_B$ , no action $1_B$ , multi read operation executed (order MSB to LSB) Reset: $0_B$
<b>OECONFIG2</b>	2	w	<b>Read Configuration Register OEConfig2</b> $0_B$ , no action $1_B$ , multi read operation executed (order MSB to LSB) Reset: $0_B$
<b>OECONFIG1</b>	1	w	<b>Read Configuration Register OEConfig1</b> $0_B$ , no action $1_B$ , multi read operation executed (order MSB to LSB) Reset: $0_B$
<b>OECONFIG0</b>	0	w	<b>Read Configuration Register OEConfig0</b> $0_B$ , no action $1_B$ , multi read operation executed (order MSB to LSB) Reset: $0_B$

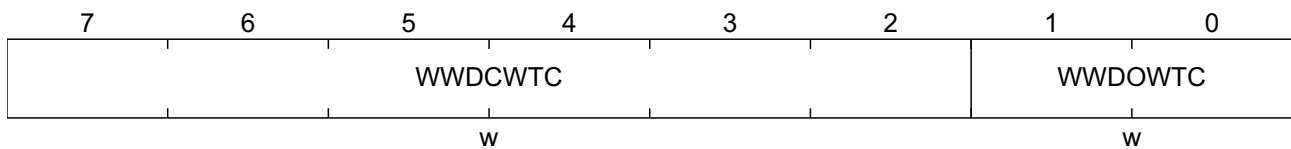


Field	Bits	Type	Description
<b>WWDCONFIG1</b>	6	w	<b>Read Status Register WWDConfig1</b> $0_B$ , no action $1_B$ , multi read operation executed (order MSB to LSB) Reset: $0_B$
<b>TECCONFIG</b>	5	w	<b>Read Status Register TECConfig</b> $0_B$ , no action $1_B$ , multi read operation executed (order MSB to LSB) Reset: $0_B$



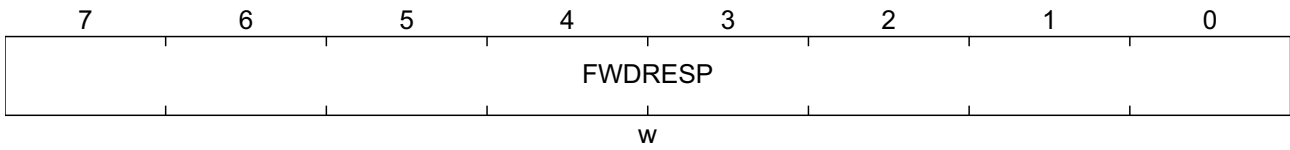
Field	Bits	Type	Description
WDHBT1	1	w	<b>Read Status Register WDHBT1</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , multi read operation executed (order MSB to LSB) Reset: 0 <sub>B</sub>
WDHBT0	0	w	<b>Read Status Register WDHBT0</b> 0 <sub>B</sub> , no action 1 <sub>B</sub> , multi read operation executed (order MSB to LSB) Reset: 0 <sub>B</sub>

**WWDServiceCmd** **Offset** **Reset Value**  
**015<sub>H</sub>** **00<sub>H</sub>**



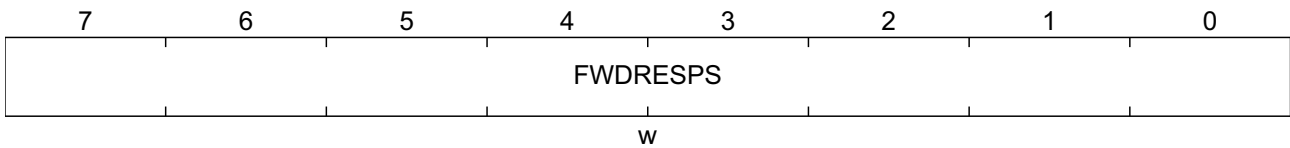
Field	Bits	Type	Description
WDCWTC	7:2	w	<b>Window Watchdog Closed Window Time Write Command:</b> Set WDCWT in register WWDConfig0 000000 <sub>B</sub> , no change - old setting used for open and closed window 000001 <sub>B</sub> , 1,6 ms 111111 <sub>B</sub> , 100,8 ms Reset: 000000 <sub>B</sub>
WDWT	1:0	w	<b>Window Watchdog Open Window Time Write Command:</b> Set WDWOT in register WWDConfig0 00 <sub>B</sub> , 3,2 ms 01 <sub>B</sub> , 6,4 ms 10 <sub>B</sub> , 9,6 ms 11 <sub>B</sub> , 12,8 ms Reset: 00 <sub>B</sub>

**FWDRespCmd** **Offset** **Reset Value**  
**016<sub>H</sub>** **00<sub>H</sub>**



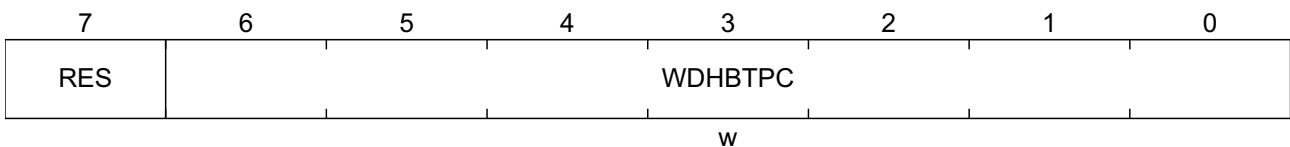
Field	Bits	Type	Description
FWDRESP	7:0	w	Functional Watchdog Response Byte Write Command Reset: 00 <sub>H</sub>

**FWDRespSyncCmd** **Offset** **Reset Value**  
**017<sub>H</sub>** **00<sub>H</sub>**

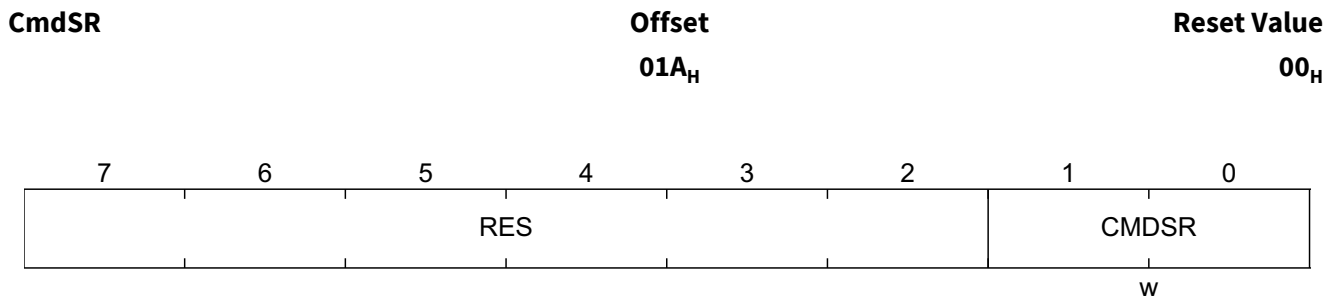


Field	Bits	Type	Description
FWDRESPS	7:0	w	Functional Watchdog Response Byte Write and Heartbeat Synchronisation Command Reset: 00 <sub>H</sub>

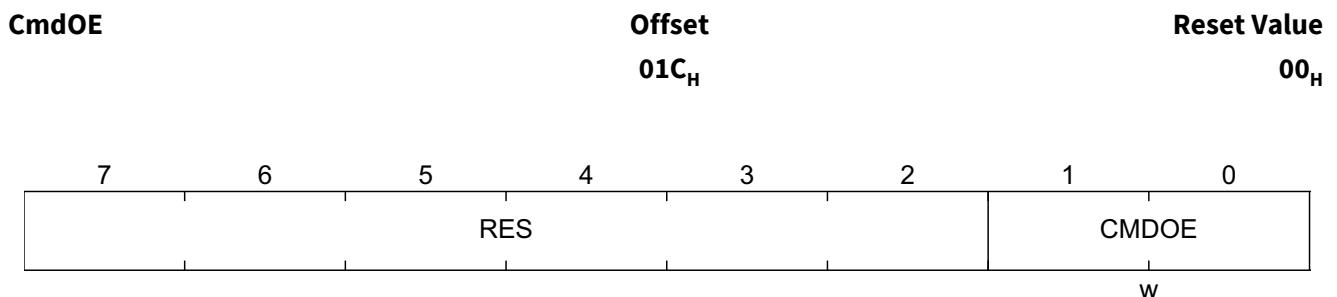
**WDHBTPSyncCmd** **Offset** **Reset Value**  
**018<sub>H</sub>** **00<sub>H</sub>**



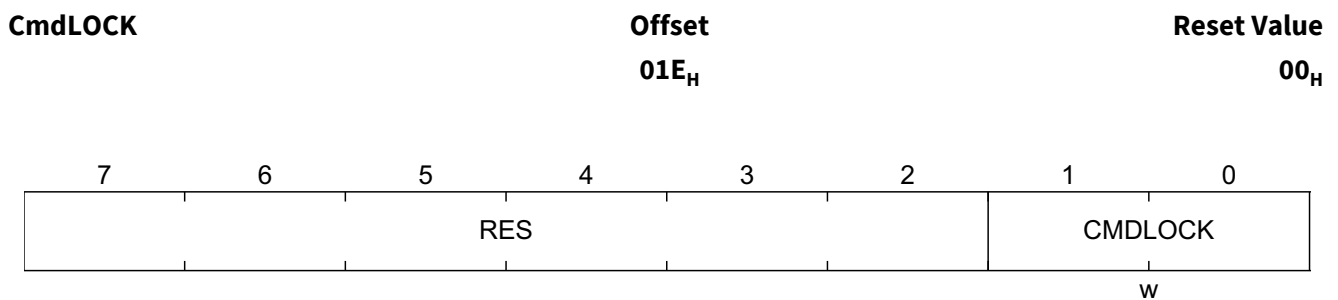
Field	Bits	Type	Description
WDHBTPC	6:0	w	<b>Heartbeat Timer Period Write and Synchronisation Command:</b> Set WDHBTP in register WDCConfig0 0000000 <sub>B</sub> , no change 0000001 <sub>B</sub> , 1,6 ms 0000010 <sub>B</sub> , 3,2 ms 1111111 <sub>B</sub> , 203,2 ms Reset: 0000000 <sub>B</sub>



Field	Bits	Type	Description
CMDSR	1:0	w	<b>Software Reset Command</b> 00 <sub>B</sub> , No action 01 <sub>B</sub> , No action 10 <sub>B</sub> , No action 11 <sub>B</sub> , Initiate software reset Reset: 00 <sub>B</sub>

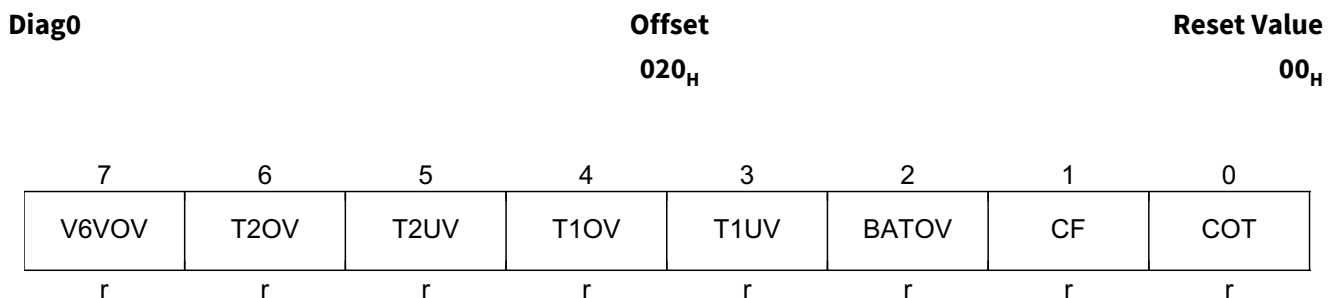


Field	Bits	Type	Description
<b>CMDOE</b>	1:0	w	<b>Global Output Enable Command</b> 00 <sub>B</sub> , No action 01 <sub>B</sub> , Set Bit OE to 0 10 <sub>B</sub> , Set Bit OE to 1 11 <sub>B</sub> , No action Reset: 00 <sub>B</sub>



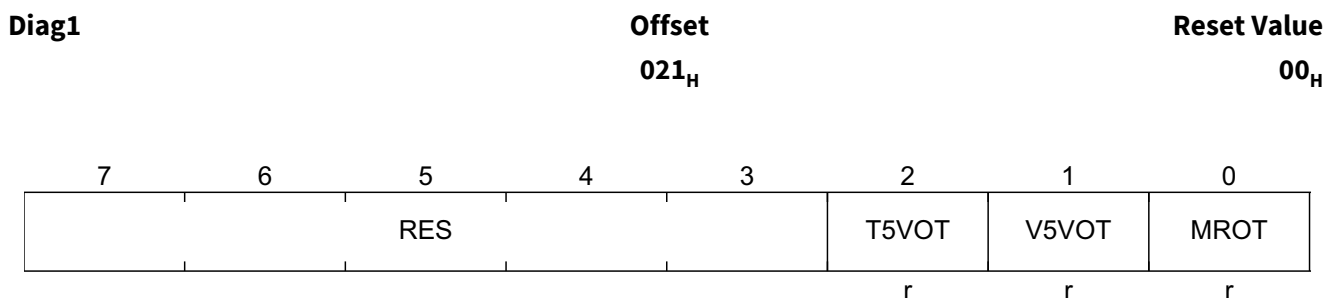
Field	Bits	Type	Description
<b>CMDLOCK</b>	1:0	w	<b>Configuration Lock Command</b> 00 <sub>B</sub> , No action 01 <sub>B</sub> , Set Bit LOCK to 0 10 <sub>B</sub> , Set Bit LOCK to 1 11 <sub>B</sub> , No action Reset: 00 <sub>B</sub>

### 14.1.2 Diagnosis Register



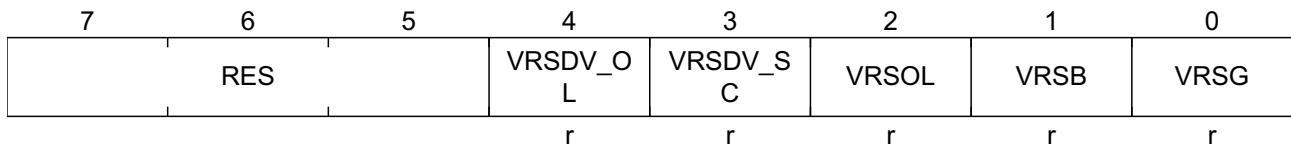


Field	Bits	Type	Description
<b>V6VOV</b>	7	r	<b>Overvoltage Diagnosis Bit of 6 V Supply V6V:</b> $0_B$ , no overvoltage $1_B$ , overvoltage Reset: $0_B$
<b>T2OV</b>	6	r	<b>Overvoltage Diagnosis Bit of Tracker Output T5V2:</b> $0_B$ , no overvoltage $1_B$ , overvoltage Reset: $0_B$
<b>T2UV</b>	5	r	<b>Undervoltage Diagnosis Bit of Tracker Output T5V2:</b> $0_B$ , no undervoltage $1_B$ , undervoltage Reset: $0_B$
<b>T1OV</b>	4	r	<b>Overvoltage Diagnosis Bit of Tracker Output T5V1:</b> $0_B$ , no overvoltage $1_B$ , overvoltage Reset: $0_B$
<b>T1UV</b>	3	r	<b>Undervoltage Diagnosis Bit of Tracker Output T5V1:</b> $0_B$ , no undervoltage $1_B$ , undervoltage Reset: $0_B$
<b>BATOV</b>	2	r	<b>Battery Overvoltage Diagnosis Bit:</b> $0_B$ , no battery overvoltage $1_B$ , battery overvoltage Reset: $0_B$
<b>CF</b>	1	r	<b>Central Failure Diagnosis Bit:</b> $0_B$ , no failure $1_B$ , failure of minimum one diagnostic detected Reset: $0_B$
<b>COT</b>	0	r	<b>Central Overtemperature Diagnosis Bit:</b> $0_B$ , no overtemperature $1_B$ , overtemperature of minimum one temperature sensor Reset: $0_B$



Field	Bits	Type	Description
T5VOT	2	r	<b>Tracker Overtemperature Diagnosis Bit:</b> 0 <sub>B</sub> , no overtemperature 1 <sub>B</sub> , overtemperature Reset: 0 <sub>B</sub>
V5VOT	1	r	<b>V5V Regulator Overtemperature Diagnosis Bit:</b> 0 <sub>B</sub> , no overtemperature 1 <sub>B</sub> , overtemperature Reset: 0 <sub>B</sub>
MROT	0	r	<b>Main Relay Overtemperature Diagnosis Bit:</b> 0 <sub>B</sub> , no overtemperature 1 <sub>B</sub> , overtemperature Reset: 0 <sub>B</sub>

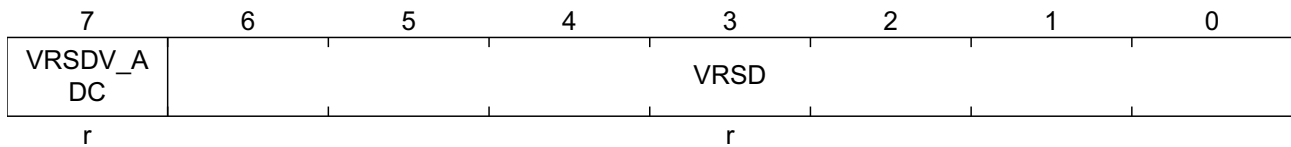
**VRSDiag0** **Offset** **Reset Value**  
**022<sub>H</sub>** **00<sub>H</sub>**



Field	Bits	Type	Description
VRSDV_OL	4	r	<b>Open Load Measurement Data Valid Bit</b> 0 <sub>B</sub> , measurement data not valid 1 <sub>B</sub> , measurement data valid Reset: 0 <sub>B</sub>
VRSDV_SC	3	r	<b>Short to GND/Bat Measurement Data Valid Bit</b> 0 <sub>B</sub> , measurement data not valid 1 <sub>B</sub> , measurement data valid Reset: 0 <sub>B</sub>
VRSOL	2	r	<b>VRS Open Load Diagnosis Bit:</b> 0 <sub>B</sub> , no open load 1 <sub>B</sub> , open load Reset: 0 <sub>B</sub>
VRSB	1	r	<b>VRS Short to Battery Diagnosis Bit:</b> 0 <sub>B</sub> , no short to battery 1 <sub>B</sub> , short to battery Reset: 0 <sub>B</sub>

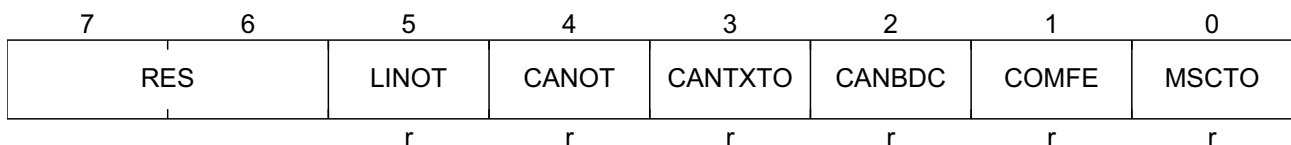
Field	Bits	Type	Description
VRSG	0	r	<b>VRS Short to GND Diagnosis Bit:</b> 0 <sub>B</sub> , no short to GND 1 <sub>B</sub> , short to GND Reset: 0 <sub>B</sub>

**VRSDiag1** **Offset** **Reset Value**  
023<sub>H</sub> 00<sub>H</sub>



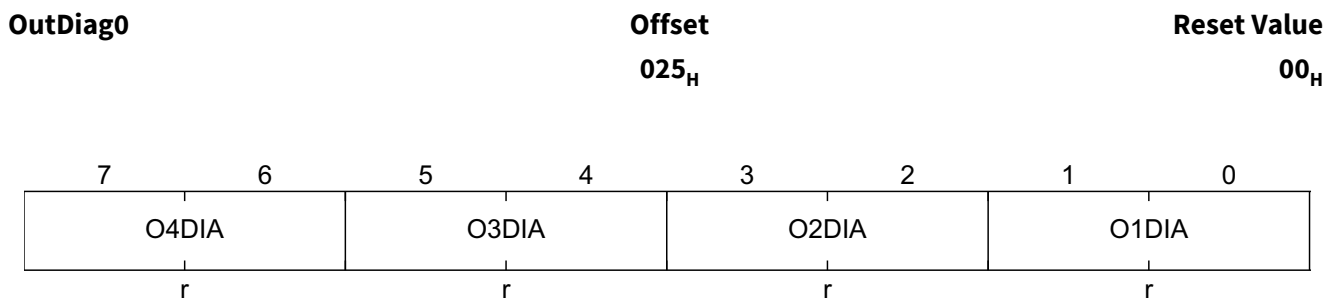
Field	Bits	Type	Description
VRSDV_ADC	7	r	<b>ADC Measurement Data Valid Bit</b> 0 <sub>B</sub> , measurement data not valid 1 <sub>B</sub> , measurement data valid Reset: 0 <sub>B</sub>
VRSD	6:0	r	<b>VRS Diagnosis Measurement Result Register</b> Reset: 0000000 <sub>B</sub>

**ComDiag** **Offset** **Reset Value**  
024<sub>H</sub> 00<sub>H</sub>



Field	Bits	Type	Description
LINOT	5	r	<b>LIN Overtemperature Diagnosis Bit:</b> 0 <sub>B</sub> , no overtemperature 1 <sub>B</sub> , overtemperature Reset: 0 <sub>B</sub>

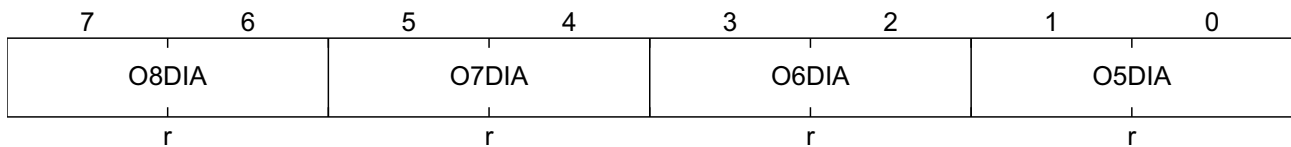
Field	Bits	Type	Description
CANOT	4	r	<b>CAN Overtemperature Diagnosis Bit:</b> 0 <sub>B</sub> , no overtemperature 1 <sub>B</sub> , overtemperature Reset: 0 <sub>B</sub>
CANTXTO	3	r	<b>CAN TX Dominant Time Out Error Diagnosis Bit:</b> 0 <sub>B</sub> , no error 1 <sub>B</sub> , TX dominant time out error Reset: 0 <sub>B</sub>
CANBDC	2	r	<b>CAN Bus Line Dominant Clamp Error Diagnosis Bit:</b> 0 <sub>B</sub> , no error 1 <sub>B</sub> , bus dominant clamp error Reset: 0 <sub>B</sub>
COMFE	1	r	<b>Communication Frame Error Diagnosis Bit:</b> 0 <sub>B</sub> , no MSC/SPI frame error 1 <sub>B</sub> , MSC/SPI frame error Reset: 0 <sub>B</sub>
MSCTO	0	r	<b>MSC Time Out Failure Diagnosis Bit:</b> 0 <sub>B</sub> , no failure 1 <sub>B</sub> , MSC time out Reset: 0 <sub>B</sub>



Field	Bits	Type	Description
O4DIA	7:6	r	<b>Output4 Diagnosis Bits: see below</b> Reset: 00 <sub>B</sub>
O3DIA	5:4	r	<b>Output3 Diagnosis Bits: see below</b> Reset: 00 <sub>B</sub>
O2DIA	3:2	r	<b>Output2 Diagnosis Bits: see below</b> Reset: 00 <sub>B</sub>

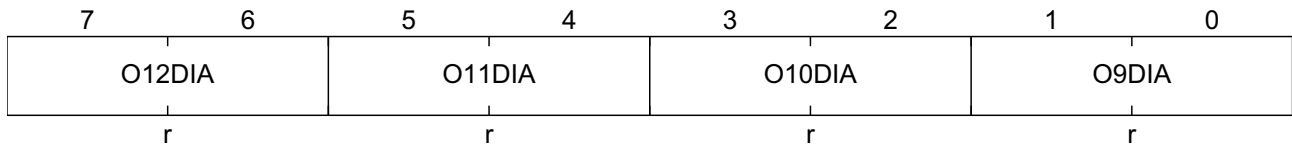
Field	Bits	Type	Description
<b>O1DIA</b>	1:0	r	<b>Output1 Diagnosis Bits:</b> 00 <sub>B</sub> , no failure 01 <sub>B</sub> , short circuit to bat (overcurrent) or overtemperature 10 <sub>B</sub> , open load in off 11 <sub>B</sub> , short circuit to ground in off Reset: 00 <sub>B</sub>

**OutDiag1** **Offset** **Reset Value**  
**026<sub>H</sub>** **00<sub>H</sub>**



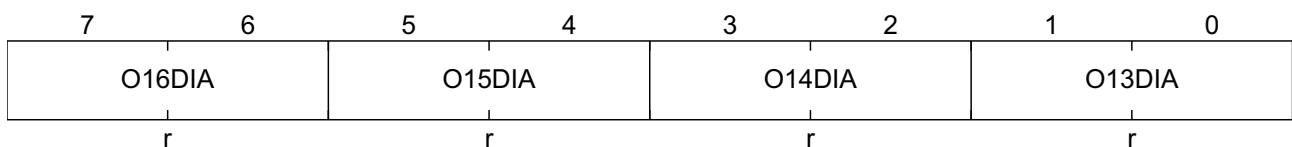
Field	Bits	Type	Description
<b>O8DIA</b>	7:6	r	<b>Output8 (DFB8) Diagnosis Bit:</b> 00 <sub>B</sub> , no failure 01 <sub>B</sub> , short circuit to bat 10 <sub>B</sub> , open load in off 11 <sub>B</sub> , short circuit to ground in off Reset: 00 <sub>B</sub>
<b>O7DIA</b>	5:4	r	<b>Output7 Diagnosis Bits: see below</b> Reset: 00 <sub>B</sub>
<b>O6DIA</b>	3:2	r	<b>Output6 Diagnosis Bits: see below</b> Reset: 00 <sub>B</sub>
<b>O5DIA</b>	1:0	r	<b>Output5 Diagnosis Bits:</b> 00 <sub>B</sub> , no failure 01 <sub>B</sub> , short circuit to bat (overcurrent) or overtemperature 10 <sub>B</sub> , open load in off 11 <sub>B</sub> , short circuit to ground in off Reset: 00 <sub>B</sub>

**OutDiag2** **Offset** **Reset Value**  
**027<sub>H</sub>** **00<sub>H</sub>**



Field	Bits	Type	Description
<b>O12DIA</b>	7:6	r	<b>Output12 (DFB12) Diagnosis Bit: see below</b> Reset: 00 <sub>B</sub>
<b>O11DIA</b>	5:4	r	<b>Output11 (DFB11) Diagnosis Bit: see below</b> Reset: 00 <sub>B</sub>
<b>O10DIA</b>	3:2	r	<b>Output10 (DFB10) Diagnosis Bit: see below</b> Reset: 00 <sub>B</sub>
<b>O9DIA</b>	1:0	r	<b>Output9 (DFB9) Diagnosis Bit:</b> 00 <sub>B</sub> , no failure 01 <sub>B</sub> , short circuit to bat 10 <sub>B</sub> , open load in off 11 <sub>B</sub> , short circuit to ground in off Reset: 00 <sub>B</sub>

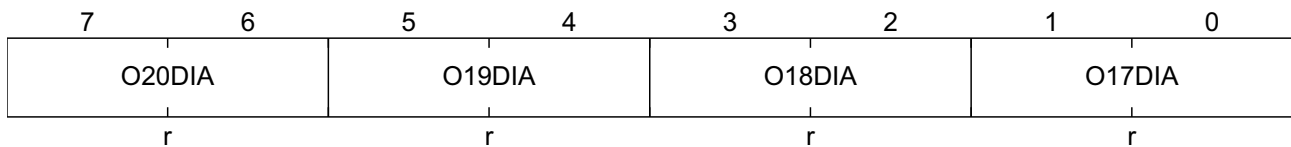
**OutDiag3** **Offset** **Reset Value**  
**028<sub>H</sub>** **00<sub>H</sub>**



Field	Bits	Type	Description
<b>O16DIA</b>	7:6	r	<b>Output16 Diagnosis Bit: see below</b> Reset: 00 <sub>B</sub>
<b>O15DIA</b>	5:4	r	<b>Output15 Diagnosis Bit: see below</b> Reset: 00 <sub>B</sub>
<b>O14DIA</b>	3:2	r	<b>Output14 Diagnosis Bit:</b> 00 <sub>B</sub> , no failure 01 <sub>B</sub> , short circuit to bat (overcurrent) or overtemperature 10 <sub>B</sub> , open load in off 11 <sub>B</sub> , short circuit to ground in off Reset: 00 <sub>B</sub>

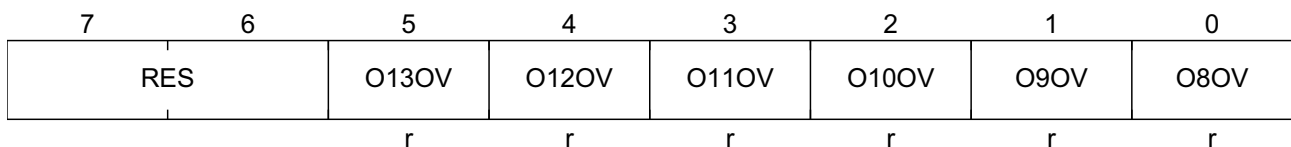
Field	Bits	Type	Description
<b>O13DIA</b>	1:0	r	<b>Output13 (DFB13) Diagnosis Bit:</b> 00 <sub>B</sub> , no failure 01 <sub>B</sub> , short circuit to bat 10 <sub>B</sub> , open load in off 11 <sub>B</sub> , short circuit to ground in off Reset: 00 <sub>B</sub>

**OutDiag4** **Offset** **Reset Value**  
**029<sub>H</sub>** **00<sub>H</sub>**

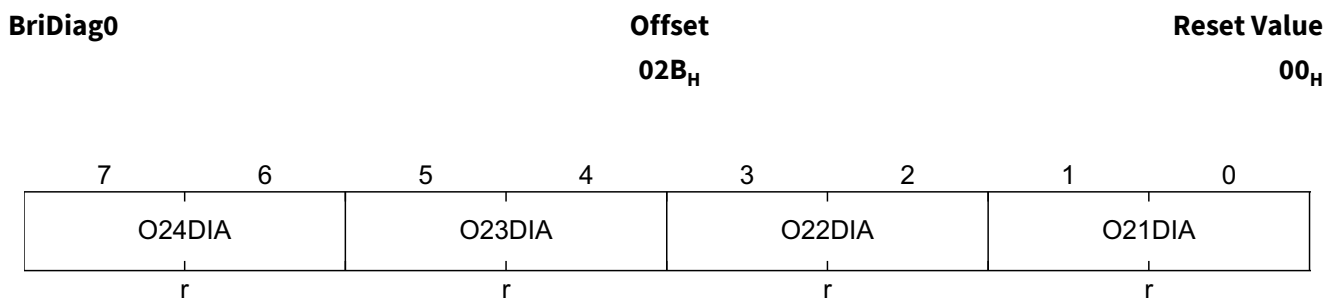


Field	Bits	Type	Description
<b>O20DIA</b>	7:6	r	<b>Output20 Diagnosis Bits: see below</b> Reset: 00 <sub>B</sub>
<b>O19DIA</b>	5:4	r	<b>Output19 Diagnosis Bits: see below</b> Reset: 00 <sub>B</sub>
<b>O18DIA</b>	3:2	r	<b>Output18 Diagnosis Bits: see below</b> Reset: 00 <sub>B</sub>
<b>O17DIA</b>	1:0	r	<b>Output17 Diagnosis Bits:</b> 00 <sub>B</sub> , no failure 01 <sub>B</sub> , short circuit to bat (overcurrent) or overtemperature 10 <sub>B</sub> , open load in off 11 <sub>B</sub> , short circuit to ground in off Reset: 00 <sub>B</sub>

**PPOVDiag** **Offset** **Reset Value**  
**02A<sub>H</sub>** **00<sub>H</sub>**



Field	Bits	Type	Description
<b>O13OV</b>	5	r	<b>Output13 Overvoltage Diagnosis Bit:</b> 0 <sub>B</sub> , no overvoltage 1 <sub>B</sub> , overvoltage Reset: 0 <sub>B</sub>
<b>O12OV</b>	4	r	<b>Output12 Overvoltage Diagnosis Bit:</b> 0 <sub>B</sub> , no overvoltage 1 <sub>B</sub> , overvoltage Reset: 0 <sub>B</sub>
<b>O11OV</b>	3	r	<b>Output11 Overvoltage Diagnosis Bit:</b> 0 <sub>B</sub> , no overvoltage 1 <sub>B</sub> , overvoltage Reset: 0 <sub>B</sub>
<b>O10OV</b>	2	r	<b>Output10 Overvoltage Diagnosis Bit:</b> 0 <sub>B</sub> , no overvoltage 1 <sub>B</sub> , overvoltage Reset: 0 <sub>B</sub>
<b>O9OV</b>	1	r	<b>Output9 Overvoltage Diagnosis Bit:</b> 0 <sub>B</sub> , no overvoltage 1 <sub>B</sub> , overvoltage Reset: 0 <sub>B</sub>
<b>O8OV</b>	0	r	<b>Output8 Overvoltage Diagnosis Bit:</b> 0 <sub>B</sub> , no overvoltage 1 <sub>B</sub> , overvoltage Reset: 0 <sub>B</sub>

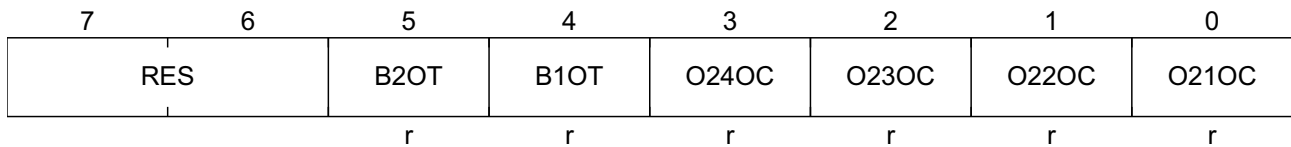


Field	Bits	Type	Description
<b>O24DIA</b>	7:6	r	<b>Output24 Diagnosis Bits (in off)</b> Reset: 00 <sub>B</sub>
<b>O23DIA</b>	5:4	r	<b>Output23 Diagnosis Bits (in off)</b> Reset: 00 <sub>B</sub>



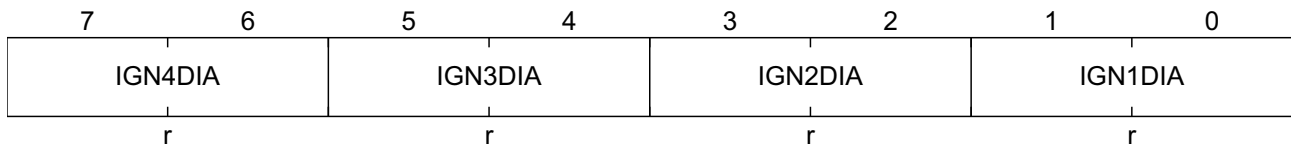
Field	Bits	Type	Description
<b>O22DIA</b>	3:2	r	<b>Output22 Diagnosis Bits (in off)</b> Reset: 00 <sub>B</sub>
<b>O21DIA</b>	1:0	r	<b>Output21 Diagnosis Bits (in off)</b> Reset: 00 <sub>B</sub>

**BriDiag1** **Offset** **Reset Value**  
**02C<sub>H</sub>** **00<sub>H</sub>**



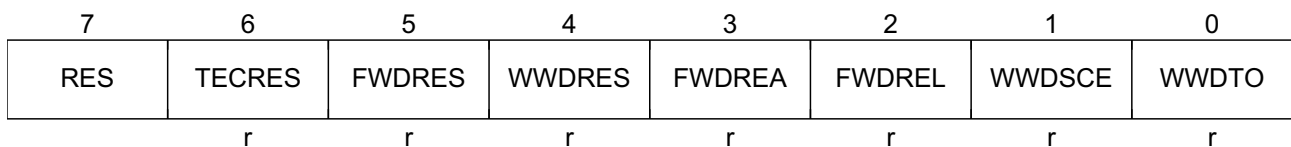
Field	Bits	Type	Description
<b>B2OT</b>	5	r	<b>Output23,24 Overtemperature Diagnosis Bit</b> 0 <sub>B</sub> , no overtemperature 1 <sub>B</sub> , overtemperature Reset: 0 <sub>B</sub>
<b>B1OT</b>	4	r	<b>Output21,22 Overtemperature Diagnosis Bit</b> 0 <sub>B</sub> , no overtemperature 1 <sub>B</sub> , overtemperature Reset: 0 <sub>B</sub>
<b>O24OC</b>	3	r	<b>Output24 Overcurrent Diagnosis Bit</b> 0 <sub>B</sub> , no overcurrent 1 <sub>B</sub> , overcurrent Reset: 0 <sub>B</sub>
<b>O23OC</b>	2	r	<b>Output23 Overcurrent Diagnosis Bit</b> 0 <sub>B</sub> , no overcurrent 1 <sub>B</sub> , overcurrent Reset: 0 <sub>B</sub>
<b>O22OC</b>	1	r	<b>Output22 Overcurrent Diagnosis Bit</b> 0 <sub>B</sub> , no overcurrent 1 <sub>B</sub> , overcurrent Reset: 0 <sub>B</sub>
<b>O21OC</b>	0	r	<b>Output21 Overcurrent Diagnosis Bit</b> 0 <sub>B</sub> , no overcurrent 1 <sub>B</sub> , overcurrent Reset: 0 <sub>B</sub>

**IgnDiag** **Offset** **Reset Value**  
**02D<sub>H</sub>** **00<sub>H</sub>**



Field	Bits	Type	Description
<b>IGN4DIA</b>	7:6	r	<b>Ignition 4 Output Diagnosis Bits: see below</b> Reset: 00 <sub>B</sub>
<b>IGN3DIA</b>	5:4	r	<b>Ignition 3 Output Diagnosis Bits: see below</b> Reset: 00 <sub>B</sub>
<b>IGN2DIA</b>	3:2	r	<b>Ignition 2 Output Diagnosis Bits: see below</b> Reset: 00 <sub>B</sub>
<b>IGN1DIA</b>	1:0	r	<b>Ignition 1 Output Diagnosis Bits:</b> 00 <sub>B</sub> , no failure 01 <sub>B</sub> , short circuit to bat or overtemperature 10 <sub>B</sub> , open load 11 <sub>B</sub> , short circuit to ground in on Reset: 00 <sub>B</sub>

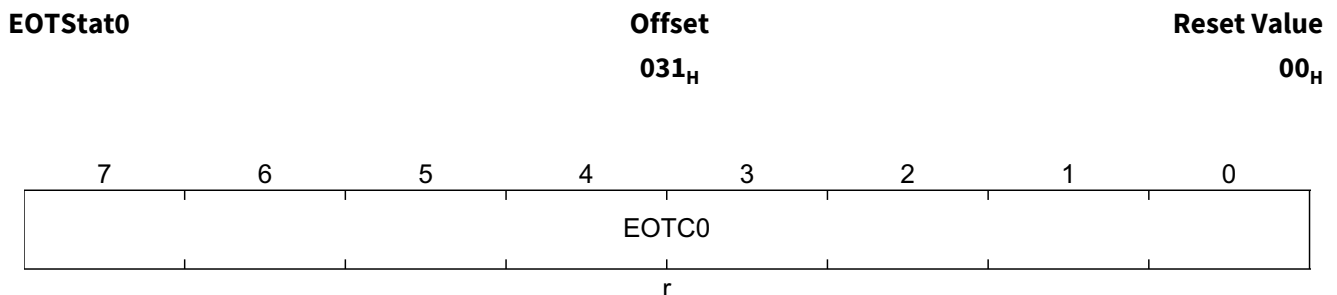
**WdDiag** **Offset** **Reset Value**  
**02E<sub>H</sub>** **00<sub>H</sub>**



Field	Bits	Type	Description
<b>TECRES</b>	6	r	<b>Reset caused by TEC:</b> 0 <sub>B</sub> , no reset (caused by TEC) happened 1 <sub>B</sub> , reset (caused by TEC) happened Reset: 0 <sub>B</sub>

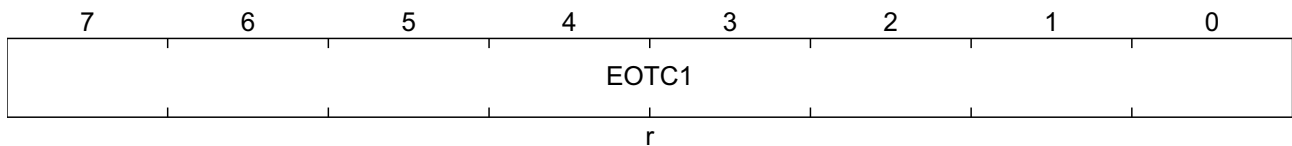
Field	Bits	Type	Description
<b>FWDRES</b>	5	r	<b>Reset caused by Functional Watchdog:</b> 0 <sub>B</sub> , no functional watchdog reset happened 1 <sub>B</sub> , functional watchdog reset happened Reset: 0 <sub>B</sub>
<b>WWDRES</b>	4	r	<b>Reset caused by Window Watchdog:</b> 0 <sub>B</sub> , no window watchdog reset happened 1 <sub>B</sub> , window watchdog reset happened Reset: 0 <sub>B</sub>
<b>FWDREA</b>	3	r	<b>Functional Watchdog Response Error of Actual Running Sequence Diagnosis Bit:</b> 0 <sub>B</sub> , no error 1 <sub>B</sub> , error Reset: 0 <sub>B</sub>
<b>FWDREL</b>	2	r	<b>Functional Watchdog Response Error of Last Sequence Diagnosis Bit:</b> 0 <sub>B</sub> , no error 1 <sub>B</sub> , error Reset: 0 <sub>B</sub>
<b>WWDSC</b>	1	r	<b>Window Watchdog Service Command too Early Diagnosis Bit:</b> 0 <sub>B</sub> , service command in time 1 <sub>B</sub> , service command too early Reset: 0 <sub>B</sub>
<b>WWDTO</b>	0	r	<b>Window Watchdog Time Out Diagnosis Bit:</b> 0 <sub>B</sub> , no time out 1 <sub>B</sub> , time out Reset: 0 <sub>B</sub>

### 14.1.3 Status Register



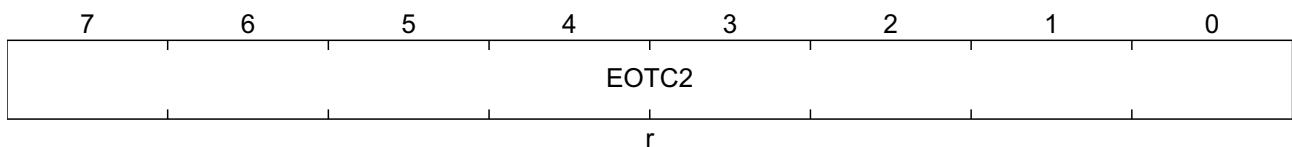
Field	Bits	Type	Description
EOTC0	7:0	r	<b>Engine Off Timer Counter Value Bits: (Bit 7 - 0)</b> Reset: 00 <sub>H</sub>

**EOTStat1** **Offset**  
032<sub>H</sub> **Reset Value**  
00<sub>H</sub>



Field	Bits	Type	Description
EOTC1	7:0	r	<b>Engine Off Timer Counter Value Bits: (Bit 15 - 8)</b> Reset: 00 <sub>H</sub>

**EOTStat2** **Offset**  
033<sub>H</sub> **Reset Value**  
00<sub>H</sub>



Field	Bits	Type	Description
EOTC2	7:0	r	<b>Engine Off Timer Counter Value Bits: (Bit 23 - 16)</b> Reset: 00 <sub>H</sub>

**OpStat0** **Offset**  
034<sub>H</sub> **Reset Value**  
00<sub>H</sub>

7	6	5	4	3	2	1	0
EOTWK	CANWK	WKINT	MON	MR	OM	WK	KEY
r	r	r	r	r	r	r	r

Field	Bits	Type	Description
<b>EOTWK</b>	7	r	<b>Status of internal EOTWK signal:</b> $0_B$ , EOTWK is inactive $1_B$ , EOTWK is active Reset: $0_B$
<b>CANWK</b>	6	r	<b>Status of internal CANWK signal:</b> $0_B$ , CANWK is inactive $1_B$ , CANWK is active Reset: $0_B$
<b>WKINT</b>	5	r	<b>Status of internal WKINT signal:</b> $0_B$ , WKINT is inactive $1_B$ , WKINT is active Reset: $0_B$
<b>MON</b>	4	r	<b>MON Pin Status Bit:</b> $0_B$ , active (low) $1_B$ , inactive (high) Reset: $0_B$
<b>MR</b>	3	r	<b>Main Relay Switch On Status Bit:</b> $0_B$ , off $1_B$ , on Reset: $0_B$
<b>OM</b>	2	r	<b>Operation Mode Bit:</b> $0_B$ , normal operation $1_B$ , afterrun mode Reset: $0_B$
<b>WK</b>	1	r	<b>WK Status Bit (filtered):</b> $0_B$ , WK = 0 $1_B$ , WK = 1 Reset: $0_B$
<b>KEY</b>	0	r	<b>KEY Status Bit (filtered):</b> $0_B$ , KEY = 0 $1_B$ , KEY = 1 Reset: $0_B$

**OpStat1**

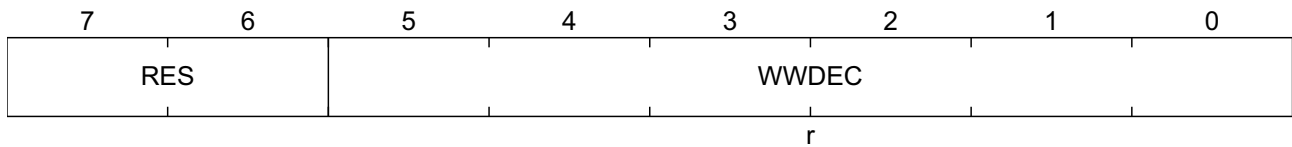
**Offset**  
**035<sub>H</sub>**

**Reset Value**  
**00<sub>H</sub>**

7	6	5	4	3	2	1	0
LOCK	OE	EOTRES	RSTR	V5VOVR	V5VUVR	WDRES	ARES
r	r	r	r	r	r	r	r

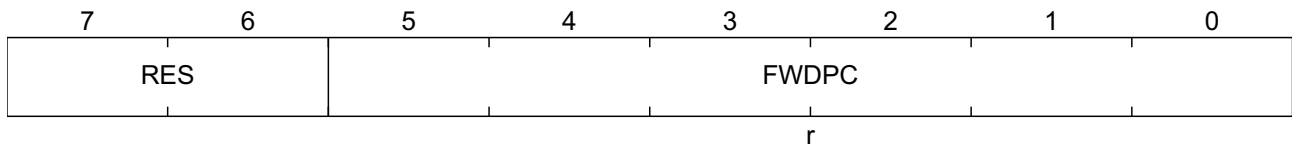
Field	Bits	Type	Description
LOCK	7	r	<b>Configuration Lock Status Bit:</b> 0 <sub>B</sub> , Configuration registers unlocked 1 <sub>B</sub> , Configuration registers locked Reset: 0 <sub>B</sub>
OE	6	r	<b>Global Output Enable Status Bit:</b> 0 <sub>B</sub> , outputs disabled and control register are reset 1 <sub>B</sub> , outputs enabled Reset: 0 <sub>B</sub>
EOTRES	5	r	<b>Engine Off Timer Reset Status Bit:</b> 0 <sub>B</sub> , no EOT reset happened 1 <sub>B</sub> , EOT reset happened Reset: 0 <sub>B</sub>
RSTR	4	r	<b>Reset caused by external RST Reset: (only valid if no internal power on reset occurs)</b> 0 <sub>B</sub> , no external RST reset happened 1 <sub>B</sub> , external RST reset happened Reset: 0 <sub>B</sub>
V5VOVR	3	r	<b>Reset caused by V5V Overvoltage Reset: (only valid if no internal power on reset occurs)</b> 0 <sub>B</sub> , no V5V overvoltage reset happened 1 <sub>B</sub> , V5V overvoltage reset happened Reset: 0 <sub>B</sub>
V5VUVR	2	r	<b>Reset caused by V5V Undervoltage Reset: (only valid if no internal power on reset occurs)</b> 0 <sub>B</sub> , no V5V undervoltage reset happened 1 <sub>B</sub> , V5V undervoltage reset happened Reset: 0 <sub>B</sub>
WDRES	1	r	<b>Reset caused by Watchdog Reset: (only valid if no internal power on reset occurs)</b> 0 <sub>B</sub> , no watchdog reset happened 1 <sub>B</sub> , watchdog reset happened Reset: 0 <sub>B</sub>
ARES	0	r	<b>Reset caused by Afterrun Reset: (only valid if no internal power on reset occurs)</b> 0 <sub>B</sub> , no afterrun reset happened 1 <sub>B</sub> , afterrun reset happened Reset: 0 <sub>B</sub>

**WWDStat** **Offset** **Reset Value**  
**036<sub>H</sub>** **30<sub>H</sub>**



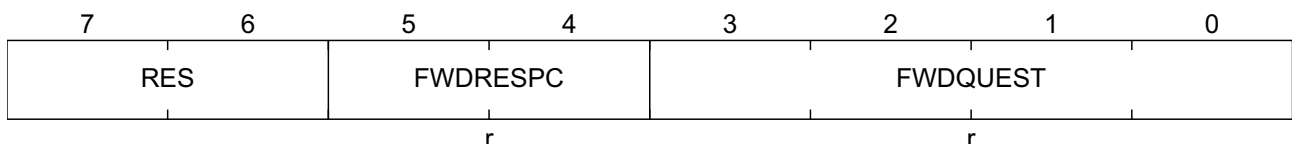
Field	Bits	Type	Description
WWDEC	5:0	r	<b>Window Watchdog Error Counter Value</b> Reset: 110000 <sub>B</sub>

**FWDStat0** **Offset** **Reset Value**  
**037<sub>H</sub>** **30<sub>H</sub>**



Field	Bits	Type	Description
FWDPC	5:0	r	<b>Functional Watchdog Pass Counter Value</b> Reset: 110000 <sub>B</sub>

**FWDStat1** **Offset** **Reset Value**  
**038<sub>H</sub>** **30<sub>H</sub>**



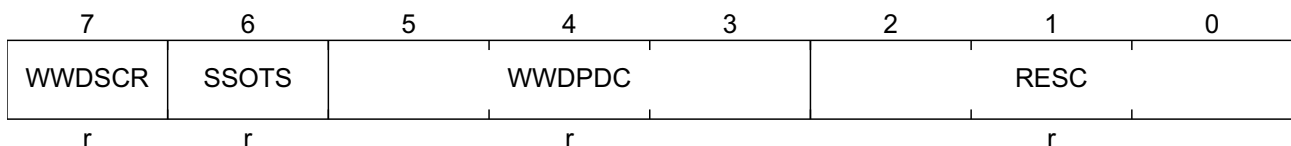
Field	Bits	Type	Description
<b>FWDRESPC</b>	5:4	r	<b>Functional Watchdog Response Counter Value</b> Reset: 11 <sub>B</sub>
<b>FWDQUEST</b>	3:0	r	<b>Functional Watchdog Question</b> Reset: 0000 <sub>B</sub>

**TECStat** **Offset** **Reset Value**  
**039<sub>H</sub>** **30<sub>H</sub>**



Field	Bits	Type	Description
<b>TEC</b>	5:0	r	<b>Total Error Counter Value</b> Reset: 110000 <sub>B</sub>

**WdStat0** **Offset** **Reset Value**  
**03A<sub>H</sub>** **00<sub>H</sub>**

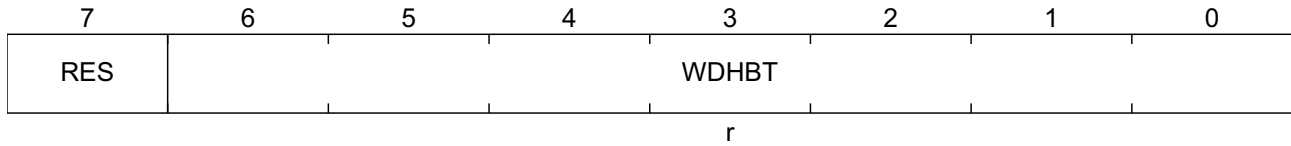


Field	Bits	Type	Description
<b>WWDSR</b>	7	r	<b>Window Watchdog Service Command received</b> 0 <sub>B</sub> , No Service Command received 1 <sub>B</sub> , Service Command received Reset: 0 <sub>B</sub>
<b>SSOTS</b>	6	r	<b>Secure Shut Off Timer Start Status Bit:</b> 0 <sub>B</sub> , timer reset 1 <sub>B</sub> , timer started Reset: 0 <sub>B</sub>





**WDHBT1** **Offset** **Reset Value**  
**03D<sub>H</sub>** **00<sub>H</sub>**

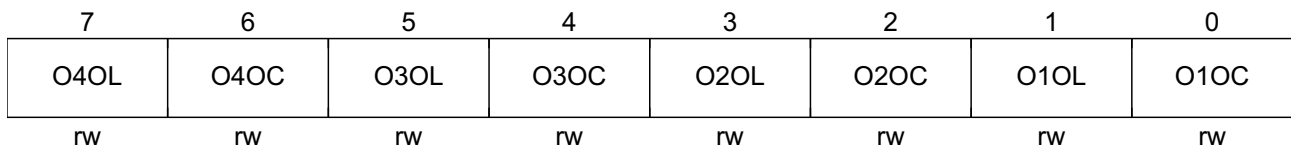


Field	Bits	Type	Description
<b>WDHBT</b>	6:0	r	<b>Sampled Watchdog Heartbeat Timer Value</b> Reset: 0000000 <sub>B</sub>

#### 14.1.4 Configuration Register

OutConfig0 locked with LOCK = 1

**OutConfig0** **Offset** **Reset Value**  
**040<sub>H</sub>** **FF<sub>H</sub>**



Field	Bits	Type	Description
<b>O4OL</b>	7	rw	<b>Output4 Open Load Set Up:</b> 0 <sub>B</sub> , pull down current deactivated 1 <sub>B</sub> , fully functional Reset: 1 <sub>B</sub>
<b>O4OC</b>	6	rw	<b>Output4 Overcurrent Protection Set Up:</b> 0 <sub>B</sub> , current limitation in case of overcurrent 1 <sub>B</sub> , switch off in case of overcurrent Reset: 1 <sub>B</sub>
<b>O3OL</b>	5	rw	<b>Output3 Open Load Set Up:</b> 0 <sub>B</sub> , pull down current deactivated 1 <sub>B</sub> , fully functional Reset: 1 <sub>B</sub>

Field	Bits	Type	Description
<b>O3OC</b>	4	rw	<b>Output3 Overcurrent Protection Set Up:</b> 0 <sub>B</sub> , current limitation in case of overcurrent 1 <sub>B</sub> , switch off in case of overcurrent Reset: 1 <sub>B</sub>
<b>O2OL</b>	3	rw	<b>Output2 Open Load Set Up:</b> 0 <sub>B</sub> , pull down current deactivated 1 <sub>B</sub> , fully functional Reset: 1 <sub>B</sub>
<b>O2OC</b>	2	rw	<b>Output2 Overcurrent Protection Set Up:</b> 0 <sub>B</sub> , current limitation in case of overcurrent 1 <sub>B</sub> , switch off in case of overcurrent Reset: 1 <sub>B</sub>
<b>O1OL</b>	1	rw	<b>Output1 Open Load Set Up:</b> 0 <sub>B</sub> , pull down current deactivated 1 <sub>B</sub> , fully functional Reset: 1 <sub>B</sub>
<b>O1OC</b>	0	rw	<b>Output1 Overcurrent Protection Set Up:</b> 0 <sub>B</sub> , current limitation in case of overcurrent 1 <sub>B</sub> , switch off in case of overcurrent Reset: 1 <sub>B</sub>

OutConfig1 locked with LOCK = 1

OutConfig1	Offset 041 <sub>H</sub>						Reset Value 3F <sub>H</sub>	
	7	6	5	4	3	2	1	0
	RES		O7OL	O7OC	O6OL	O6OC	O5OL	O5OC
			rw	rw	rw	rw	rw	rw

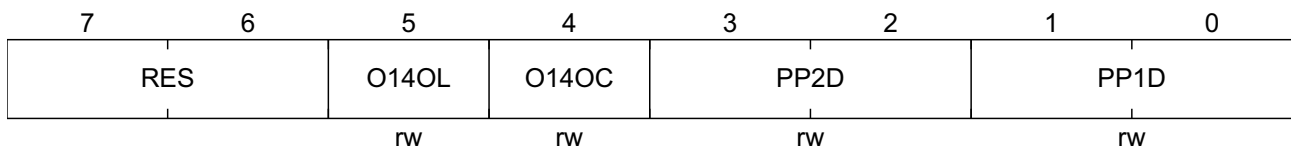
Field	Bits	Type	Description
<b>O7OL</b>	5	rw	<b>Output7 Open Load Set Up:</b> 0 <sub>B</sub> , pull down current deactivated 1 <sub>B</sub> , fully functional Reset: 1 <sub>B</sub>
<b>O7OC</b>	4	rw	<b>Output7 Overcurrent Protection Set Up:</b> 0 <sub>B</sub> , current limitation in case of overcurrent 1 <sub>B</sub> , switch off in case of overcurrent Reset: 1 <sub>B</sub>



Field	Bits	Type	Description
<b>O110L</b>	3	rw	<b>Output11 Open Load Set Up:</b> 0 <sub>B</sub> , pull down current deactivated 1 <sub>B</sub> , fully functional Reset: 1 <sub>B</sub>
<b>O100L</b>	2	rw	<b>Output10 Open Load Set Up:</b> 0 <sub>B</sub> , pull down current deactivated 1 <sub>B</sub> , fully functional Reset: 1 <sub>B</sub>
<b>O90L</b>	1	rw	<b>Output9 Open Load Set Up:</b> 0 <sub>B</sub> , pull down current deactivated 1 <sub>B</sub> , fully functional Reset: 1 <sub>B</sub>
<b>O80L</b>	0	rw	<b>Output8 Open Load Set Up:</b> 0 <sub>B</sub> , pull down current deactivated 1 <sub>B</sub> , fully functional Reset: 1 <sub>B</sub>

OutConfig3 locked with LOCK = 1

**OutConfig3** **Offset** **Reset Value**  
**043<sub>H</sub>** **30<sub>H</sub>**



Field	Bits	Type	Description
<b>O140L</b>	5	rw	<b>Output14 Open Load Set Up:</b> 0 <sub>B</sub> , pull down current deactivated 1 <sub>B</sub> , fully functional Reset: 1 <sub>B</sub>
<b>O140C</b>	4	rw	<b>Output14 Overcurrent Protection Set Up:</b> 0 <sub>B</sub> , current limitation in case of overcurrent 1 <sub>B</sub> , switch off in case of overcurrent Reset: 1 <sub>B</sub>
<b>PP2D</b>	3:2	rw	<b>Diagnosis in On Set Up for OUT12 and OUT13:</b> 00 <sub>B</sub> , typ. 125 mV short to bat in on threshold 01 <sub>B</sub> , typ. 225 mV short to bat in on threshold 10 <sub>B</sub> , typ. 400 mV short to bat in on threshold 11 <sub>B</sub> , typ. 0.8 V short to bat in on threshold Reset: 00 <sub>B</sub>

Field	Bits	Type	Description
PP1D	1:0	rw	<b>Diagnosis in On Set Up for OUT10 and OUT11:</b> 00 <sub>B</sub> , typ. 125 mV short to bat in on threshold 01 <sub>B</sub> , typ. 225 mV short to bat in on threshold 10 <sub>B</sub> , typ. 400 mV short to bat in on threshold 11 <sub>B</sub> , typ. 0.8 V short to bat in on threshold Reset: 00 <sub>B</sub>

OutConfig4 locked with LOCK = 1

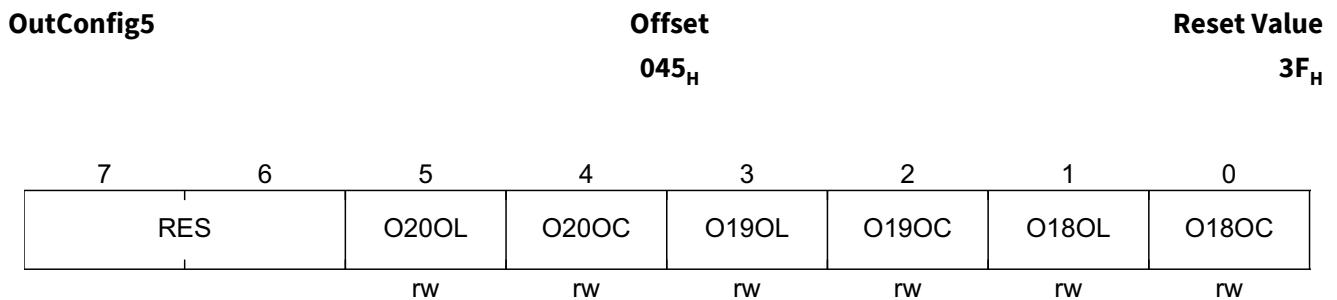
**OutConfig4** **Offset** **Reset Value**  
**044<sub>H</sub>** **3F<sub>H</sub>**

7	6	5	4	3	2	1	0
RES	O17D	O17OL	O17OC	O16OL	O16OC	O15OL	O15OC
	rw	rw	rw	rw	rw	rw	rw

Field	Bits	Type	Description
O17D	6	rw	<b>Output17 Delayed Off Set Up:</b> 0 <sub>B</sub> , no delayed off function 1 <sub>B</sub> , delayed off function activated Reset: 0 <sub>B</sub>
O17OL	5	rw	<b>Output17 Open Load Set Up:</b> 0 <sub>B</sub> , pull down current deactivated 1 <sub>B</sub> , fully functional Reset: 1 <sub>B</sub>
O17OC	4	rw	<b>Output17 Overcurrent Protection Set Up:</b> 0 <sub>B</sub> , current limitation in case of overcurrent 1 <sub>B</sub> , switch off in case of overcurrent Reset: 1 <sub>B</sub>
O16OL	3	rw	<b>Output16 Open Load Set Up:</b> 0 <sub>B</sub> , pull down current deactivated 1 <sub>B</sub> , fully functional Reset: 1 <sub>B</sub>
O16OC	2	rw	<b>Output16 Overcurrent Protection Set Up:</b> 0 <sub>B</sub> , current limitation in case of overcurrent 1 <sub>B</sub> , switch off in case of overcurrent Reset: 1 <sub>B</sub>
O15OL	1	rw	<b>Output15 Open Load Set Up:</b> 0 <sub>B</sub> , pull down current deactivated 1 <sub>B</sub> , fully functional Reset: 1 <sub>B</sub>

Field	Bits	Type	Description
<b>O15OC</b>	0	rw	<b>Output15 Overcurrent Protection Set Up:</b> $0_B$ , current limitation in case of overcurrent $1_B$ , switch off in case of overcurrent Reset: $1_B$

OutConfig5 locked with LOCK = 1



Field	Bits	Type	Description
<b>O20OL</b>	5	rw	<b>Output20 Open Load Set Up:</b> $0_B$ , pull down and pull up current deactivated $1_B$ , fully functional Reset: $1_B$
<b>O20OC</b>	4	rw	<b>Output20 Overcurrent Protection Set Up:</b> $0_B$ , current limitation in case of overcurrent $1_B$ , switch off in case of overcurrent Reset: $1_B$
<b>O19OL</b>	3	rw	<b>Output19 Open Load Set Up:</b> $0_B$ , pull down and pull up current deactivated $1_B$ , fully functional Reset: $1_B$
<b>O19OC</b>	2	rw	<b>Output19 Overcurrent Protection Set Up:</b> $0_B$ , current limitation in case of overcurrent $1_B$ , switch off in case of overcurrent Reset: $1_B$
<b>O18OL</b>	1	rw	<b>Output18 Open Load Set Up:</b> $0_B$ , pull down and pull up current deactivated $1_B$ , fully functional Reset: $1_B$
<b>O18OC</b>	0	rw	<b>Output18 Overcurrent Protection Set Up:</b> $0_B$ , current limitation in case of overcurrent $1_B$ , switch off in case of overcurrent Reset: $1_B$

BriConfig0 locked with LOCK = 1

**BriConfig0** **Offset** **Reset Value**  
**046<sub>H</sub>** **00<sub>H</sub>**

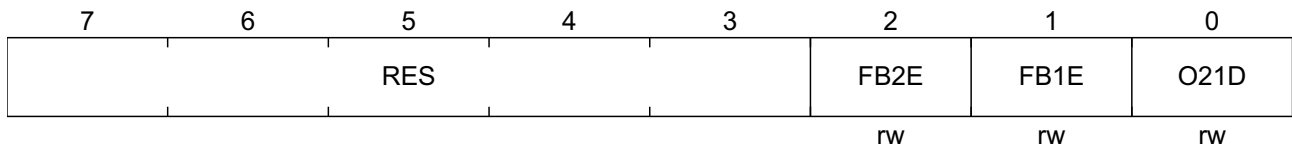
	7	6	5	4	3	2	1	0
	O24F	O24M	O23F	O23M	O22F	O22M	O21F	O21M
	rw	rw	rw	rw	rw	rw	rw	rw

Field	Bits	Type	Description
<b>O24F</b>	7	rw	<b>Output24 Freewheeling Mode Set Up:</b> $0_B$ , passive freewheeling mode $1_B$ , active freewheeling mode Reset: $0_B$
<b>O24M</b>	6	rw	<b>Output24 Mode Set Up:</b> $0_B$ , low-side switch mode $1_B$ , high-side switch mode Reset: $0_B$
<b>O23F</b>	5	rw	<b>Output23 Freewheeling Mode Set Up:</b> $0_B$ , passive freewheeling mode $1_B$ , active freewheeling mode Reset: $0_B$
<b>O23M</b>	4	rw	<b>Output23 Mode Set Up:</b> $0_B$ , low-side switch mode $1_B$ , high-side switch mode Reset: $0_B$
<b>O22F</b>	3	rw	<b>Output22 Freewheeling Mode Set Up:</b> $0_B$ , passive freewheeling mode $1_B$ , active freewheeling mode Reset: $0_B$
<b>O22M</b>	2	rw	<b>Output22 Mode Set Up:</b> $0_B$ , low-side switch mode $1_B$ , high-side switch mode Reset: $0_B$
<b>O21F</b>	1	rw	<b>Output21 Freewheeling Mode Set Up:</b> $0_B$ , passive freewheeling mode $1_B$ , active freewheeling mode Reset: $0_B$
<b>O21M</b>	0	rw	<b>Output21 Mode Set Up:</b> $0_B$ , low-side switch mode $1_B$ , high-side switch mode Reset: $0_B$



BriConfig1 locked with LOCK = 1

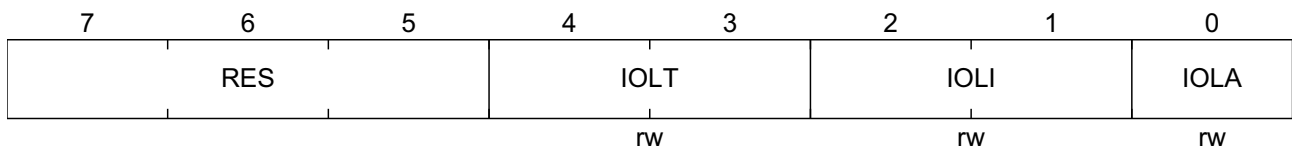
**BriConfig1** **Offset** **Reset Value**  
**047<sub>H</sub>** **00<sub>H</sub>**



Field	Bits	Type	Description
<b>FB2E</b>	2	rw	<b>Full Bridge 2 Enable Bit:</b> 0 <sub>B</sub> , Output 23 and 24 are not used in full bridge configuration 1 <sub>B</sub> , Output 23 and 24 are used in full bridge configuration Reset: 0 <sub>B</sub>
<b>FB1E</b>	1	rw	<b>Full Bridge 1 Enable Bit:</b> 0 <sub>B</sub> , Output 21 and 22 are not used in full bridge configuration 1 <sub>B</sub> , Output 21 and 22 are used in full bridge configuration Reset: 0 <sub>B</sub>
<b>O21D</b>	0	rw	<b>Output21 Delayed Off Set Up:</b> 0 <sub>B</sub> , no delayed off function 1 <sub>B</sub> , delayed off function activated Reset: 0 <sub>B</sub>

IGNConfig locked with LOCK = 1

**IGNConfig** **Offset** **Reset Value**  
**048<sub>H</sub>** **00<sub>H</sub>**

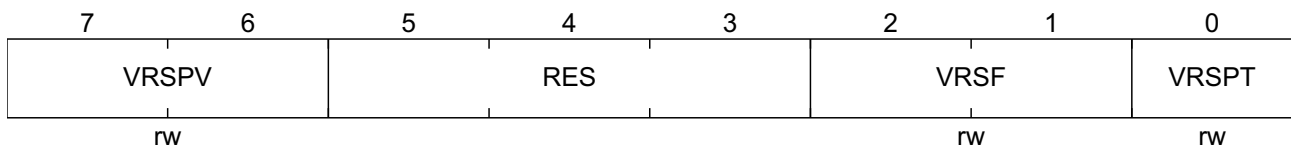


Field	Bits	Type	Description
IOLT	4:3	rw	<b>Ignition Time Setting for Open Load Detection:</b> 00 <sub>B</sub> , 64 μs 01 <sub>B</sub> , 256 μs 10 <sub>B</sub> , 512 μs 11 <sub>B</sub> , 768 μs Reset: 00 <sub>B</sub>
IOLI	2:1	rw	<b>Ignition Current Setting for Open Load Detection:</b> 00 <sub>B</sub> , -100 μA 01 <sub>B</sub> , -400 μA 10 <sub>B</sub> , -1 mA 11 <sub>B</sub> , -4 mA Reset: 00 <sub>B</sub>
IOLA	0	rw	<b>Ignition Open Load Detection Activation:</b> 0 <sub>B</sub> , no open load detection 1 <sub>B</sub> , open load detection active Reset: 0 <sub>B</sub>

VRSConfig0

Offset  
049<sub>H</sub>

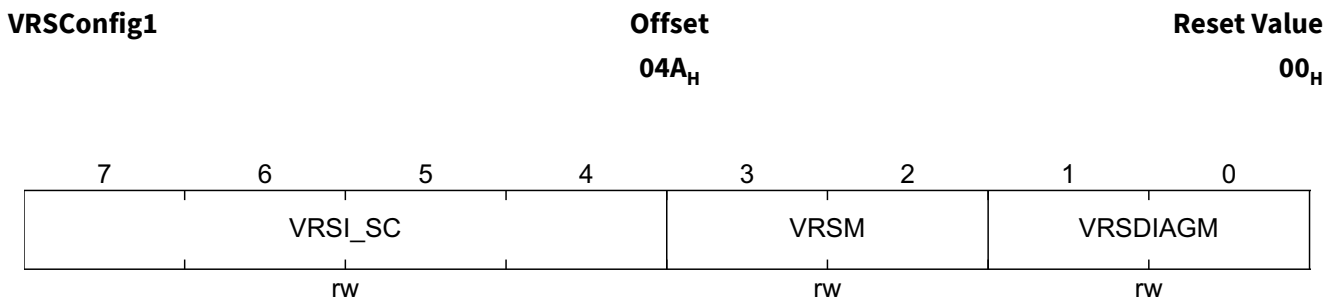
Reset Value  
00<sub>H</sub>



Field	Bits	Type	Description
VRSPV	7:6	rw	<b>VRS Peak Voltage Detection Set Up:</b> 00 <sub>B</sub> , 50 mV 01 <sub>B</sub> , 150 mV 10 <sub>B</sub> , 350 mV 11 <sub>B</sub> , 550 mV Reset: 00 <sub>B</sub>
VRSF	2:1	rw	<b>VRS Output Filter Time Set Up:</b> 00 <sub>B</sub> , 1 μs, reset value 01 <sub>B</sub> , 5 μs 10 <sub>B</sub> , 10 μs 11 <sub>B</sub> , 20 μs Reset: 00 <sub>B</sub>

Field	Bits	Type	Description
<b>VRSPT</b>	0	rw	<b>VRS Peak Time Set Up:</b> $0_B$ , 10 $\mu$ s, reset value $1_B$ , 250 $\mu$ s Reset: $0_B$

VRSConfig1 locked with LOCK = 1



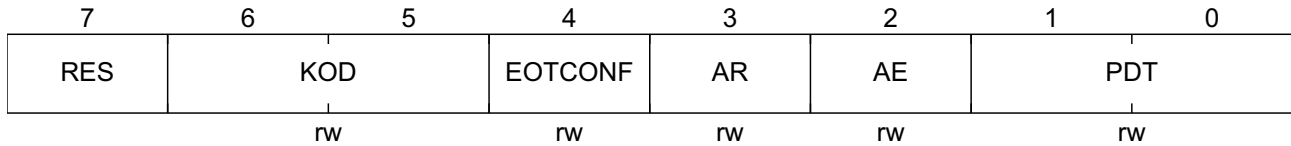
Field	Bits	Type	Description
<b>VRSI_SC</b>	7:4	rw	<b>Current setting for short to GND/Bat measurement</b> $0000_B$ , 10 $\mu$ A $0001_B$ , 20 $\mu$ A $0010_B$ , 30 $\mu$ A $0011_B$ , 40 $\mu$ A $0100_B$ , 50 $\mu$ A $0101_B$ , 60 $\mu$ A $0110_B$ , 70 $\mu$ A $0111_B$ , 80 $\mu$ A $1000_B$ , 100 $\mu$ A $1001_B$ , 120 $\mu$ A $1010_B$ , 140 $\mu$ A $1011_B$ , 160 $\mu$ A $1100_B$ , to full scale (0b1111) 160 $\mu$ A Reset: $0000_B$
<b>VRSM</b>	3:2	rw	<b>VRS/Hall Sensor Mode Set Up:</b> $00_B$ , auto detection mode for VR sensor signals (reset value) $01_B$ , semi auto detection mode for VR sensor signals $10_B$ , manuel detection mode for VR sensor signals $11_B$ , Hall sensor mode Reset: $00_B$
<b>VRSDIAGM</b>	1:0	rw	<b>VRS Diagnosis Mode Set Up:</b> $00_B$ , normal detection mode $01_B$ , short to GND/Bat diagnosis mode $10_B$ , open load diagnosis mode $11_B$ , ADC diagnosis mode Reset: $00_B$



OpConfig0

Offset  
04E<sub>H</sub>

Reset Value  
09<sub>H</sub>



Field	Bits	Type	Description
<b>KOD</b>	6:5	rw	<b>Key Off Delay Set Up:</b> 00 <sub>B</sub> , 100 ms 01 <sub>B</sub> , 200 ms 10 <sub>B</sub> , 400 ms 11 <sub>B</sub> , 800 ms Reset: 00 <sub>B</sub>
<b>EOTCONF</b>	4	rw	<b>Engine Off Timer Configuration:</b> 0 <sub>B</sub> , timer start with negative edge of KEY signal 1 <sub>B</sub> , timer start with command EOTS in register Cmd0 Reset: 0 <sub>B</sub>
<b>AR</b>	3	rw	<b>Afterrun Reset Behavior Set Up:</b> 0 <sub>B</sub> , no afterrun reset 1 <sub>B</sub> , afterrun reset Reset: 1 <sub>B</sub>
<b>AE</b>	2	rw	<b>Afterrun Enable:</b> 0 <sub>B</sub> , no afterrun mode 1 <sub>B</sub> , afterrun mode Reset: 0 <sub>B</sub>
<b>PDT</b>	1:0	rw	<b>Power-Down Time Set Up:</b> 00 <sub>B</sub> , 100 ms 01 <sub>B</sub> , 200 ms 10 <sub>B</sub> , 300 ms 11 <sub>B</sub> , 400 ms Reset: 01 <sub>B</sub>

ComConfig0 locked with LOCK = 1

ComConfig0

Offset  
04F<sub>H</sub>

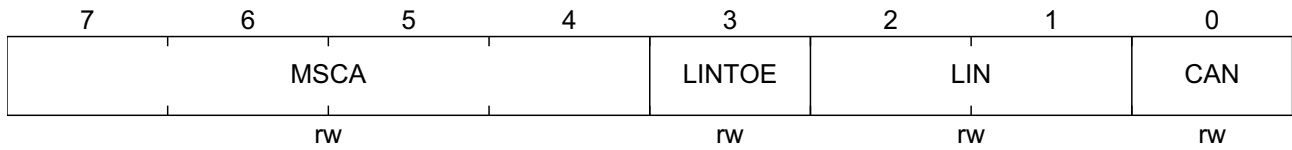
Reset Value  
A4<sub>H</sub>



Field	Bits	Type	Description
<b>MSCF</b>	7:5	rw	<b>MSC Upstream Frequency Divider Set Up:</b> 000 <sub>B</sub> , Division by 64 001 <sub>B</sub> , Division by 4 010 <sub>B</sub> , Division by 8 011 <sub>B</sub> , Division by 16 100 <sub>B</sub> , Division by 32 101 <sub>B</sub> , Division by 64 110 <sub>B</sub> , Division by 128 111 <sub>B</sub> , Division by 256 Reset: 101 <sub>B</sub>
<b>MSCO</b>	4	rw	<b>MSC SDO Definition:</b> 0 <sub>B</sub> , open drain 1 <sub>B</sub> , push pull Reset: 0 <sub>B</sub>
<b>MSCAD</b>	3	rw	<b>MSC Address Definition A0 to A3:</b> 0 <sub>B</sub> , value of A2 to A3 are incremented with each read command 1 <sub>B</sub> , A0 to A3 values are fixed to the values of MSCA[3:0] Reset: 0 <sub>B</sub>
<b>MSCP</b>	2	rw	<b>MSC Upstream Parity Format Set Up:</b> 0 <sub>B</sub> , odd parity 1 <sub>B</sub> , even parity Reset: 1 <sub>B</sub>
<b>MSCUF</b>	1:0	rw	<b>MSC Upstream Address Format Setup:</b> 00 <sub>B</sub> , upstream format without address 01 <sub>B</sub> , upstream format with address 10 <sub>B</sub> , upstream format with address 11 <sub>B</sub> , upstream format with address Reset: 00 <sub>B</sub>

ComConfig1 locked with LOCK = 1

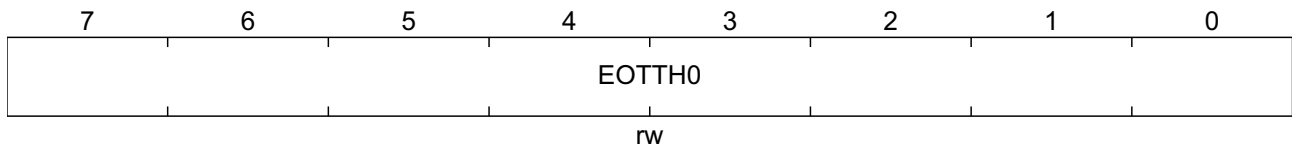
<b>ComConfig1</b>	<b>Offset</b> 050 <sub>H</sub>	<b>Reset Value</b> 0D <sub>H</sub>
-------------------	-----------------------------------	---------------------------------------



Field	Bits	Type	Description
<b>MSCA</b>	7:4	rw	<b>MSC Upstream Address for MSCAD = 1</b> Reset: 0000 <sub>B</sub>
<b>LINTOE</b>	3	rw	<b>LIN TX Time OUT Function Enable:</b> 0 <sub>B</sub> , TX time out function disabled 1 <sub>B</sub> , TX time out function enabled Reset: 1 <sub>B</sub>
<b>LIN</b>	2:1	rw	<b>Operation Mode:</b> 00 <sub>B</sub> , receive only mode 01 <sub>B</sub> , LIN/K-line operation 10 <sub>B</sub> , flash mode 11 <sub>B</sub> , receive only mode Reset: 10 <sub>B</sub>
<b>CAN</b>	0	rw	<b>CAN Operation Mode:</b> 0 <sub>B</sub> , receive only mode 1 <sub>B</sub> , high speed CAN mode Reset: 1 <sub>B</sub>

EOTConfig0 locked with LOCK = 1

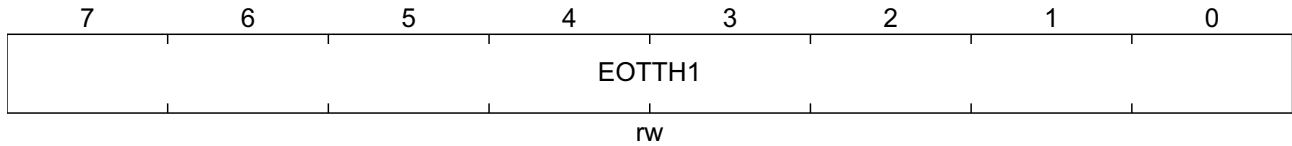
**EOTConfig0** **Offset**  
051<sub>H</sub> **Reset Value**  
00<sub>H</sub>



Field	Bits	Type	Description
<b>EOTTH0</b>	7:0	rw	<b>Engine Off Timer Comparator Threshold: (Bit 7 - 0)</b> Reset: 00 <sub>H</sub>

EOTConfig1 locked with LOCK = 1

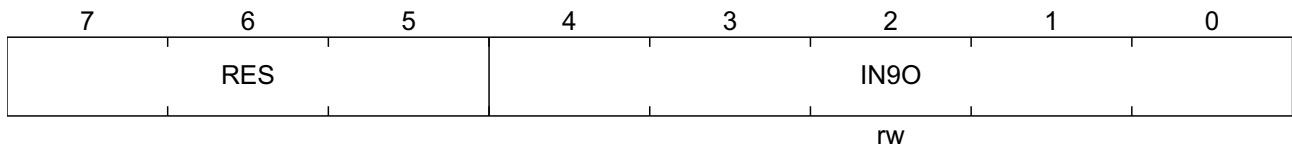
**EOTConfig1** **Offset** **Reset Value**  
**052<sub>H</sub>** **00<sub>H</sub>**



Field	Bits	Type	Description
<b>EOTTH1</b>	7:0	rw	<b>Engine Off Timer Comparator Threshold: (Bit 15 - 8)</b> Reset: 00 <sub>H</sub>

InConfig0 locked with LOCK = 1

**InConfig0** **Offset** **Reset Value**  
**053<sub>H</sub>** **00<sub>H</sub>**



Field	Bits	Type	Description
<b>IN90</b>	4:0	rw	<b>Direct control Input9 Assignment:</b> See <a href="#">Table 51</a> Reset: 00000 <sub>B</sub>

### Additional Table with Constants

This table describes more than 16 constants.

**Table 51 Constant Values**

Name and Description	Value
output5	00000 <sub>B</sub>
output6	00001 <sub>B</sub>
output7	00010 <sub>B</sub>
output8	00011 <sub>B</sub>

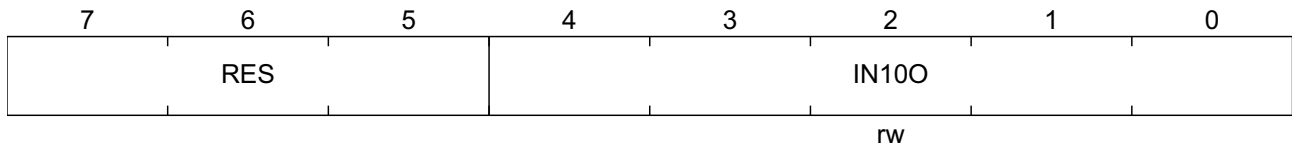


**Table 51 Constant Values (cont'd)**

<b>Name and Description</b>	<b>Value</b>
output9	00100 <sub>B</sub>
output10	00101 <sub>B</sub>
output11	00110 <sub>B</sub>
output12	00111 <sub>B</sub>
output13	01000 <sub>B</sub>
output14	01001 <sub>B</sub>
output15	01010 <sub>B</sub>
output16	01011 <sub>B</sub>
output17	01100 <sub>B</sub>
output18	01101 <sub>B</sub>
output19	01110 <sub>B</sub>
output20	01111 <sub>B</sub>
output21	10000 <sub>B</sub>
output22	10001 <sub>B</sub>
output23	10010 <sub>B</sub>
output24	10011 <sub>B</sub>

InConfig1 locked with LOCK = 1

<b>InConfig1</b>	<b>Offset</b> 054 <sub>H</sub>	<b>Reset Value</b> 00 <sub>H</sub>
------------------	-----------------------------------	---------------------------------------



Field	Bits	Type	Description
IN100	4:0	rw	<b>Direct control Input10 Assignment:</b> See <a href="#">Table 52</a> Reset: 00000 <sub>B</sub>

**Additional Table with Constants**

This table describes more than 16 constants.

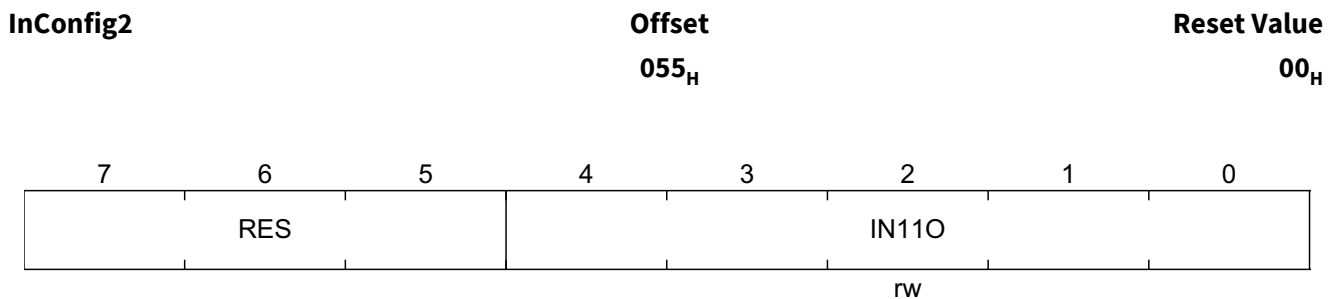
**Table 52 Constant Values**

Name and Description	Value
output5	00000 <sub>B</sub>
output6	00001 <sub>B</sub>
output7	00010 <sub>B</sub>
output8	00011 <sub>B</sub>
output9	00100 <sub>B</sub>
output10	00101 <sub>B</sub>
output11	00110 <sub>B</sub>
output12	00111 <sub>B</sub>
output13	01000 <sub>B</sub>
output14	01001 <sub>B</sub>
output15	01010 <sub>B</sub>
output16	01011 <sub>B</sub>
output17	01100 <sub>B</sub>
output18	01101 <sub>B</sub>

**Table 52 Constant Values (cont'd)**

Name and Description	Value
output19	01110 <sub>B</sub>
output20	01111 <sub>B</sub>
output21	10000 <sub>B</sub>
output22	10001 <sub>B</sub>
output23	10010 <sub>B</sub>
output24	10011 <sub>B</sub>

InConfig2 locked with LOCK = 1



Field	Bits	Type	Description
<b>IN110</b>	4:0	rw	<b>Direct control Input11 Assignment:</b> See <a href="#">Table 53</a> Reset: 00000 <sub>B</sub>

**Additional Table with Constants**

This table describes more than 16 constants.

**Table 53 Constant Values**

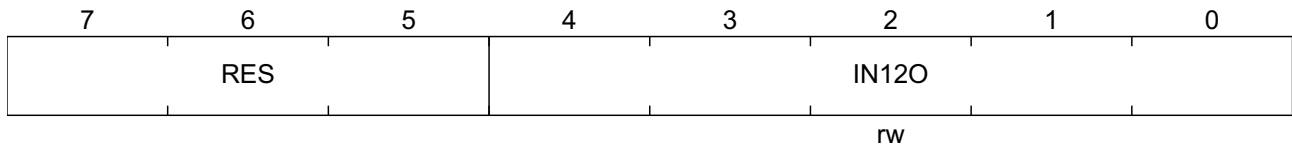
Name and Description	Value
output5	00000 <sub>B</sub>
output6	00001 <sub>B</sub>
output7	00010 <sub>B</sub>

**Table 53 Constant Values (cont'd)**

<b>Name and Description</b>	<b>Value</b>
output8	00011 <sub>B</sub>
output9	00100 <sub>B</sub>
output10	00101 <sub>B</sub>
output11	00110 <sub>B</sub>
output12	00111 <sub>B</sub>
output13	01000 <sub>B</sub>
output14	01001 <sub>B</sub>
output15	01010 <sub>B</sub>
output16	01011 <sub>B</sub>
output17	01100 <sub>B</sub>
output18	01101 <sub>B</sub>
output19	01110 <sub>B</sub>
output20	01111 <sub>B</sub>
output21	10000 <sub>B</sub>
output22	10001 <sub>B</sub>
output23	10010 <sub>B</sub>
output24	10011 <sub>B</sub>

InConfig3 locked with LOCK = 1

<b>InConfig3</b>	<b>Offset</b> 056 <sub>H</sub>	<b>Reset Value</b> 00 <sub>H</sub>
------------------	-----------------------------------	---------------------------------------



Field	Bits	Type	Description
IN120	4:0	rw	<b>Direct control Input12 Assignment:</b> See <a href="#">Table 54</a> Reset: 00000 <sub>B</sub>

**Additional Table with Constants**

This table describes more than 16 constants.

**Table 54 Constant Values**

Name and Description	Value
output5	00000 <sub>B</sub>
output6	00001 <sub>B</sub>
output7	00010 <sub>B</sub>
output8	00011 <sub>B</sub>
output9	00100 <sub>B</sub>
output10	00101 <sub>B</sub>
output11	00110 <sub>B</sub>
output12	00111 <sub>B</sub>
output13	01000 <sub>B</sub>
output14	01001 <sub>B</sub>
output15	01010 <sub>B</sub>
output16	01011 <sub>B</sub>
output17	01100 <sub>B</sub>
output18	01101 <sub>B</sub>

**Table 54 Constant Values (cont'd)**

Name and Description	Value
output19	01110 <sub>B</sub>
output20	01111 <sub>B</sub>
output21	10000 <sub>B</sub>
output22	10001 <sub>B</sub>
output23	10010 <sub>B</sub>
output24	10011 <sub>B</sub>

DDConfig0 locked with LOCK = 1

DDConfig0								Offset	Reset Value
								057 <sub>H</sub>	00 <sub>H</sub>
7	6	5	4	3	2	1	0		
O8DD	O7DD	O6DD	O5DD	O4DD	O3DD	O2DD	O1DD		
rw	rw	rw	rw	rw	rw	rw	rw		

Field	Bits	Type	Description
<b>O8DD</b>	7	rw	<b>Output8 Direct Drive Control: see below</b> Reset: 0 <sub>B</sub>
<b>O7DD</b>	6	rw	<b>Output7 Direct Drive Control: see below</b> Reset: 0 <sub>B</sub>
<b>O6DD</b>	5	rw	<b>Output6 Direct Drive Control: see below</b> Reset: 0 <sub>B</sub>
<b>O5DD</b>	4	rw	<b>Output5 Direct Drive Control: see below</b> Reset: 0 <sub>B</sub>
<b>O4DD</b>	3	rw	<b>Output4 Direct Drive Control: see below</b> Reset: 0 <sub>B</sub>
<b>O3DD</b>	2	rw	<b>Output3 Direct Drive Control: see below</b> Reset: 0 <sub>B</sub>
<b>O2DD</b>	1	rw	<b>Output2 Direct Drive Control: see below</b> Reset: 0 <sub>B</sub>

Field	Bits	Type	Description
<b>O1DD</b>	0	rw	<b>Output1 Direct Drive Control:</b> $0_B$ , controlled by MSC/SPI interface $1_B$ , controlled by Direct Drive Input Reset: $0_B$

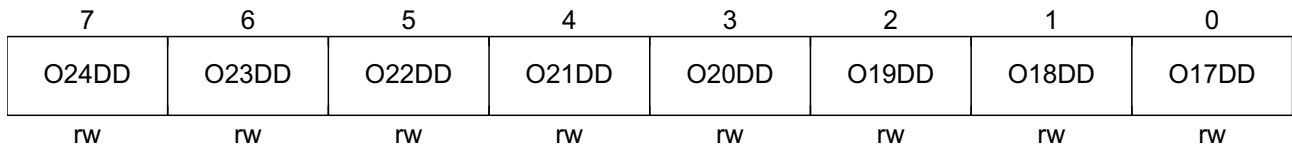
DDConfig1 locked with LOCK = 1

<b>DDConfig1</b>								<b>Offset</b>	<b>Reset Value</b>
								<b>058<sub>H</sub></b>	<b>00<sub>H</sub></b>
7	6	5	4	3	2	1	0		
O16DD	O15DD	O14DD	O13DD	O12DD	O11DD	O10DD	O9DD		
rw	rw	rw	rw	rw	rw	rw	rw		

Field	Bits	Type	Description
<b>O16DD</b>	7	rw	<b>Output16 Direct Drive Control: see below</b> Reset: $0_B$
<b>O15DD</b>	6	rw	<b>Output15 Direct Drive Control: see below</b> Reset: $0_B$
<b>O14DD</b>	5	rw	<b>Output14 Direct Drive Control: see below</b> Reset: $0_B$
<b>O13DD</b>	4	rw	<b>Output13 Direct Drive Control: see below</b> Reset: $0_B$
<b>O12DD</b>	3	rw	<b>Output12 Direct Drive Control: see below</b> Reset: $0_B$
<b>O11DD</b>	2	rw	<b>Output11 Direct Drive Control: see below</b> Reset: $0_B$
<b>O10DD</b>	1	rw	<b>Output10 Direct Drive Control: see below</b> Reset: $0_B$
<b>O9DD</b>	0	rw	<b>Output9 Direct Drive Control:</b> $0_B$ , controlled by MSC/SPI interface $1_B$ , controlled by Direct Drive Input Reset: $0_B$

DDConfig2 locked with LOCK = 1

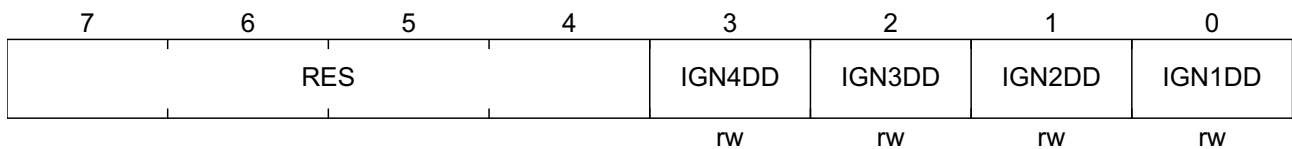
<b>DDConfig2</b>		<b>Offset</b>	<b>Reset Value</b>
		<b>059<sub>H</sub></b>	<b>00<sub>H</sub></b>



Field	Bits	Type	Description
<b>O24DD</b>	7	rw	<b>Output24 Direct Drive Control: see below</b> Reset: 0 <sub>B</sub>
<b>O23DD</b>	6	rw	<b>Output23 Direct Drive Control: see below</b> Reset: 0 <sub>B</sub>
<b>O22DD</b>	5	rw	<b>Output22 Direct Drive Control: see below</b> Reset: 0 <sub>B</sub>
<b>O21DD</b>	4	rw	<b>Output21 Direct Drive Control: see below</b> Reset: 0 <sub>B</sub>
<b>O20DD</b>	3	rw	<b>Output20 Direct Drive Control: see below</b> Reset: 0 <sub>B</sub>
<b>O19DD</b>	2	rw	<b>Output19 Direct Drive Control: see below</b> Reset: 0 <sub>B</sub>
<b>O18DD</b>	1	rw	<b>Output18 Direct Drive Control: see below</b> Reset: 0 <sub>B</sub>
<b>O17DD</b>	0	rw	<b>Output17 Direct Drive Control:</b> 0 <sub>B</sub> , controlled by MSC/SPI interface 1 <sub>B</sub> , controlled by Direct Drive Input Reset: 0 <sub>B</sub>

DDConfig3 locked with LOCK = 1

**DDConfig3** **Offset** **Reset Value**  
**05A<sub>H</sub>** **00<sub>H</sub>**



Field	Bits	Type	Description
<b>IGN4DD</b>	3	rw	<b>Ignition Output4 Direct Drive Control: see below</b> Reset: 0 <sub>B</sub>
<b>IGN3DD</b>	2	rw	<b>Ignition Output3 Direct Drive Control: see below</b> Reset: 0 <sub>B</sub>

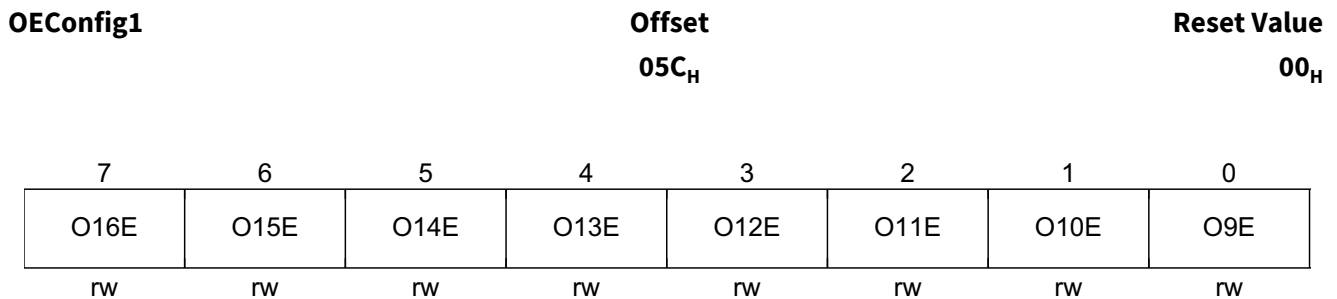


Field	Bits	Type	Description
<b>IGN2DD</b>	1	rw	<b>Ignition Output2 Direct Drive Control: see below</b> Reset: 0 <sub>B</sub>
<b>IGN1DD</b>	0	rw	<b>Ignition Output1 Direct Drive Control:</b> 0 <sub>B</sub> , controlled by MSC/SPI interface 1 <sub>B</sub> , controlled by Direct Drive Input Reset: 0 <sub>B</sub>

<b>OEConfig0</b>								<b>Offset</b>	<b>Reset Value</b>
								<b>05B<sub>H</sub></b>	<b>00<sub>H</sub></b>
7	6	5	4	3	2	1	0		
O8E	O7E	O6E	O5E	O4E	O3E	O2E	O1E		
rw	rw	rw	rw	rw	rw	rw	rw		

Field	Bits	Type	Description
<b>O8E</b>	7	rw	<b>Output8 Enable Bit:</b> 0 <sub>B</sub> , output disabled 1 <sub>B</sub> , output enabled Reset: 0 <sub>B</sub>
<b>O7E</b>	6	rw	<b>Output7 Enable Bit:</b> 0 <sub>B</sub> , output disabled 1 <sub>B</sub> , output enabled Reset: 0 <sub>B</sub>
<b>O6E</b>	5	rw	<b>Output6 Enable Bit:</b> 0 <sub>B</sub> , output disabled 1 <sub>B</sub> , output enabled Reset: 0 <sub>B</sub>
<b>O5E</b>	4	rw	<b>Output5 Enable Bit:</b> 0 <sub>B</sub> , output disabled 1 <sub>B</sub> , output enabled Reset: 0 <sub>B</sub>
<b>O4E</b>	3	rw	<b>Output4 Enable Bit:</b> 0 <sub>B</sub> , output disabled 1 <sub>B</sub> , output enabled Reset: 0 <sub>B</sub>
<b>O3E</b>	2	rw	<b>Output3 Enable Bit:</b> 0 <sub>B</sub> , output disabled 1 <sub>B</sub> , output enabled Reset: 0 <sub>B</sub>

Field	Bits	Type	Description
<b>O2E</b>	1	rw	<b>Output2 Enable Bit:</b> 0 <sub>B</sub> , output disabled 1 <sub>B</sub> , output enabled Reset: 0 <sub>B</sub>
<b>O1E</b>	0	rw	<b>Output1 Enable Bit:</b> 0 <sub>B</sub> , output disabled 1 <sub>B</sub> , output enabled Reset: 0 <sub>B</sub>



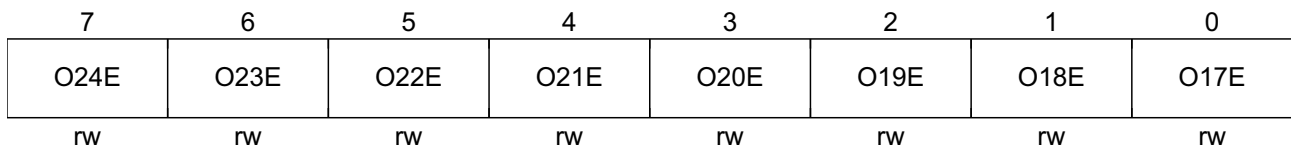
Field	Bits	Type	Description
<b>O16E</b>	7	rw	<b>Output16 Enable Bit:</b> 0 <sub>B</sub> , output disabled 1 <sub>B</sub> , output enabled Reset: 0 <sub>B</sub>
<b>O15E</b>	6	rw	<b>Output15 Enable Bit:</b> 0 <sub>B</sub> , output disabled 1 <sub>B</sub> , output enabled Reset: 0 <sub>B</sub>
<b>O14E</b>	5	rw	<b>Output14 Enable Bit:</b> 0 <sub>B</sub> , output disabled 1 <sub>B</sub> , output enabled Reset: 0 <sub>B</sub>
<b>O13E</b>	4	rw	<b>Output13 Enable Bit:</b> 0 <sub>B</sub> , output disabled 1 <sub>B</sub> , output enabled Reset: 0 <sub>B</sub>
<b>O12E</b>	3	rw	<b>Output12 Enable Bit:</b> 0 <sub>B</sub> , output disabled 1 <sub>B</sub> , output enabled Reset: 0 <sub>B</sub>

Field	Bits	Type	Description
<b>O11E</b>	2	rw	<b>Output11 Enable Bit:</b> 0 <sub>B</sub> , output disabled 1 <sub>B</sub> , output enabled Reset: 0 <sub>B</sub>
<b>O10E</b>	1	rw	<b>Output10 Enable Bit:</b> 0 <sub>B</sub> , output disabled 1 <sub>B</sub> , output enabled Reset: 0 <sub>B</sub>
<b>O9E</b>	0	rw	<b>Output9 Enable Bit:</b> 0 <sub>B</sub> , output disabled 1 <sub>B</sub> , output enabled Reset: 0 <sub>B</sub>

**OEConfig2**

**Offset**  
**05D<sub>H</sub>**

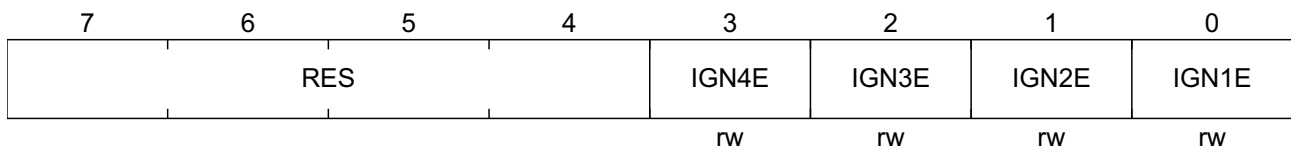
**Reset Value**  
**00<sub>H</sub>**



Field	Bits	Type	Description
<b>O24E</b>	7	rw	<b>Output24 Enable Bit:</b> 0 <sub>B</sub> , output disabled 1 <sub>B</sub> , output enabled Reset: 0 <sub>B</sub>
<b>O23E</b>	6	rw	<b>Output23 Enable Bit:</b> 0 <sub>B</sub> , output disabled 1 <sub>B</sub> , output enabled Reset: 0 <sub>B</sub>
<b>O22E</b>	5	rw	<b>Output22 Enable Bit:</b> 0 <sub>B</sub> , output disabled 1 <sub>B</sub> , output enabled Reset: 0 <sub>B</sub>
<b>O21E</b>	4	rw	<b>Output21 Enable Bit:</b> 0 <sub>B</sub> , output disabled 1 <sub>B</sub> , output enabled Reset: 0 <sub>B</sub>

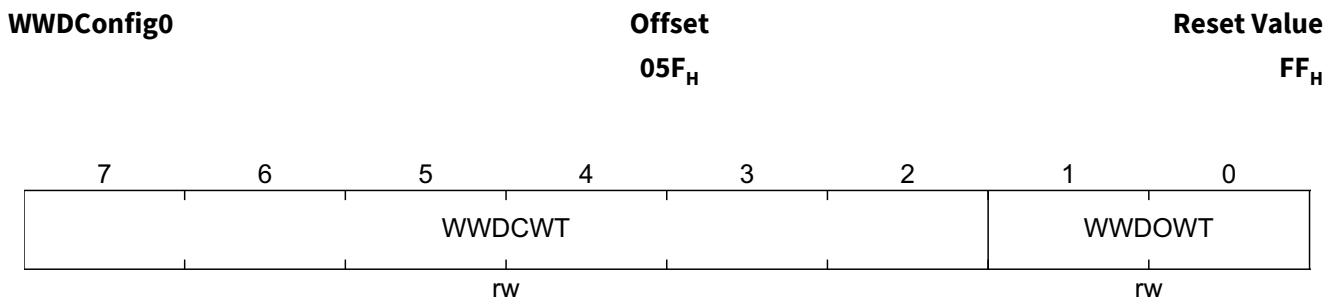
Field	Bits	Type	Description
<b>O20E</b>	3	rw	<b>Output20 Enable Bit:</b> 0 <sub>B</sub> , output disabled 1 <sub>B</sub> , output enabled Reset: 0 <sub>B</sub>
<b>O19E</b>	2	rw	<b>Output19 Enable Bit:</b> 0 <sub>B</sub> , output disabled 1 <sub>B</sub> , output enabled Reset: 0 <sub>B</sub>
<b>O18E</b>	1	rw	<b>Output18 Enable Bit:</b> 0 <sub>B</sub> , output disabled 1 <sub>B</sub> , output enabled Reset: 0 <sub>B</sub>
<b>O17E</b>	0	rw	<b>Output17 Enable Bit:</b> 0 <sub>B</sub> , output disabled 1 <sub>B</sub> , output enabled Reset: 0 <sub>B</sub>

**OEConfig3** **Offset** **Reset Value**  
**05E<sub>H</sub>** **00<sub>H</sub>**

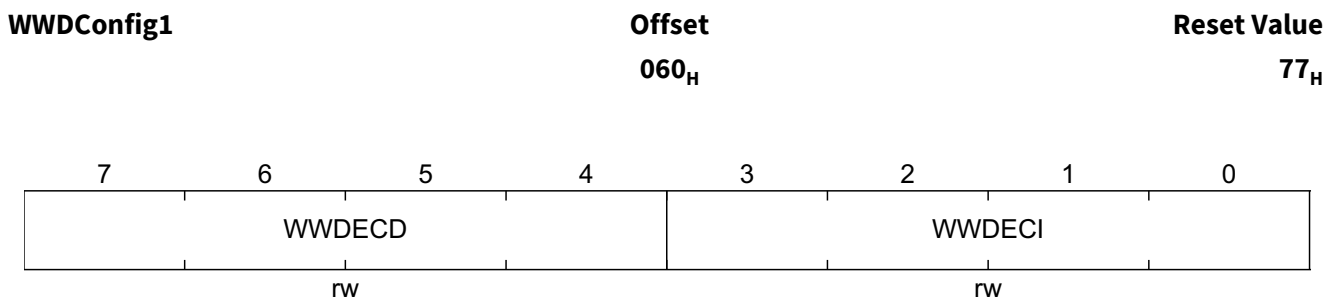


Field	Bits	Type	Description
<b>IGN4E</b>	3	rw	<b>Ignition 4 Output Enable Bit:</b> 0 <sub>B</sub> , output disabled 1 <sub>B</sub> , output enabled Reset: 0 <sub>B</sub>
<b>IGN3E</b>	2	rw	<b>Ignition 3 Output Enable Bit:</b> 0 <sub>B</sub> , output disabled 1 <sub>B</sub> , output enabled Reset: 0 <sub>B</sub>
<b>IGN2E</b>	1	rw	<b>Ignition 2 Output Enable Bit:</b> 0 <sub>B</sub> , output disabled 1 <sub>B</sub> , output enabled Reset: 0 <sub>B</sub>

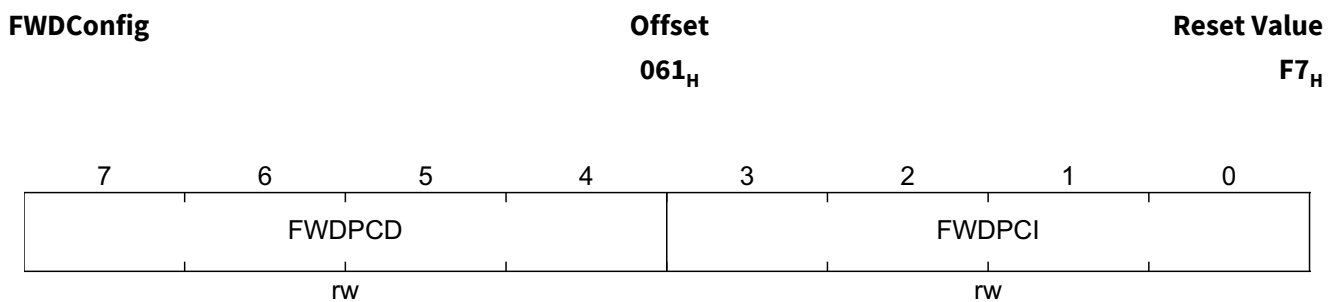
Field	Bits	Type	Description
IGN1E	0	rw	<b>Ignition 1 Output Enable Bit:</b> 0 <sub>B</sub> , output disabled 1 <sub>B</sub> , output enabled Reset: 0 <sub>B</sub>



Field	Bits	Type	Description
WWDCWT	7:2	rw	<b>Window Watchdog Closed Window Time:</b> 000000 <sub>B</sub> , no change - old setting used for open and closed window 000001 <sub>B</sub> , 1,6 ms 111111 <sub>B</sub> , 100,8 ms Reset: 111111 <sub>B</sub>
WWDOWT	1:0	rw	<b>Window Watchdog Open Window Time:</b> 00 <sub>B</sub> , 3,2 ms 01 <sub>B</sub> , 6,4 ms 10 <sub>B</sub> , 9,6 ms 11 <sub>B</sub> , 12,8 ms Reset: 11 <sub>B</sub>

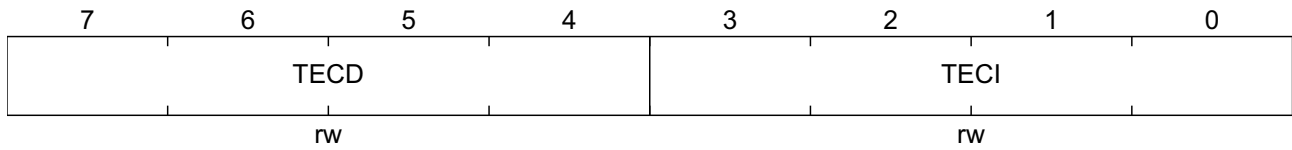


Field	Bits	Type	Description
WWDECD	7:4	rw	<b>Window Watchdog Error Counter Decrement:</b> 0000 <sub>B</sub> , -1 0001 <sub>B</sub> , -2 1111 <sub>B</sub> , -16 Reset: 0111 <sub>B</sub>
WWDECI	3:0	rw	<b>Window Watchdog Error Counter Increment:</b> 0000 <sub>B</sub> , +1 0001 <sub>B</sub> , +2 1111 <sub>B</sub> , +16 Reset: 0111 <sub>B</sub>



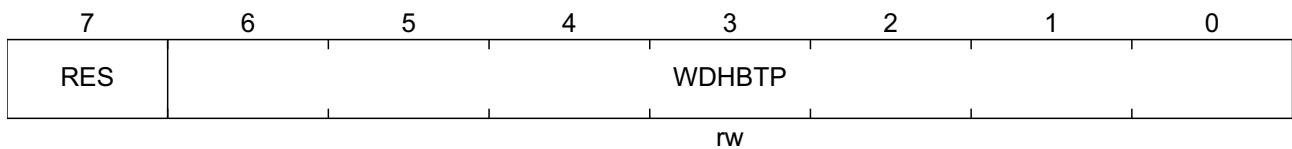
Field	Bits	Type	Description
FWDCD	7:4	rw	<b>Functional Watchdog Pass Counter Decrement:</b> 0000 <sub>B</sub> , -1 0001 <sub>B</sub> , -2 1111 <sub>B</sub> , -16 Reset: 1111 <sub>B</sub>
FWDCI	3:0	rw	<b>Functional Watchdog Pass Counter Increment:</b> 0000 <sub>B</sub> , +1 0001 <sub>B</sub> , +2 1111 <sub>B</sub> , +16 Reset: 0111 <sub>B</sub>





Field	Bits	Type	Description
<b>TECD</b>	7:4	rw	<b>Total Error Counter Decrement:</b> 0000 <sub>B</sub> , -1 0001 <sub>B</sub> , -2 1111 <sub>B</sub> , -16 Reset: 0111 <sub>B</sub>
<b>TECI</b>	3:0	rw	<b>Total Error Counter Increment:</b> 0000 <sub>B</sub> , +1 0001 <sub>B</sub> , +2 1111 <sub>B</sub> , +16 Reset: 0111 <sub>B</sub>

**WDConfig0** **Offset** **Reset Value**  
**063<sub>H</sub>** **47<sub>H</sub>**



Field	Bits	Type	Description
<b>WDHBTP</b>	6:0	rw	<b>Watchdog Heartbeat Timer Period:</b> 0000000 <sub>B</sub> , no change 0000001 <sub>B</sub> , 1,6 ms 0000010 <sub>B</sub> , 3,2 ms 1111111 <sub>B</sub> , 203,2 ms Reset: 1000111 <sub>B</sub>

WDConfig1 locked with LOCK = 1

**WDConfig1** **Offset** **Reset Value**  
**064<sub>H</sub>** **03<sub>H</sub>**





Field	Bits	Type	Description
O8ON	7	rw	<b>Output8 Switch on Control Bit:</b> 0 <sub>B</sub> , off 1 <sub>B</sub> , on Reset: 0 <sub>B</sub>
O7ON	6	rw	<b>Output7 Switch on Control Bit:</b> 0 <sub>B</sub> , off 1 <sub>B</sub> , on Reset: 0 <sub>B</sub>
O6ON	5	rw	<b>Output6 Switch on Control Bit:</b> 0 <sub>B</sub> , off 1 <sub>B</sub> , on Reset: 0 <sub>B</sub>
O5ON	4	rw	<b>Output5 Switch on Control Bit:</b> 0 <sub>B</sub> , off 1 <sub>B</sub> , on Reset: 0 <sub>B</sub>
O4ON	3	rw	<b>Output4 Switch on Control Bit:</b> 0 <sub>B</sub> , off 1 <sub>B</sub> , on Reset: 0 <sub>B</sub>
O3ON	2	rw	<b>Output3 Switch on Control Bit:</b> 0 <sub>B</sub> , off 1 <sub>B</sub> , on Reset: 0 <sub>B</sub>
O2ON	1	rw	<b>Output2 Switch on Control Bit:</b> 0 <sub>B</sub> , off 1 <sub>B</sub> , on Reset: 0 <sub>B</sub>
O1ON	0	rw	<b>Output1 Switch on Control Bit:</b> 0 <sub>B</sub> , off 1 <sub>B</sub> , on Reset: 0 <sub>B</sub>

Cont1

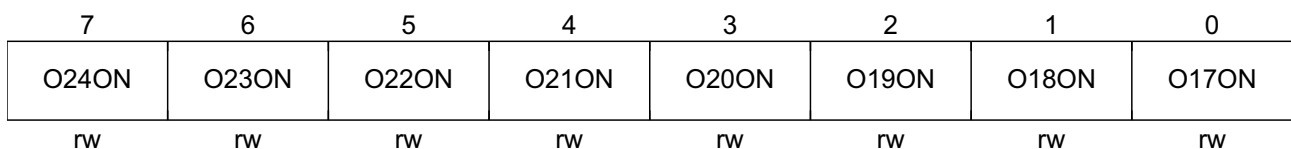
Offset  
07C<sub>H</sub>

Reset Value  
00<sub>H</sub>

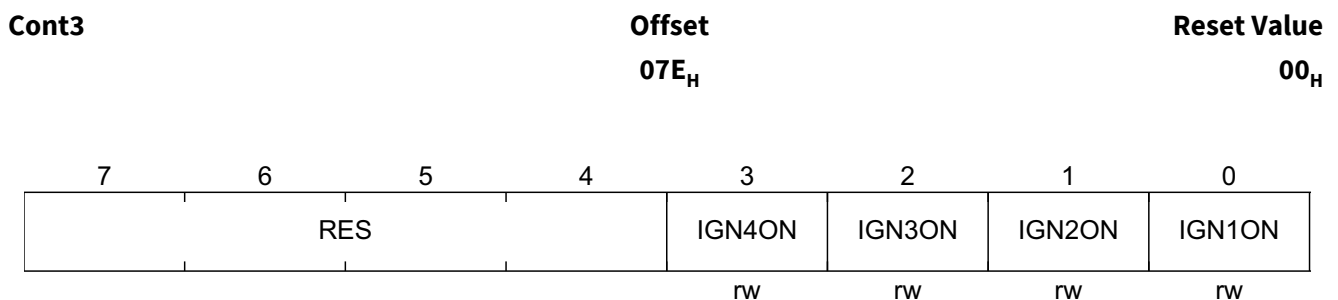
7	6	5	4	3	2	1	0
O16ON	O15ON	O14ON	O13ON	O12ON	O11ON	O10ON	O9ON
rw	rw	rw	rw	rw	rw	rw	rw

Field	Bits	Type	Description
<b>O16ON</b>	7	rw	<b>Output16 Switch on Control Bit:</b> $0_B$ , off $1_B$ , on Reset: $0_B$
<b>O15ON</b>	6	rw	<b>Output15 Switch on Control Bit:</b> $0_B$ , off $1_B$ , on Reset: $0_B$
<b>O14ON</b>	5	rw	<b>Output14 Switch on Control Bit:</b> $0_B$ , off $1_B$ , on Reset: $0_B$
<b>O13ON</b>	4	rw	<b>Output13 Switch on Control Bit:</b> $0_B$ , off $1_B$ , on Reset: $0_B$
<b>O12ON</b>	3	rw	<b>Output12 Switch on Control Bit:</b> $0_B$ , off $1_B$ , on Reset: $0_B$
<b>O11ON</b>	2	rw	<b>Output11 Switch on Control Bit:</b> $0_B$ , off $1_B$ , on Reset: $0_B$
<b>O10ON</b>	1	rw	<b>Output10 Switch on Control Bit:</b> $0_B$ , off $1_B$ , on Reset: $0_B$
<b>O9ON</b>	0	rw	<b>Output9 Switch on Control Bit:</b> $0_B$ , off $1_B$ , on Reset: $0_B$

**Cont2** **Offset** **Reset Value**  
**07D<sub>H</sub>** **00<sub>H</sub>**



Field	Bits	Type	Description
<b>O24ON</b>	7	rw	<b>Output24 Switch on Control Bit:</b> $0_B$ , off $1_B$ , on Reset: $0_B$
<b>O23ON</b>	6	rw	<b>Output23 Switch on Control Bit:</b> $0_B$ , off $1_B$ , on Reset: $0_B$
<b>O22ON</b>	5	rw	<b>Output22 Switch on Control Bit:</b> $0_B$ , off $1_B$ , on Reset: $0_B$
<b>O21ON</b>	4	rw	<b>Output21 Switch on Control Bit:</b> $0_B$ , off $1_B$ , on Reset: $0_B$
<b>O20ON</b>	3	rw	<b>Output20 Switch on Control Bit:</b> $0_B$ , off $1_B$ , on Reset: $0_B$
<b>O19ON</b>	2	rw	<b>Output19 Switch on Control Bit:</b> $0_B$ , off $1_B$ , on Reset: $0_B$
<b>O18ON</b>	1	rw	<b>Output18 Switch on Control Bit:</b> $0_B$ , off $1_B$ , on Reset: $0_B$
<b>O17ON</b>	0	rw	<b>Output17 Switch on Control Bit:</b> $0_B$ , off $1_B$ , on Reset: $0_B$



Field	Bits	Type	Description
<b>IGN4ON</b>	3	rw	<b>Ignition Output4 Switch on Control Bit:</b> $0_B$ , off $1_B$ , on Reset: $0_B$
<b>IGN3ON</b>	2	rw	<b>Ignition Output3 Switch on Control Bit:</b> $0_B$ , off $1_B$ , on Reset: $0_B$
<b>IGN2ON</b>	1	rw	<b>Ignition Output2 Switch on Control Bit:</b> $0_B$ , off $1_B$ , on Reset: $0_B$
<b>IGN1ON</b>	0	rw	<b>Ignition Output1 Switch on Control Bit:</b> $0_B$ , off $1_B$ , on Reset: $0_B$

SPI

## 15 SPI

Alternatively to the MSC communication interface a SPI interface is available. It uses the pins *SIP*, *SDO*, *CSN* and *FCLP*. The configuration is done via the pins *FCLN* and *SIN*. *FCLN* must be connected to *VDDIO* and *SIN* must be connected to *AGND*. In SPI mode the output stage of the pin *SDO* is set to push pull operation (definition and description see [Chapter 13.2](#) and [Chapter 13.4](#)).

The definition of the registers is the same as for the MSC communication (see [Chapter 14](#)), only the frame is SPI specific (see [Figure 67](#) and [Chapter 15.1](#)). Multiple read commands are not allowed.

There is no monitoring of valid transmissions implemented (like MSC monitoring, see [Chapter 13.1.1](#)).

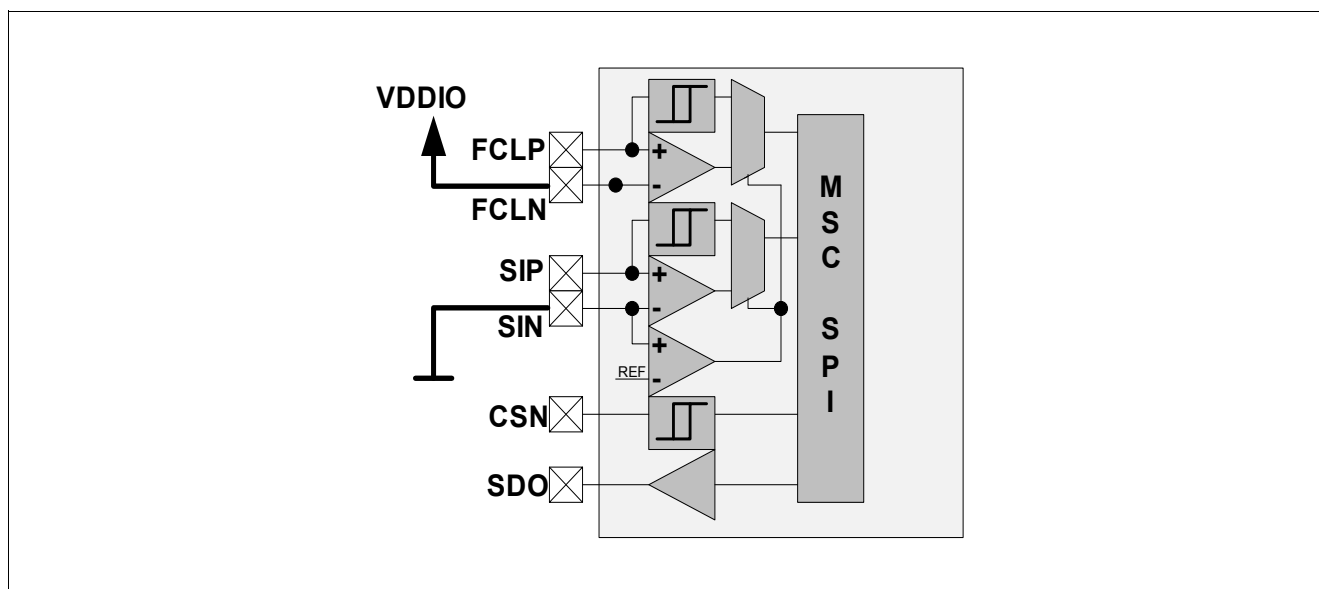


Figure 66 Block diagram of the SPI interface

### 15.1 SPI Protocol

The principle of the SPI communication is shown in [Figure 67](#). The message from the microcontroller must be sent LSB first. The data from the *SDO* pin is sent LSB first. The TLE8888-1QK samples data from the *SIP* pin on the falling edge of *FCLP* and shifts data out of the *SDO* pin on the rising edge of *FCLP*. Each access must be terminated by a rising edge of *CSN*.

All SPI messages must be exactly 16 bits long, otherwise the SPI message is discarded and the bit **COMFE** in diagnosis register **ComDiag** is set to "1".

There is one message delay in the response to each message (i.e. the response for message N will be returned during message N+1).

There are two valid access possible:

- Write access to registers with write permission: the answer is 1 for the R/W bit, the address and the content of the register
- Read access to register with read permission: the answer is 0 for the R/W bit, the address and the content of the register

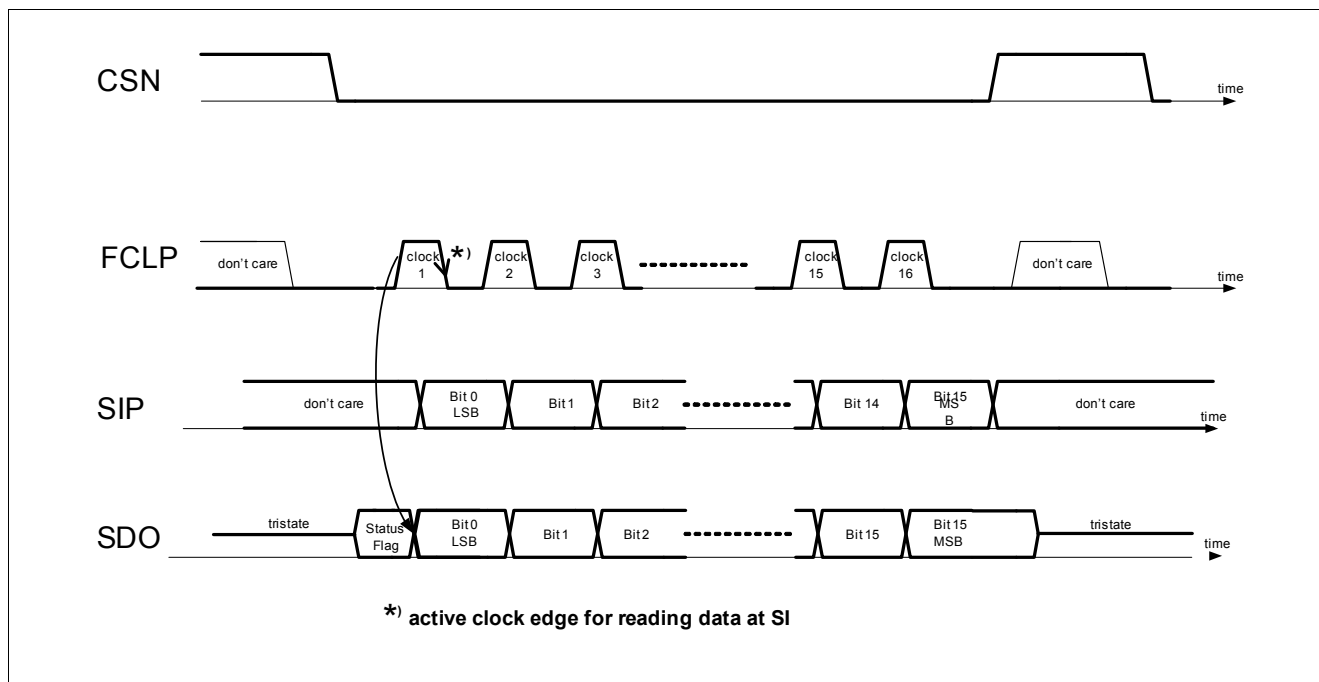
Everything else is not executed.

Write access to multiple read commands are also not valid in SPI mode.

**SPI**

Status Flag Indication: after the falling edge of *CSN* and before the first rising edge of *FCLP* the level of the *SDO* indicates an OR combination of the status of the central failure bit **CF** and the central overtemperature bit **COT** of the diagnosis register **Diag0**.

With this feature during every SPI communication a check of the diagnosis status can be done without additional read access of the diagnosis register.



**Figure 67 SPI Protocol**

SPI Answers:

- during power on reset: SPI commands are ignored, *SDO* is always tristate
- after power on reset: the address and the content of the status register **OpStat0** is transmitted with the next SPI transmission
- during watchdog reset: SPI commands are ignored, *SDO* has the value of the status flag
- after watchdog reset: the address and the content of the diagnosis register **FWDStat1** is transmitted with the first SPI transmission after the low to high transition of *RST*
- after a read or write command: the address and content of the selected register is transmitted with the next SPI transmission (for not existing addresses or wrong access mode the data is always “0”)
- after an invalid communication frame: the address and the content of the diagnosis register **Diag0** is transmitted with the next SPI transmission and the bit **COMFE** in diagnosis register **ComDiag** is set to “1”

SPI

15.2 SPI Frame Definition

Overview SPI Frame

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
CD7	CD6	CD5	CD4	CD3	CD2	CD1	CD0	C7	C6	C5	C4	C3	C2	C1	C0

Field	Bits	Type	Description
C0	0		R/W Bit: defines the access to the register
C[7:1]	[7:1]		Address Bits, definition see <a href="#">Chapter 14</a>
CD[7:0]	[15:8]		Data Bits, definition see <a href="#">Chapter 14</a>

**SPI**

**15.3 Electrical Characteristics SPI**

**Table 55 Electrical Characteristics Communication**

$V_S = 13.5\text{ V}$ ,  $V_{VSV} = 5\text{ V}$ ,  $T_j = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ , all voltages with respect to GND, positive current flowing into pin, (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
SPI detection threshold for <i>SIN</i>	VFCLN_SPI	0.3	–	0.7	V		P_15.1
Single ended mode detection threshold for <i>FCLN</i>	VFCLN_singl e	2	–	3	V		P_15.2
<i>SDO</i>						see <a href="#">Chapter 13.4</a>	P_15.3
Input low level ( <i>SIP, FCLP, CSN</i> )	VINn_L	-0.3	–	0.8	V		P_15.4
Input high level ( <i>SIP, FCLP, CSN</i> )	VINn_H	1.6	–	5.5	V		P_15.5
Input hysteresis ( <i>SIP, FCLP, CSN</i> )	VINn_Hys	0.1	–	0.5	V		P_15.6
Clock frequency	fSPI	–	–	5	MHz		P_15.7



## **16 EMC Requirements**

### **16.1 ISO Pulse Tests**

Definitions for all ISO pulse test on application including the TLE8888-1QK are regarding standard ISO 7637-2:2011. The following amplitude definitions for the tests are required:

- Pulse 3a:  $V_S = -140\text{ V}$ , all outputs available on ECU connector
- Pulse 3b:  $V_S = 140\text{ V}$ , all outputs available on ECU connector
- Pulse 5:  $V_S = +38.5\text{ V}$  (clamped),  $t_d = 400\text{ ms}$  (ECU reset is permitted under this test, outputs will be switched off)

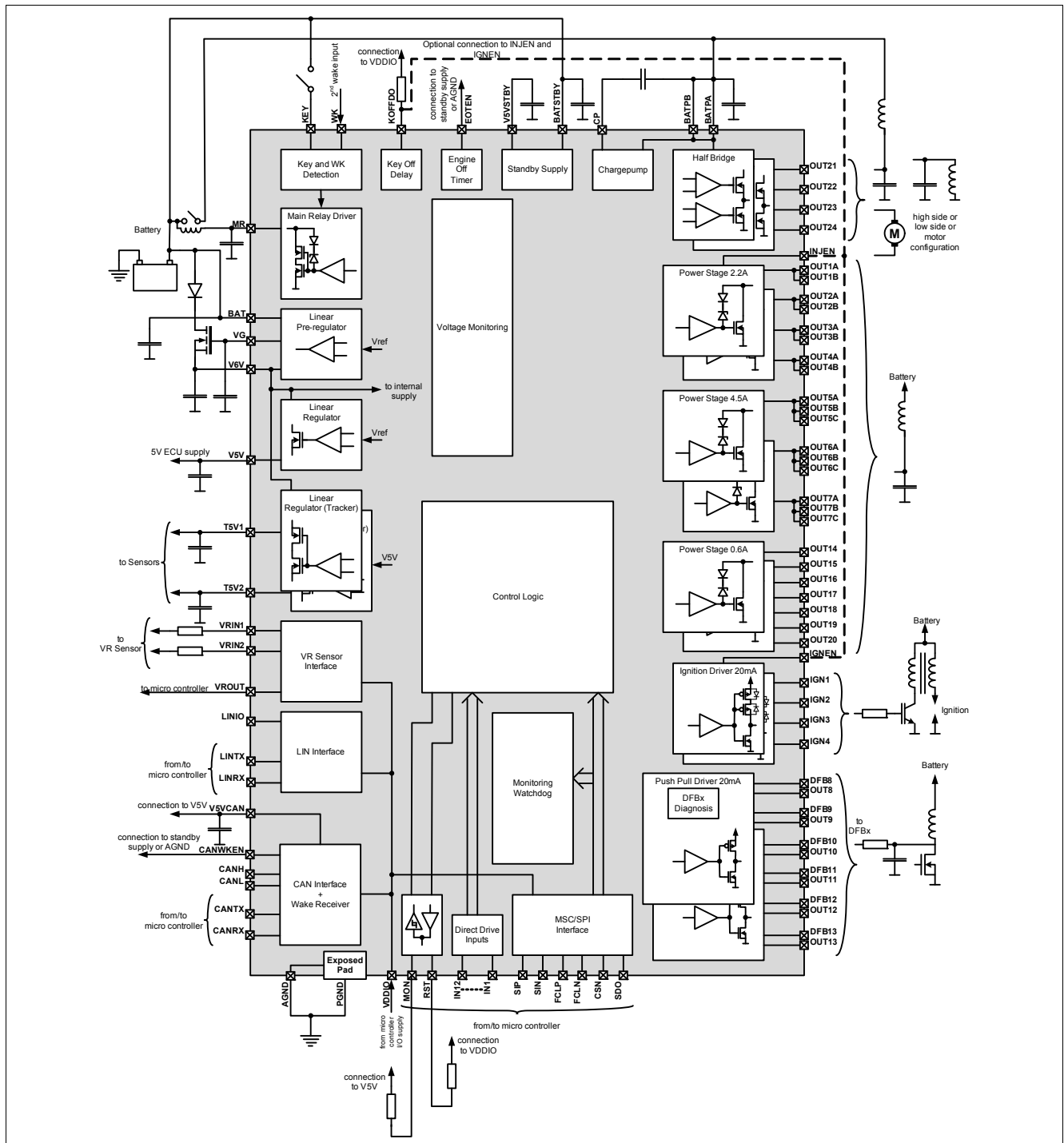
The tests are performed only on application level.

**Application Information**

**17 Application Information**

*Note: The information in this chapter is given as a hint for the implementation of the device only and shall not be regarded as a description or warranty of a certain functionality, condition or quality of the device.*

*Note: These are very simplified examples of application circuits. The functions must be verified in the real application.*



**Figure 68 Application Diagram**

Application Information

17.1 Supply Systems

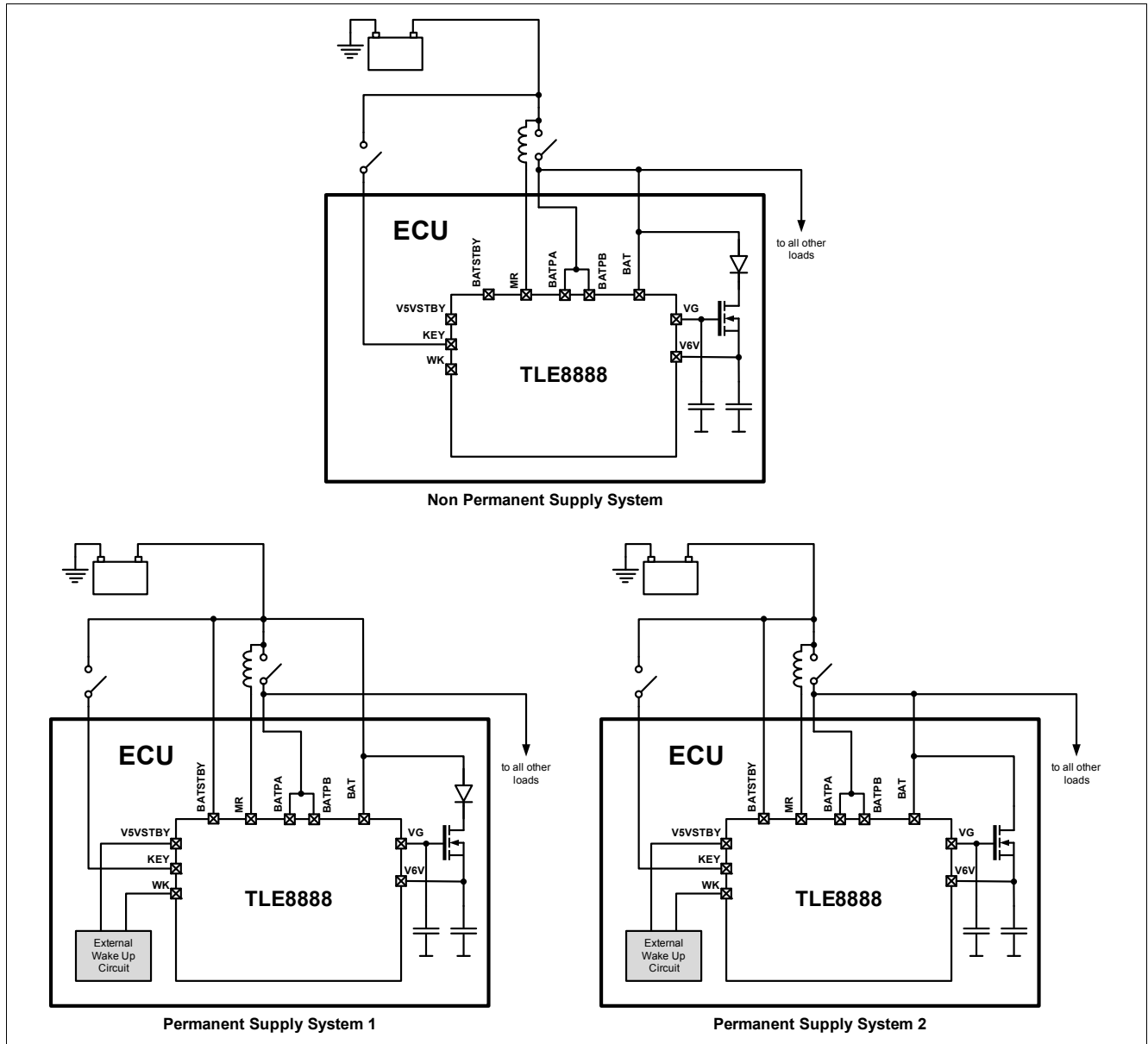


Figure 69 Application Diagram Supply Systems

In [Figure 69](#) three setups for connecting the battery supply to the TLE8888-1QK are shown. With non permanent battery supply there is no standby supply available and all functions related to this supply (e.g. engine off timer) are not active. Wake-up could be done by a signal at the pins *KEY* and *WK*.

In a permanent supply system the standby supply is permanently connected to the battery and all functions related to this supply can be enabled (e.g. CAN remote wake-up). The pins *BATPA* and *BATPB* must be connected to the switched battery supply because there is no special mode to reduce the current consumption in standby mode. The pin *BAT* and the external MOSFET of the pre regulator are allowed to be connected permanently to the battery.

Application Information

17.2 VR Sensor Interface

For Hall sensor signal detection in [Figure 70](#) and [Figure 71](#) different proposals for the external devices are shown. For the description of the set ups see [Chapter 10](#).

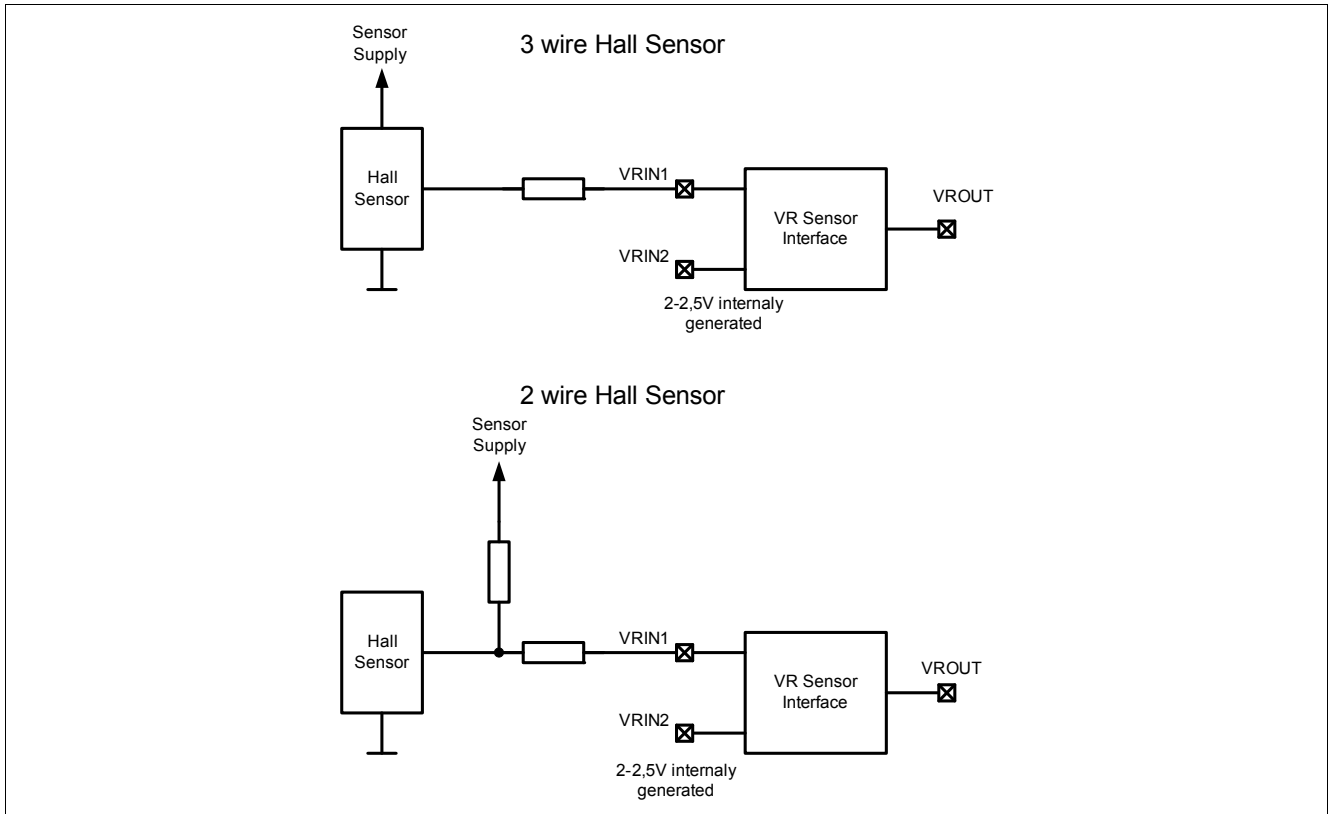


Figure 70 Application Circuit for VR Sensor Interface used for Hall Sensor in Hall Mode Set Up

Application Information

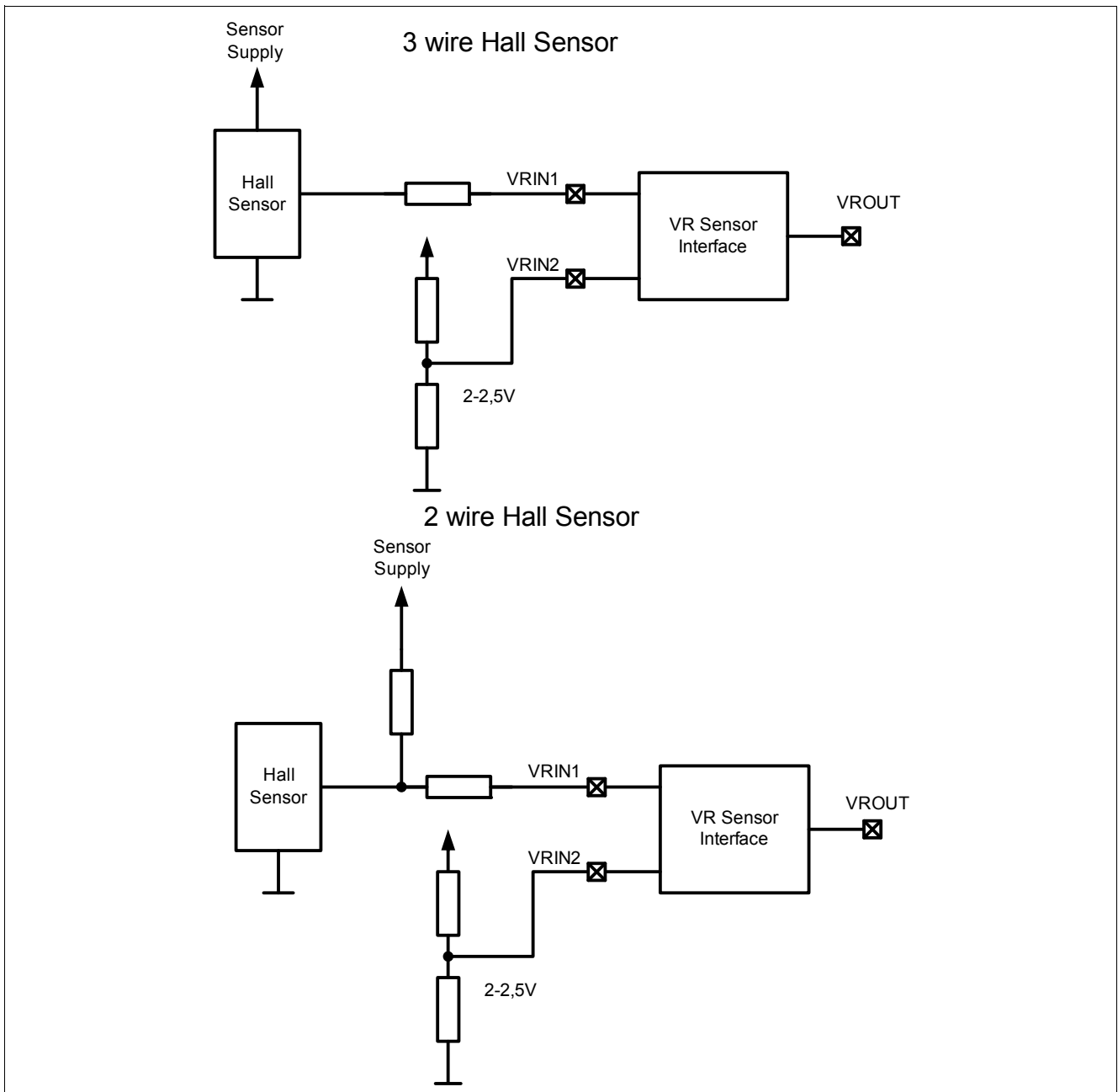


Figure 71 Application Circuit for VR Sensor Interface used for Hall Sensor in Auto, Semi Auto and Manual Detection Mode Set Up

## 18 Package Outlines

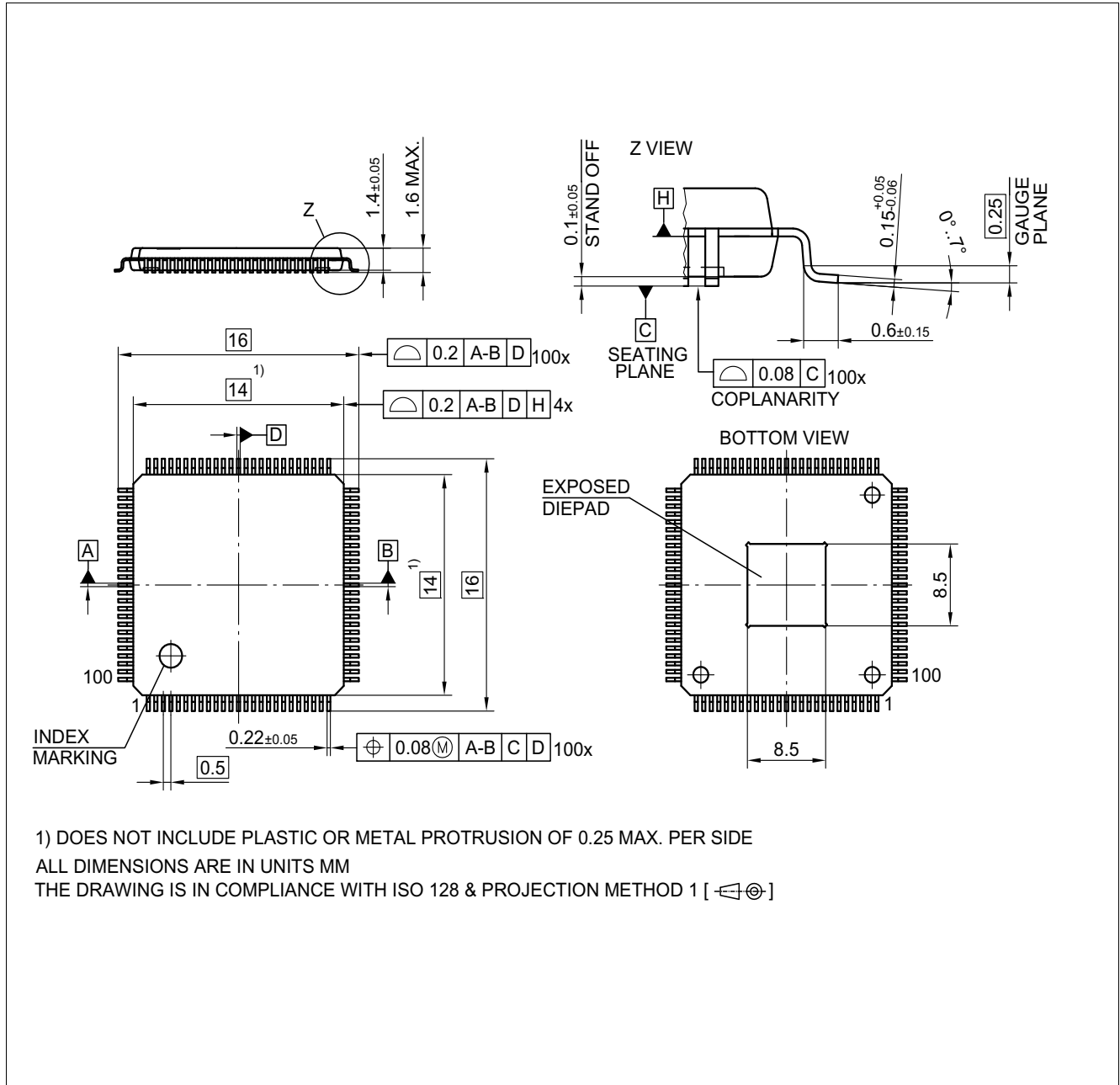


Figure 72 LQFP-100

### Green Product (RoHS compliant)

To meet the world-wide customer requirements for environmentally friendly products and to be compliant with government regulations the device is available as a green product. Green products are RoHS-Compliant (i.e Pb-free finish on leads and suitable for Pb-free soldering according to IPC/JEDEC J-STD-020).

**Revision History**

**19 Revision History**

<b>Revision</b>	<b>Date</b>	<b>Changes</b>
V1.2	2017-02-10	updated to new layout, package picture (page 5) and package outline picture (page 206) updated, paragraph below package outline picture removed
V1.1	2014-08-20	on all pages: general name changed to “TLE8888-1QK” and date and revision
V1.1	2014-08-20	page 5 and 6: 2 device types added
V1.1	2014-08-20	page 29: parameter P_5.3.24 min/max changed
V1.1	2014-08-20	page 52: parameter P_7.5.2 and P_7.5.11 max defined
V1.1	2014-08-20	page 57: parameter P_8.8.38, P_8.8.39, P_8.8.40, P_8.8.42, P_8.8.43 and P_8.8.44 definition improved
V1.1	2014-08-20	page 58: parameter P_8.8.45 definition improved
V1.1	2014-08-20	page 62: table 25 corrected
V1.1	2014-08-20	page 100: PGND reference pin changed
V1.1	2014-08-20	page 2, 9, 10, 11, 17, 18, 20, 21, 22, 26, 38, 39, 43, 44, 45, 48, 49, 52, 56, 58, 196: missing variable names added
V1.0	2014-03-13	Data Sheet

#### Trademarks of Infineon Technologies AG

$\mu$ HVIC™,  $\mu$ IPM™,  $\mu$ PFC™, AU-ConvertIR™, AURIX™, C166™, CanPAK™, CIPOS™, CIPURSE™, CoolDP™, CoolGaN™, COOLiR™, CoolMOS™, CoolSET™, CoolSiC™, DAVE™, DI-POL™, DirectFET™, DrBlade™, EasyPIM™, EconoBRIDGE™, EconoDUAL™, EconoPACK™, EconoPIM™, EiceDRIVER™, eupec™, FCOS™, GaNpowIR™, HEXFET™, HITFET™, HybridPACK™, iMOTION™, IRAM™, ISOFACE™, IsoPACK™, LEDriviR™, LITIX™, MIPAQ™, ModSTACK™, my-d™, NovalithIC™, OPTIGA™, OptiMOS™, ORIGA™, PowIRaudio™, PowIRStage™, PrimePACK™, PrimeSTACK™, PROFET™, PRO-SIL™, RASIC™, REAL3™, SmartLEWIS™, SOLID FLASH™, SPOC™, StrongIRFET™, SupIRBuck™, TEMPFET™, TRENCHSTOP™, TriCore™, UHVIC™, XHP™, XMC™.

Trademarks updated November 2015

#### Other Trademarks

All referenced product or service names and trademarks are the property of their respective owners.

**Edition 2017-02-10**

**Published by**

**Infineon Technologies AG**

**81726 Munich, Germany**

**© 2017 Infineon Technologies AG.**

**All Rights Reserved.**

**Do you have a question about any aspect of this document?**

**Email: [erratum@infineon.com](mailto:erratum@infineon.com)**

#### IMPORTANT NOTICE

The information given in this document shall in no event be regarded as a guarantee of conditions or characteristics ("Beschaffheitsgarantie").

With respect to any examples, hints or any typical values stated herein and/or any information regarding the application of the product, Infineon Technologies hereby disclaims any and all warranties and liabilities of any kind, including without limitation warranties of non-infringement of intellectual property rights of any third party.

In addition, any information given in this document is subject to customer's compliance with its obligations stated in this document and any applicable legal requirements, norms and standards concerning customer's products and any use of the product of Infineon Technologies in customer's applications.

The data contained in this document is exclusively intended for technically trained staff. It is the responsibility of customer's technical departments to evaluate the suitability of the product for the intended application and the completeness of the product information given in this document with respect to such application.

For further information on technology, delivery terms and conditions and prices, please contact the nearest Infineon Technologies Office ([www.infineon.com](http://www.infineon.com)).

#### WARNINGS

Due to technical requirements products may contain dangerous substances. For information on the types in question please contact your nearest Infineon Technologies office.

Except as otherwise explicitly approved by Infineon Technologies in a written document signed by authorized representatives of Infineon Technologies, Infineon Technologies' products may not be used in any applications where a failure of the product or any consequences of the use thereof can reasonably be expected to result in personal injury.